

SFR-2016
X-ray apparatus

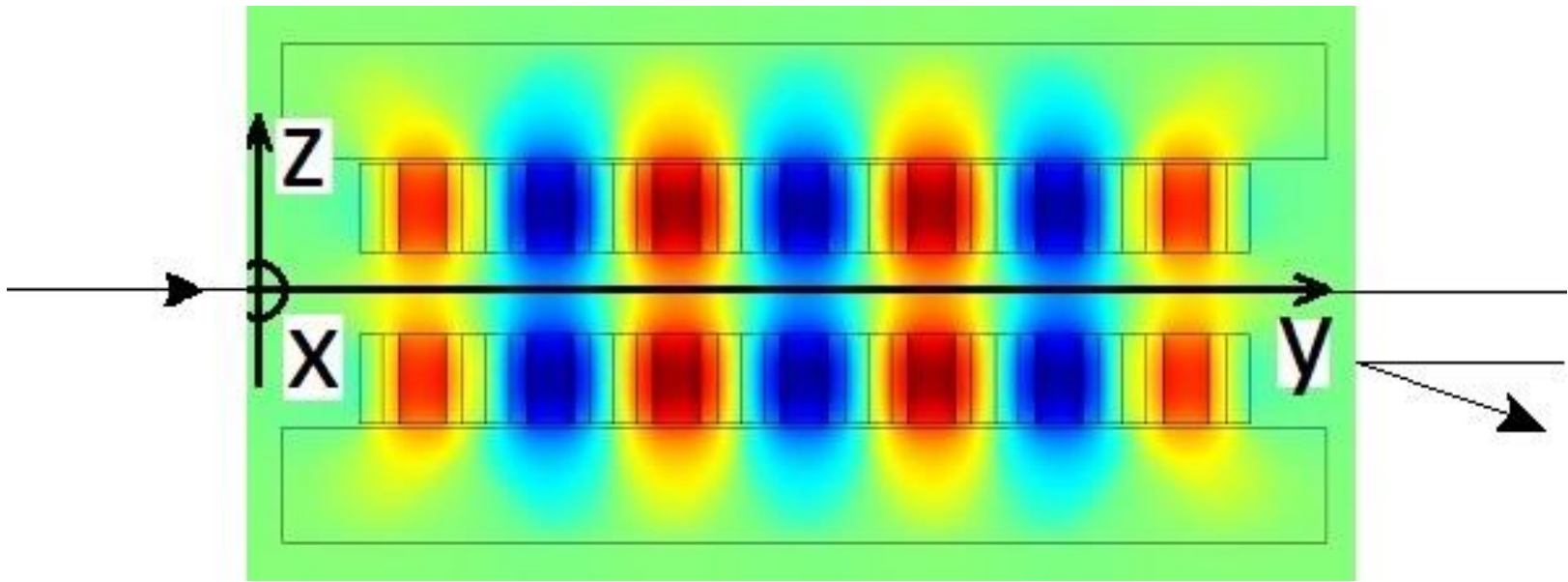
Current driven wire based magnetic measurement systems

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Electron beam + magnetic field = synchrotron radiation.

A wiggler/undulator = many magnets, but it is not a bending magnet.

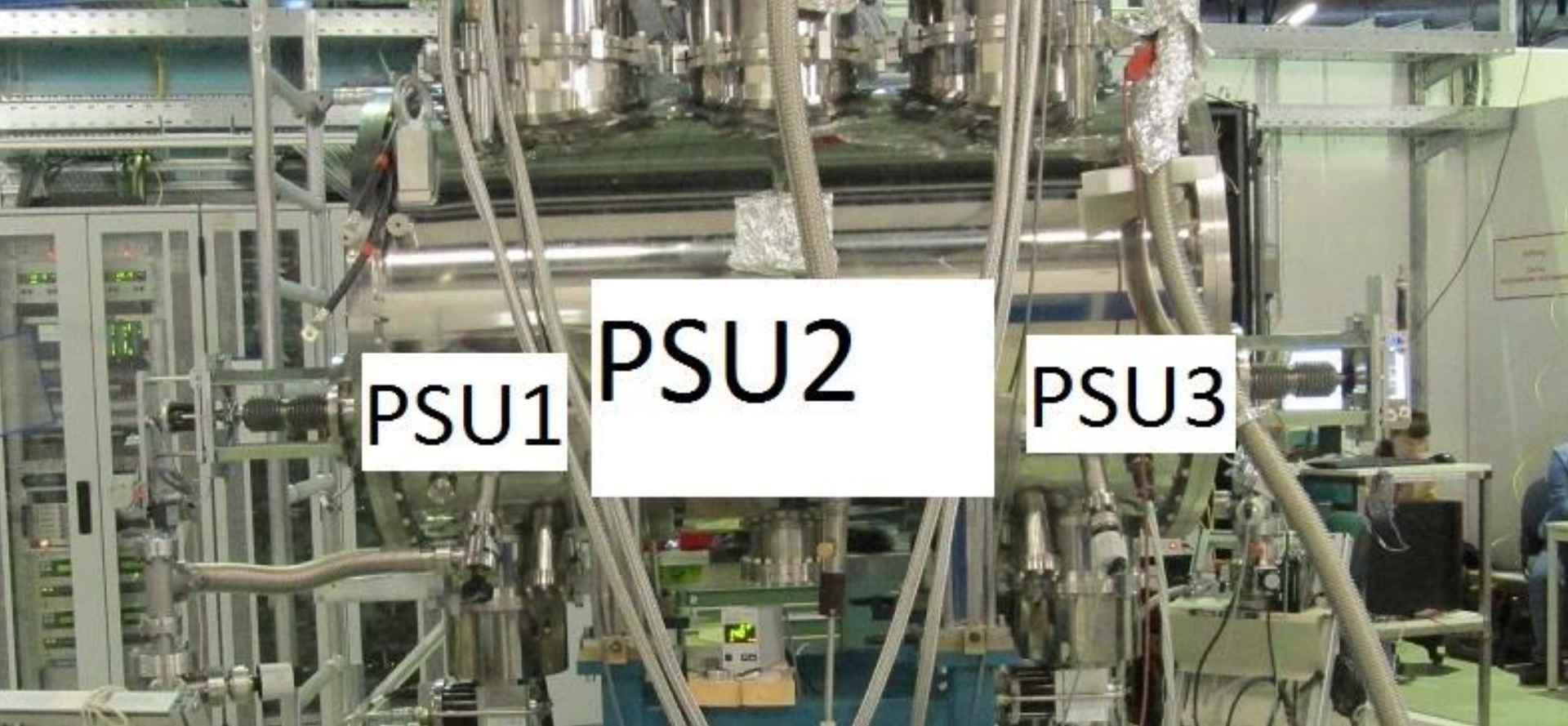
Electron beam trajectory shouldn't change.

