

Current R&D and Future Trends in Silicon Detectors

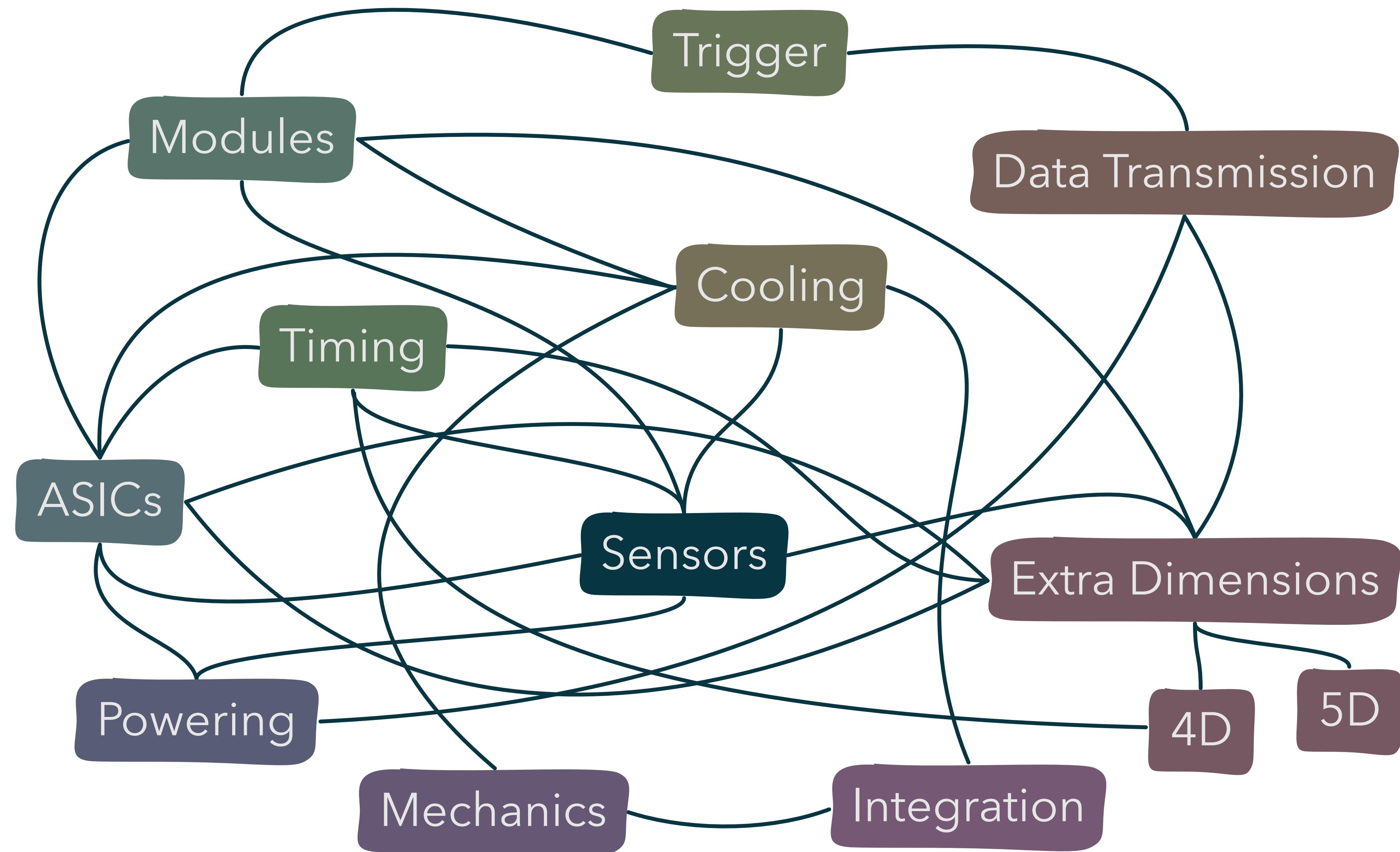