J_1 means angle, J_2 means shift.

Tasks: minimize and measure J_1 , J_2 and some other parameters.

$$J_1 = \int_0^L B(s) \cdot ds$$

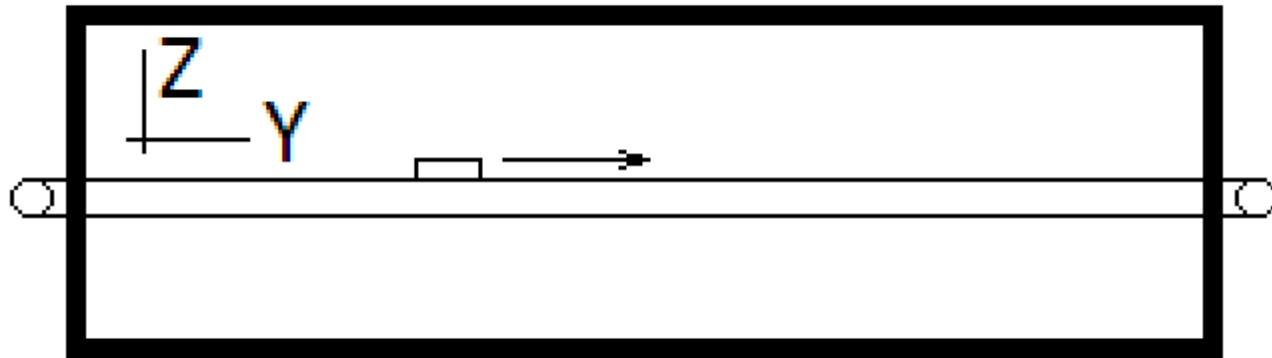
$$J_2 = \int_0^L ds \int_0^s B(s') \cdot ds'$$