Andreas Mussgiller

Instrumentation for Colliding Beam Physics (INSTR20)

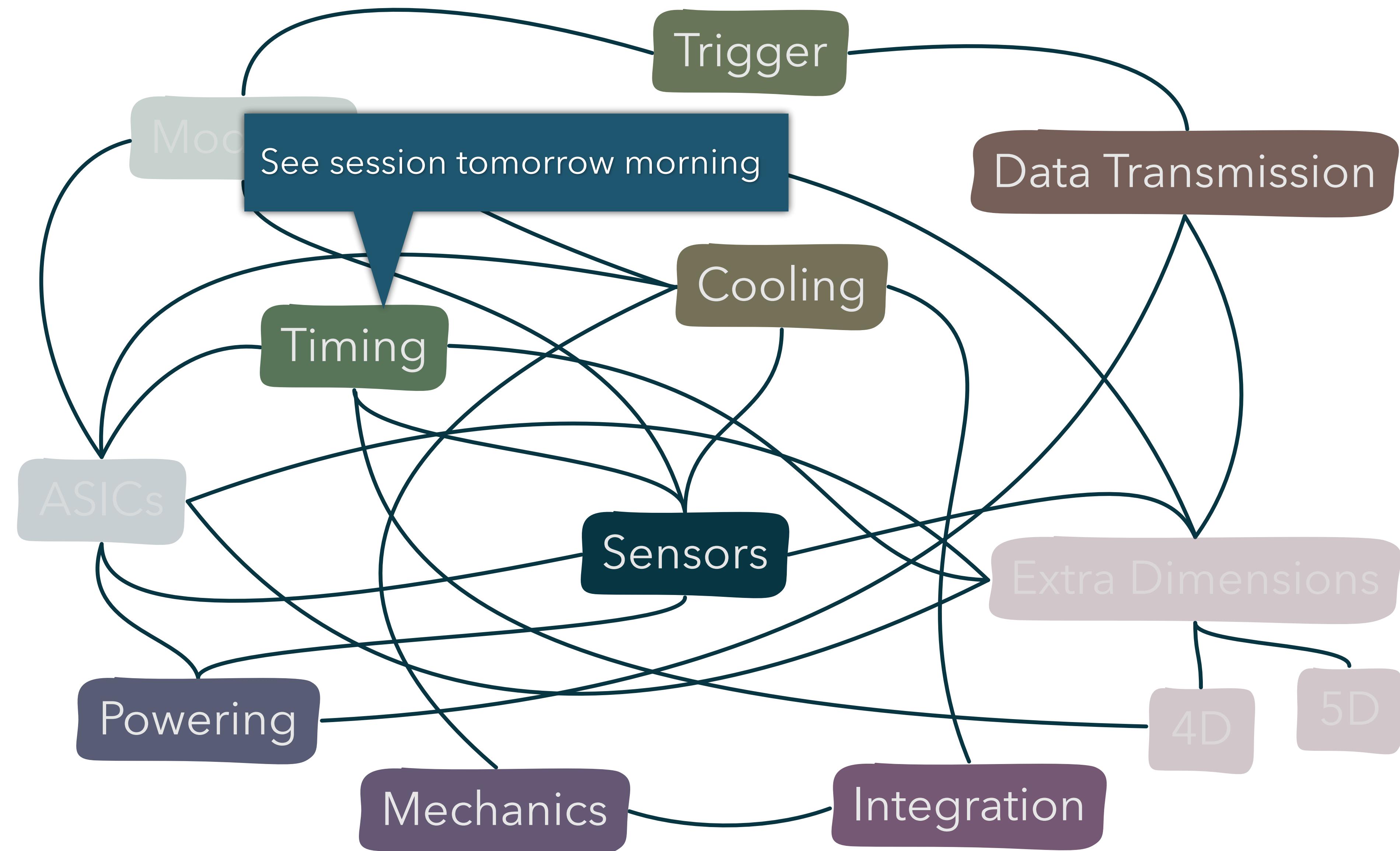
25/02/2020