3 PSU = B, J1, J2

Hall probe sensor

- Much space
 - Much time, no ramping
 - Mechanics
 - Calibration
- Liquid He

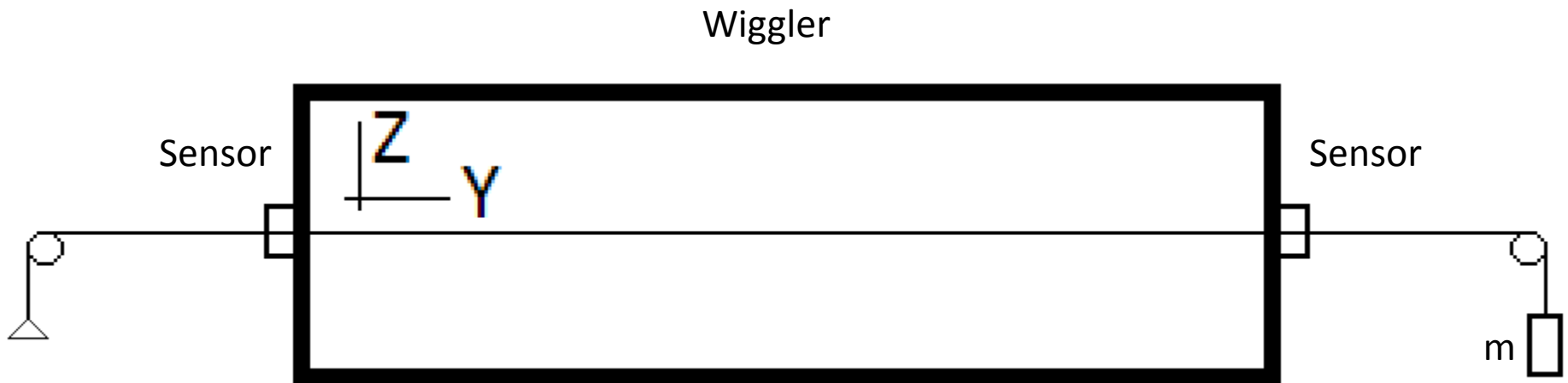


Moving wire based systems

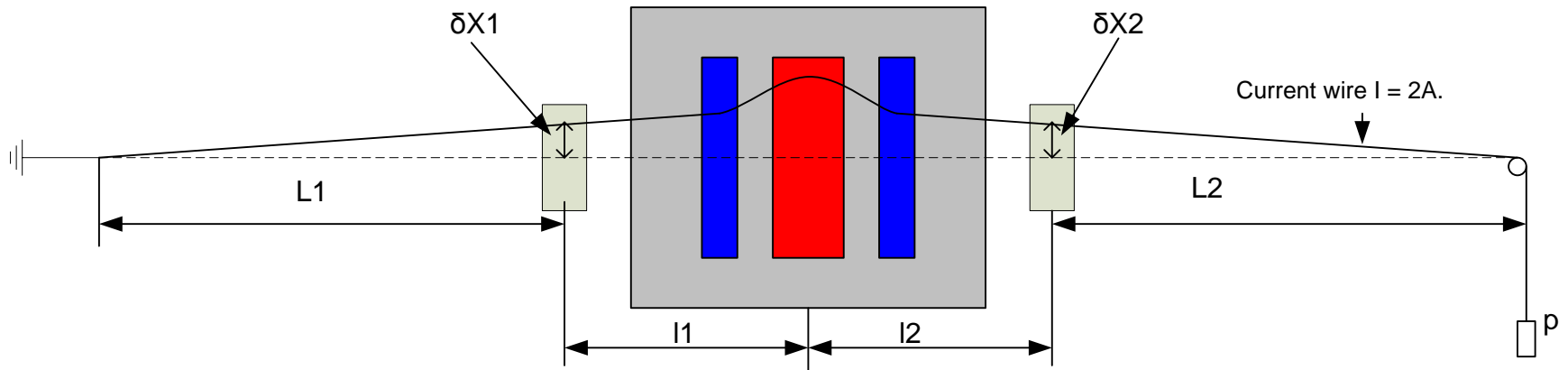
- Faraday's law of induction: moving wire + magnetic field = voltage
- Different configurations of wire are possible: straight wire, coil, eight-form coil...
- Mechanics
- Much space

Current driven wire based systems

- Current moves through stretched wire and interacts with magnetic field (Ampere force). The wire deflects, and its position is measured.



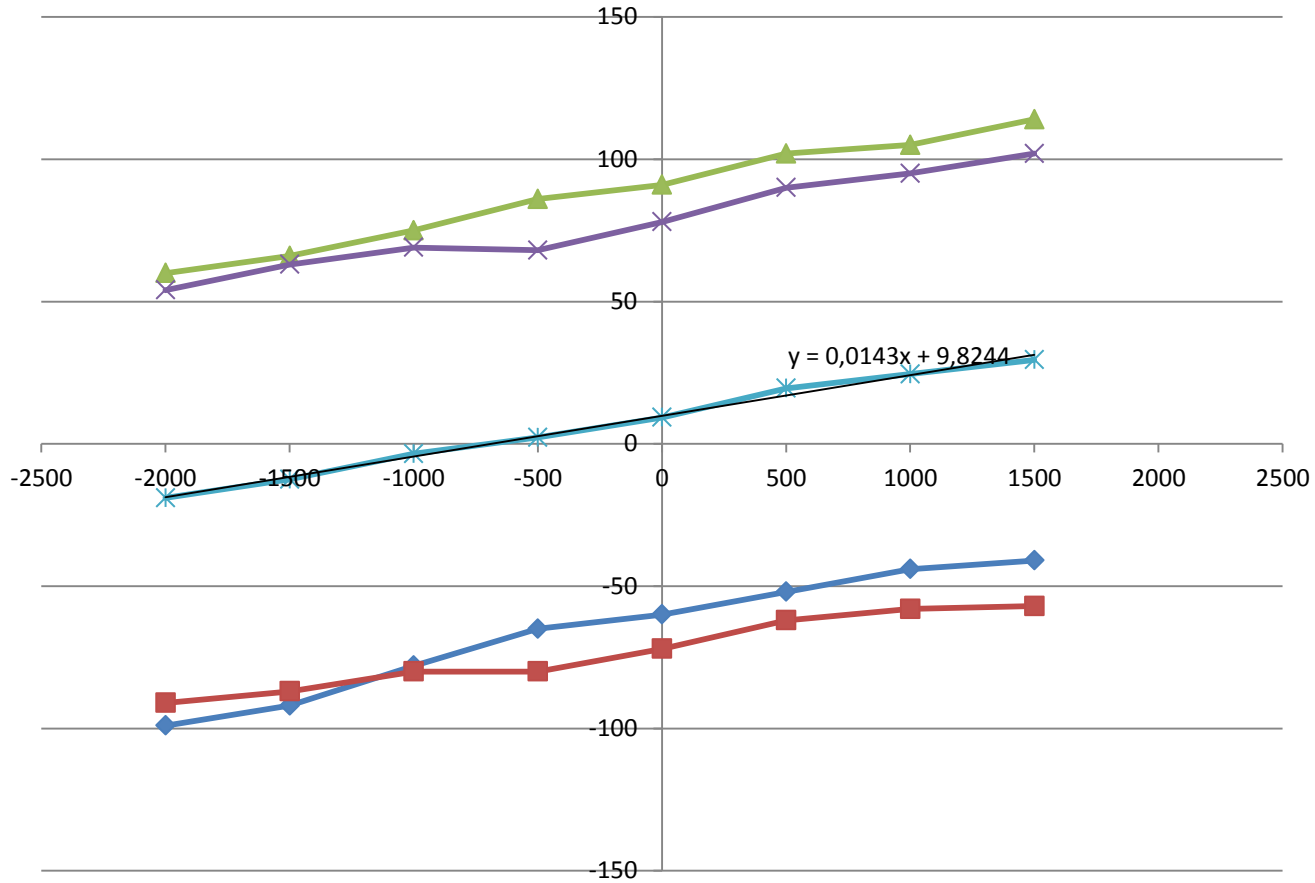
Constant current method



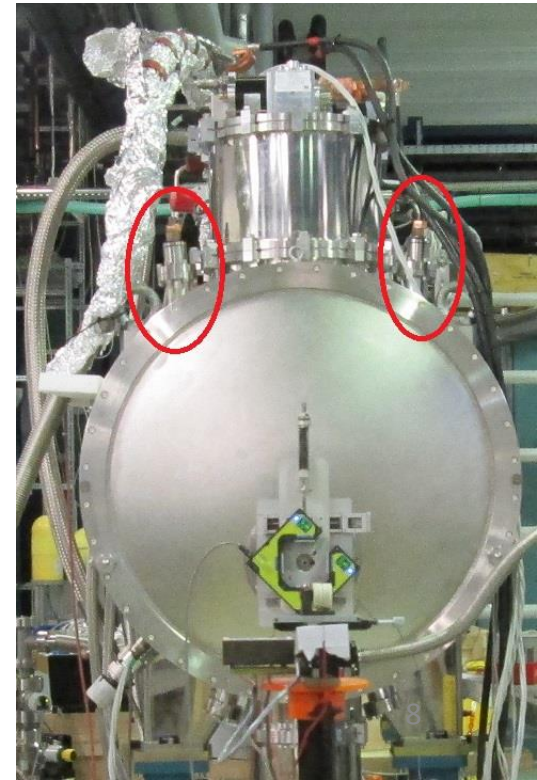
$$I_{first} = I_1 \left(\frac{L}{2} \right) = \delta\alpha * \frac{T}{I} = \frac{T}{I} \left(\frac{\delta x_1}{L_1} + \frac{\delta x_2}{L_2} \right) \text{ -first field integral}$$

$$I_{second} = I_2 \left(\frac{L}{2} \right) = \delta x \cdot \frac{T}{I} = \frac{T}{I} (\delta x_2 - \delta x_1) \text{ -- second field integral}$$