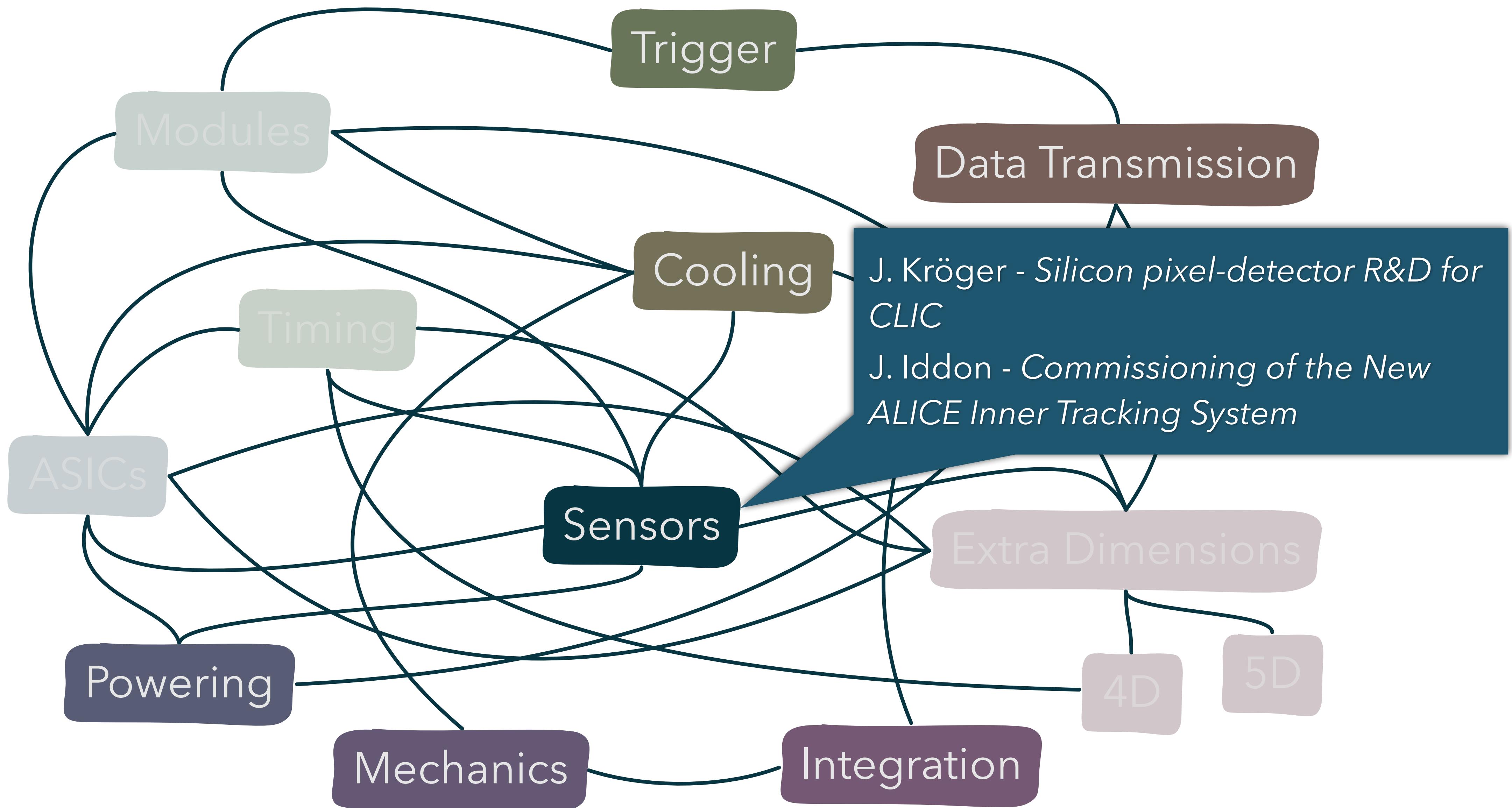
Outline



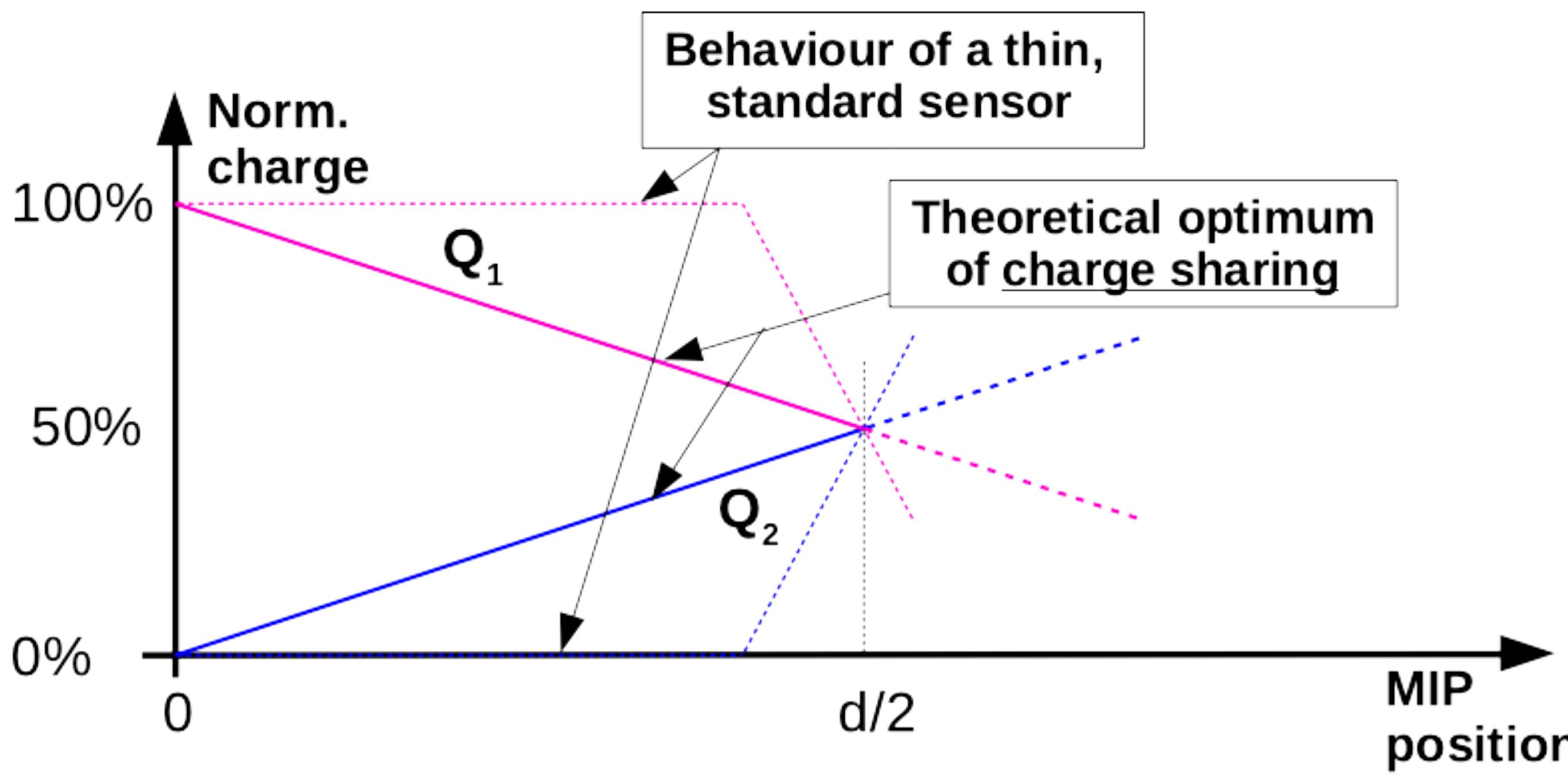