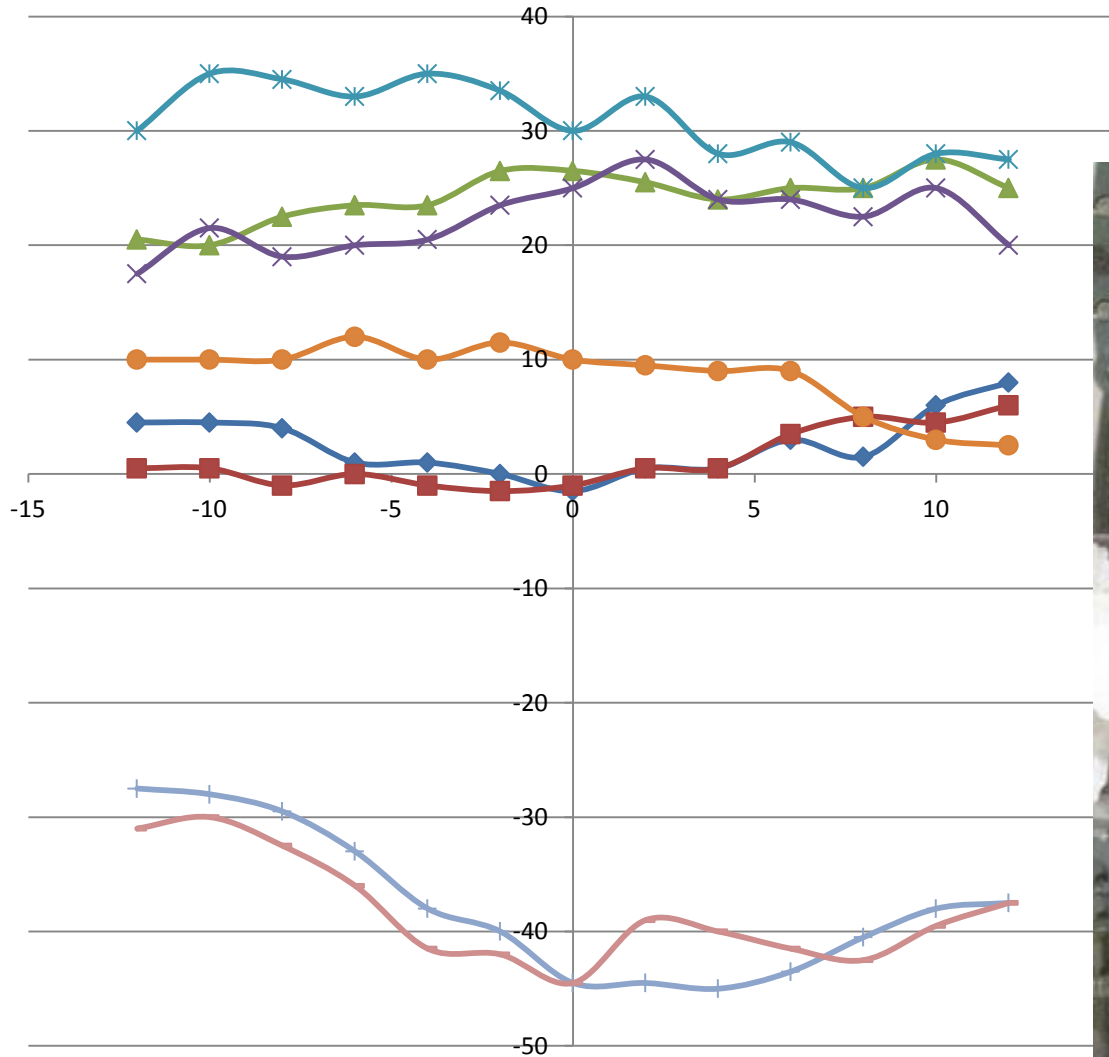
Median plane



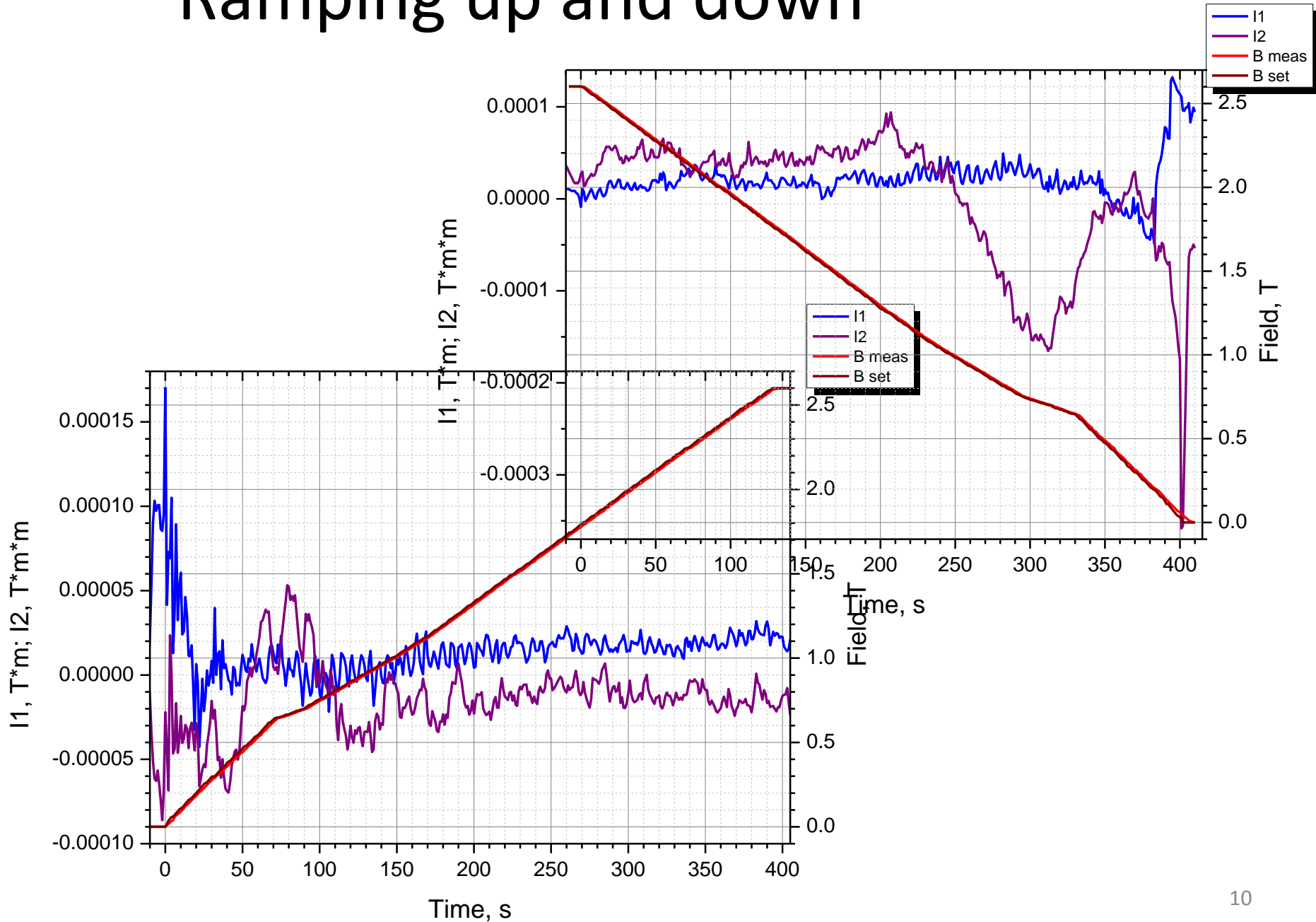
Wiggler
focuses



Sextupole measurement



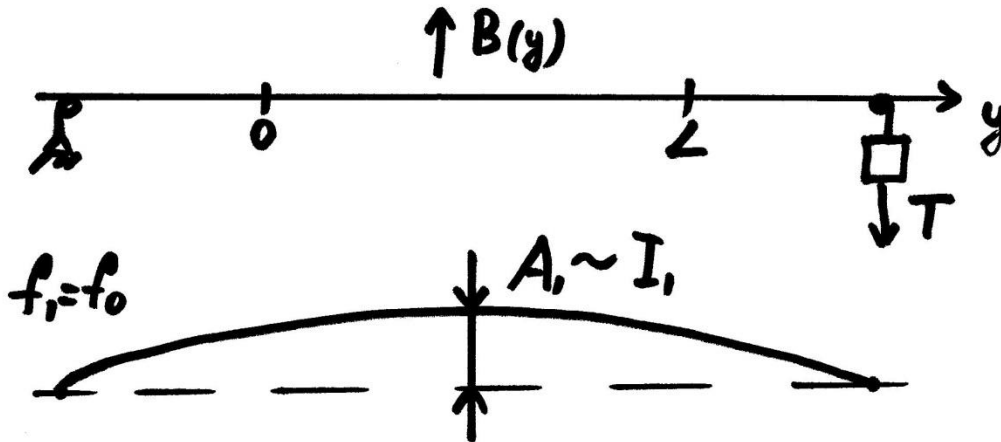
Ramping up and down



Vibrating wire technique (resonant method)

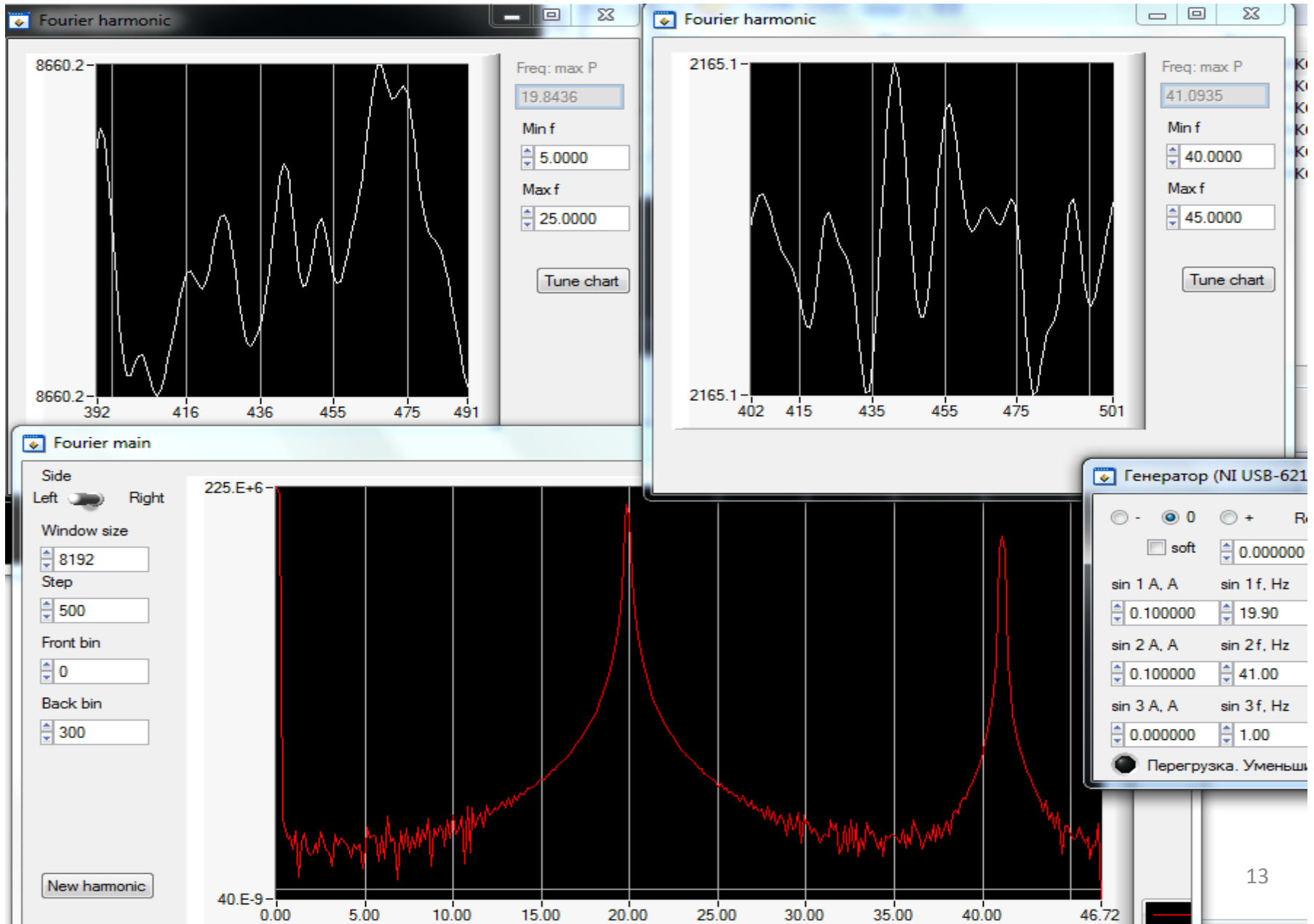
- Let f_0 is wire self-resonant frequency
- Let A is amplitude of oscillation (measured by a sensor) when the wire is driven by harmonic current frequency f
- It is possible to show that
 $I_{first} \sim A(f = f_0)$, $I_{second} \sim A(f = 2f_0)$, and
so on

$$I_1 = \int_0^L B dy; \quad I_2 = \int_0^L dy' \int_0^L B dy; \quad I_3 = \dots$$

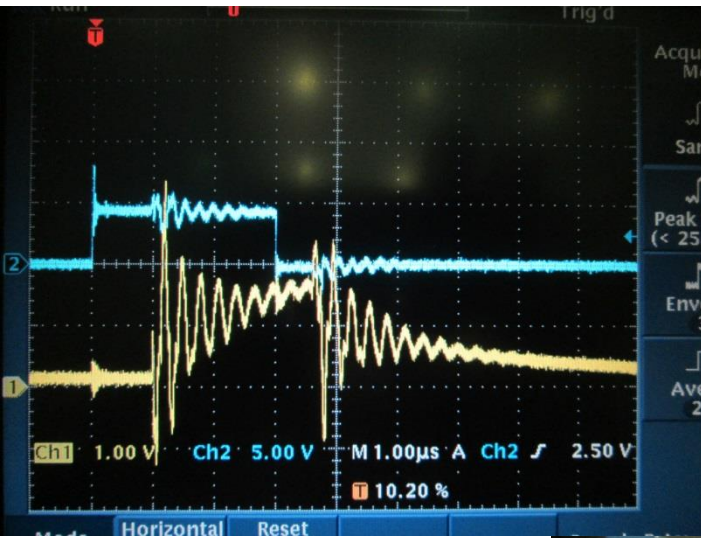


- Sensor position
- Phase detection
- Coefficients, supports, calibration
- Q-factor, time