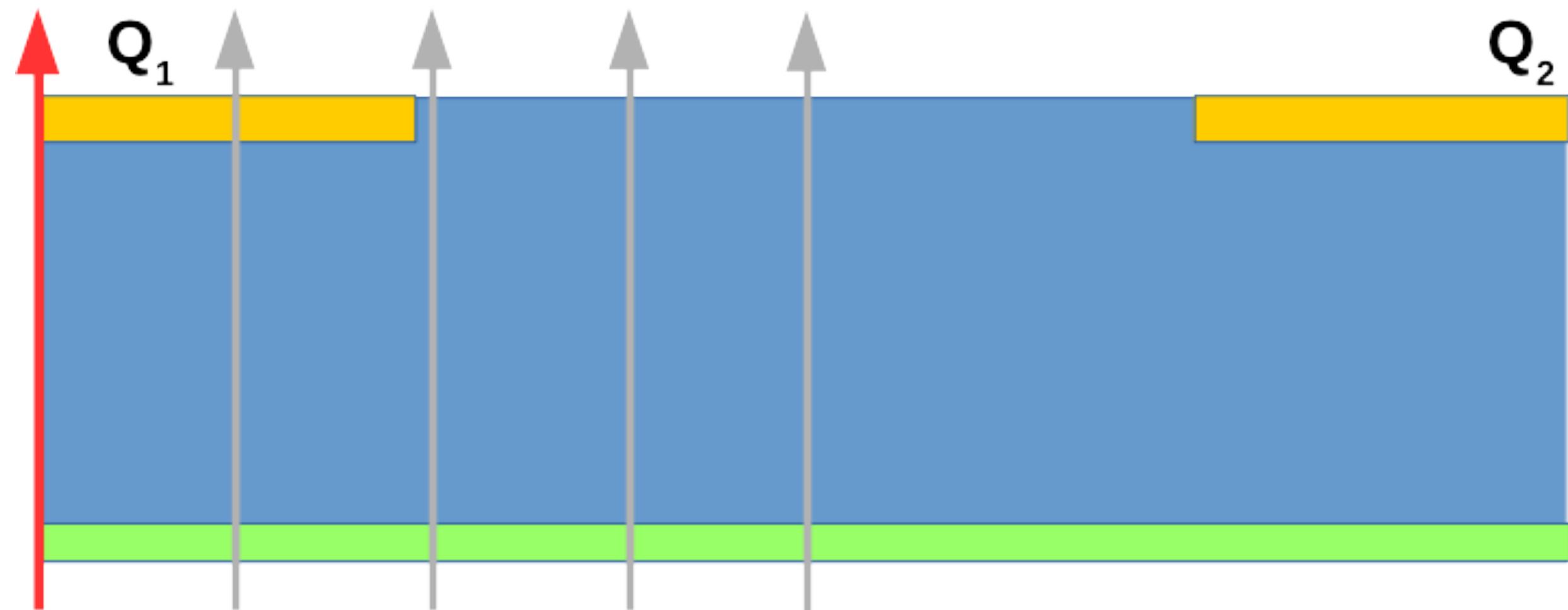
Outline



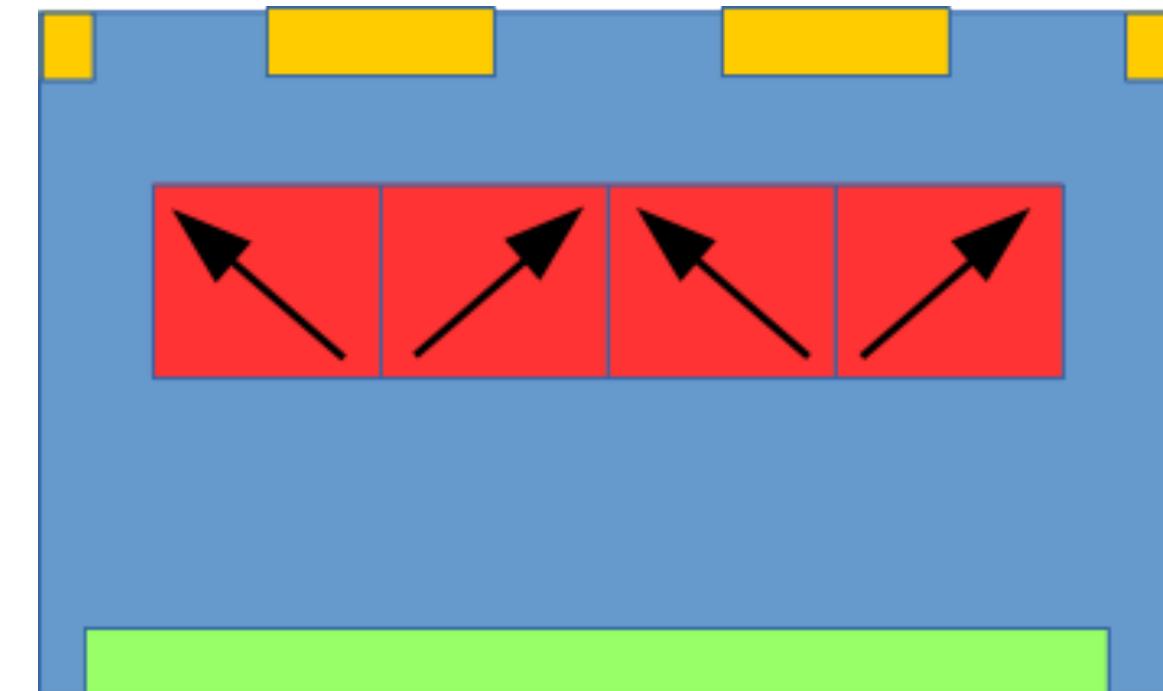