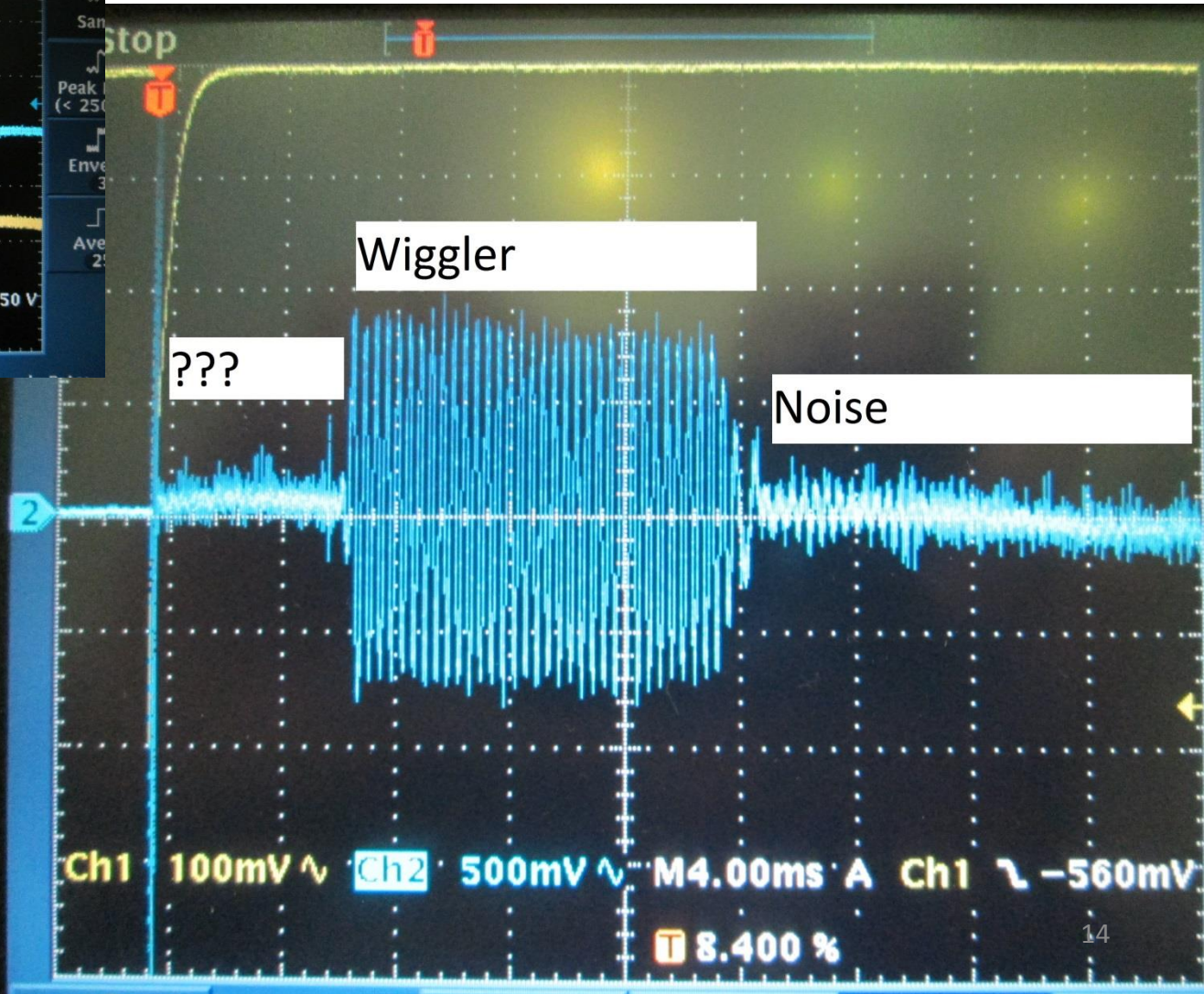
Software interface



Pulsed Wire Method



- J1
- J2
- Axis tilt
- Axis offset



20

OK

On

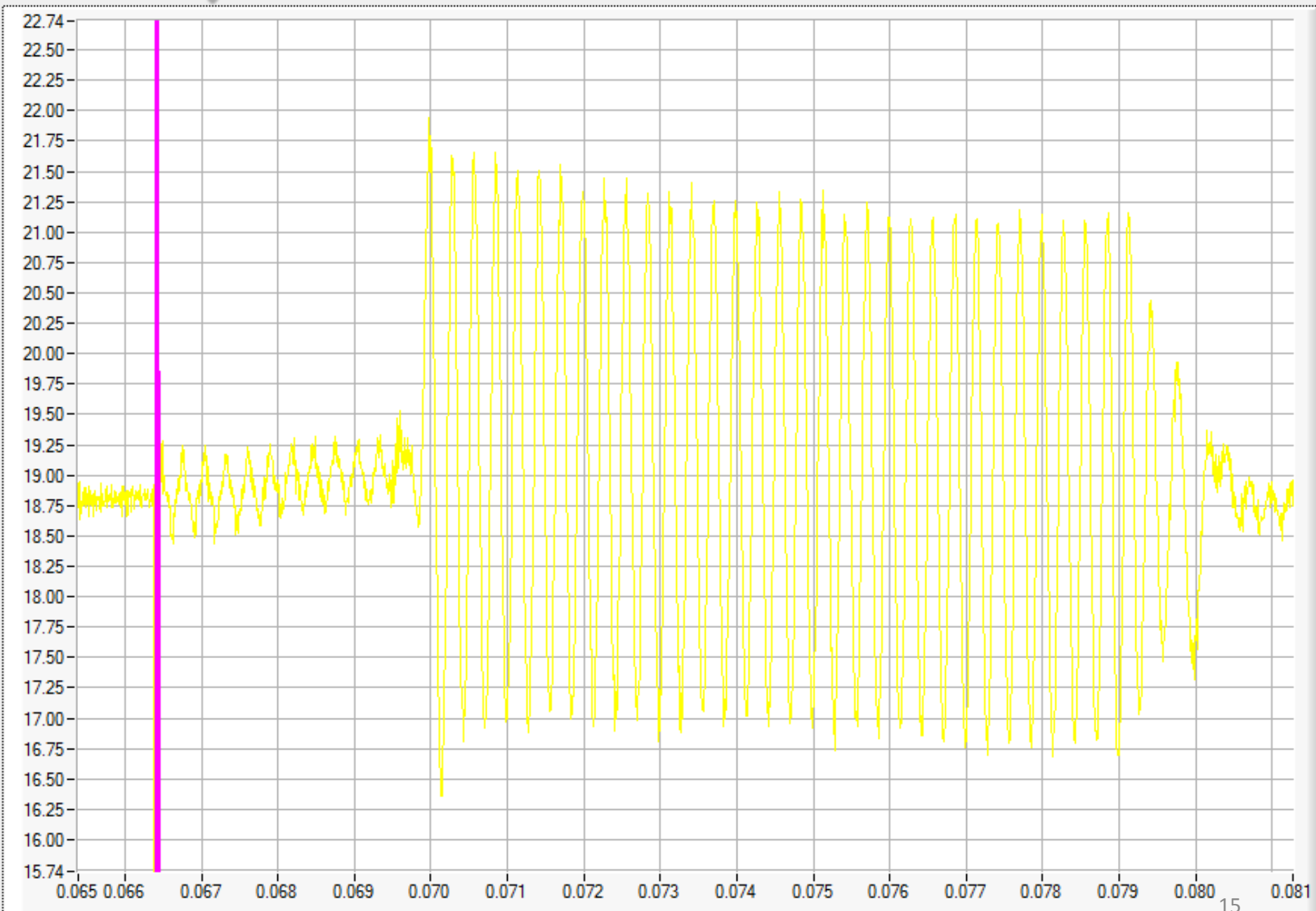
0.00

0.00

1

10.00

Off



Problems

- Sag, tension, sensitivity, l , diameter
- Noise: wind, acoustic waves, vibration
- Earth magnetic field
- Wire imperfectness (for pulsed method)

Conclusion

- Hall probe: liquid helium, constant field
- Constant current method: the best for wigglers. Accuracy is better $5 \cdot 10^{-5} \text{ T} \cdot \text{m}$, limited by PSUs
- Vibrating wire (resonant) method: good for zeroing integrals, problems with calibration
- Vibrating, pulsed methods: perspective for superconducting undulators

Thank you!