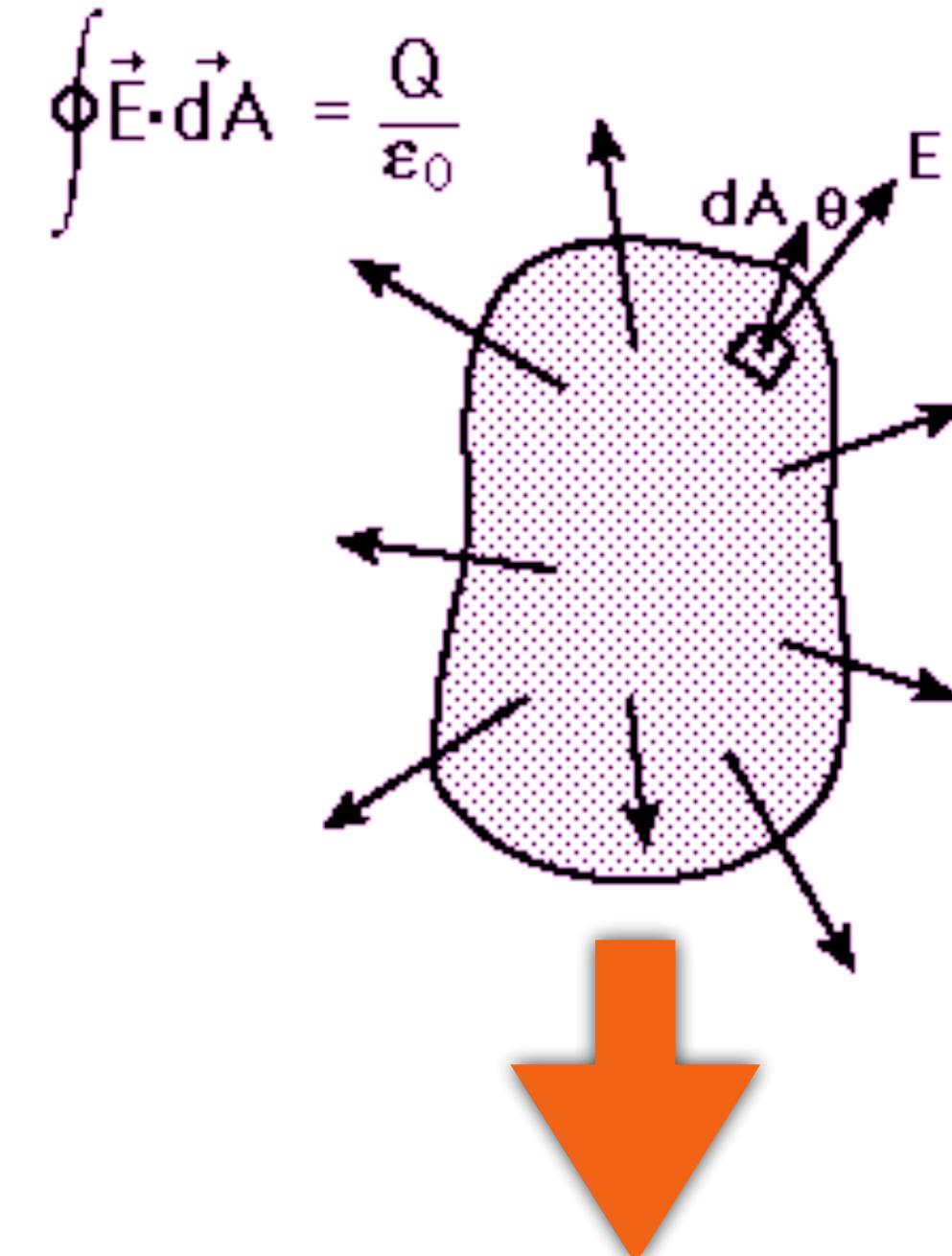
Outline



Position Resolution Revisited

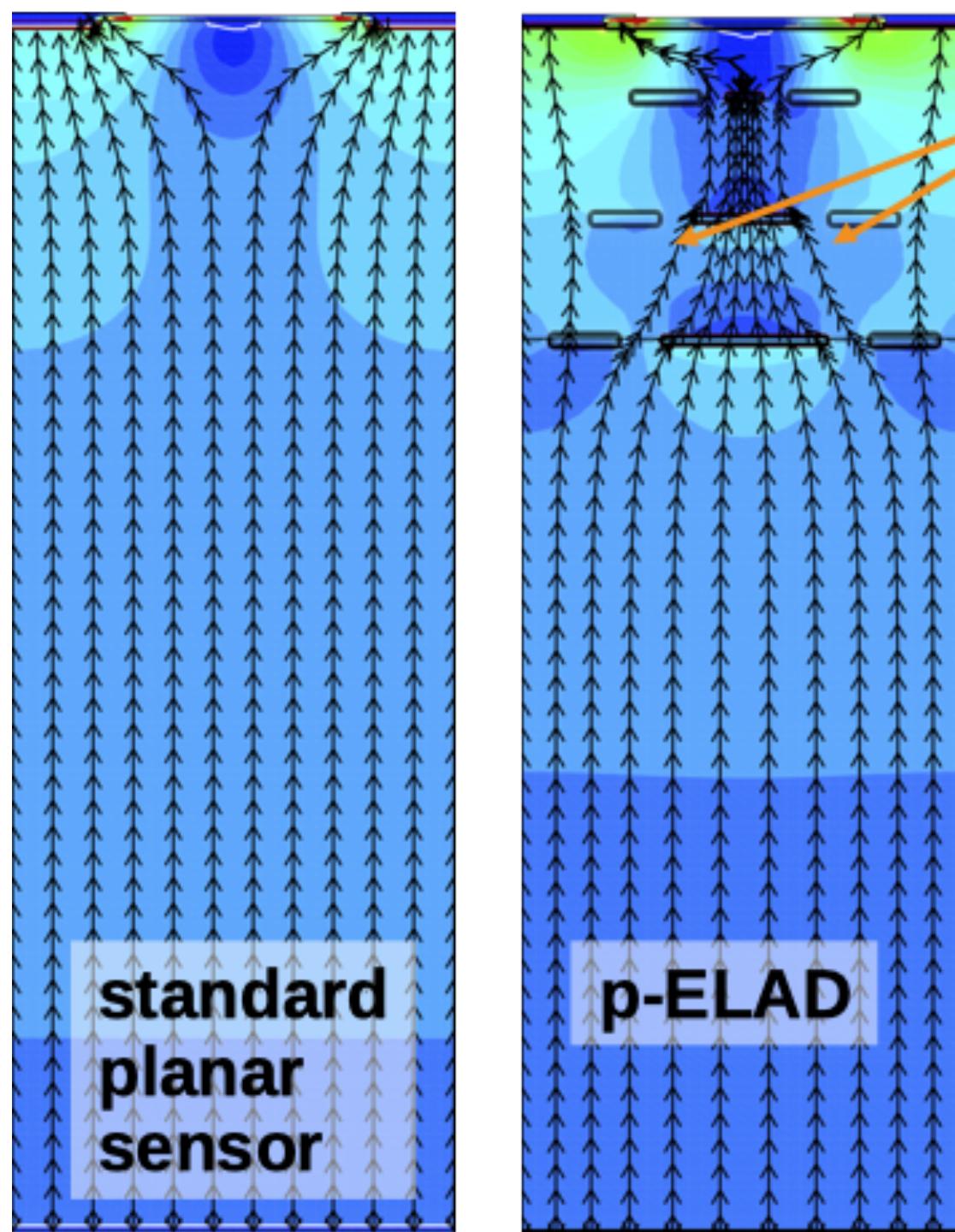
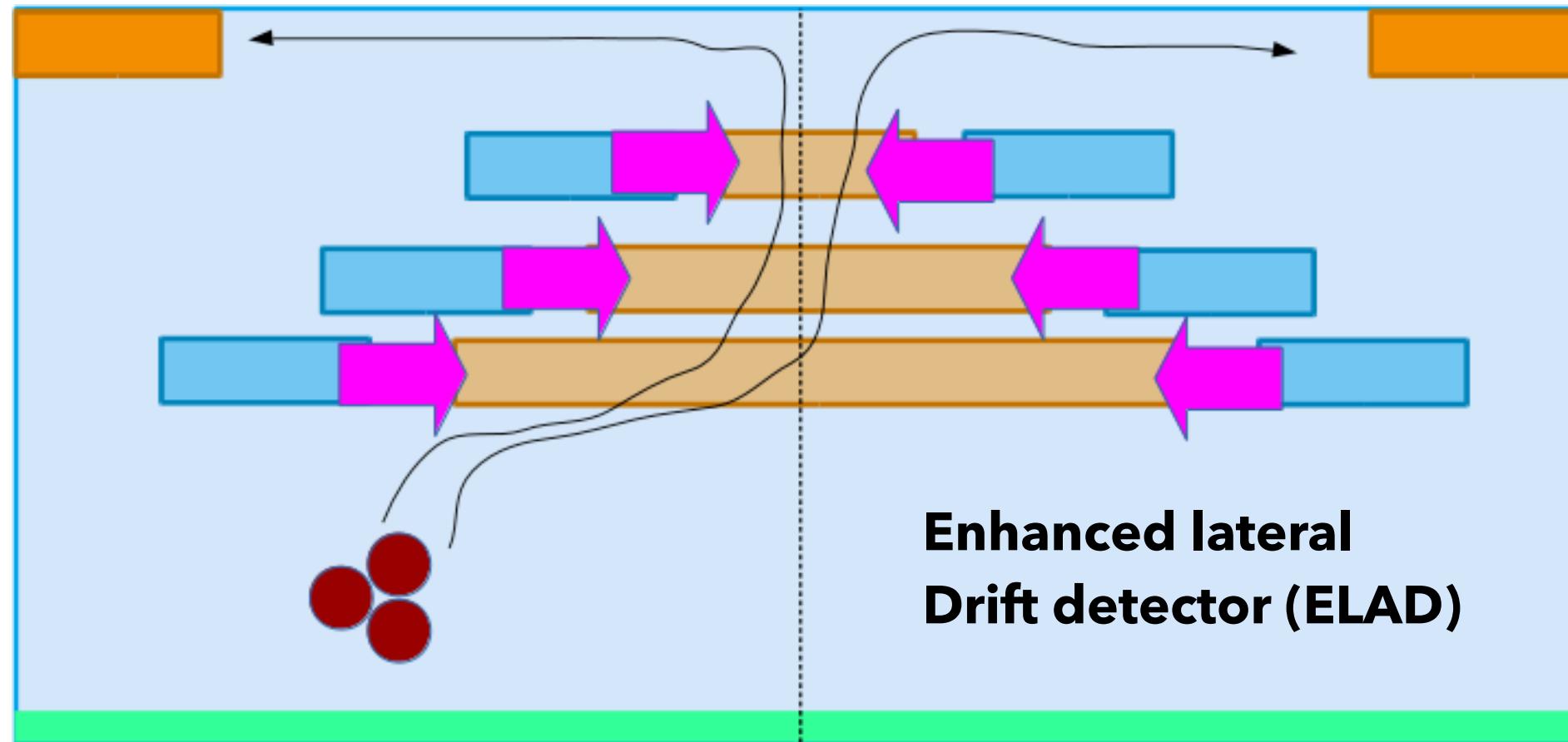


Free charges follow field lines
→ exploit Maxwell's 1st eq

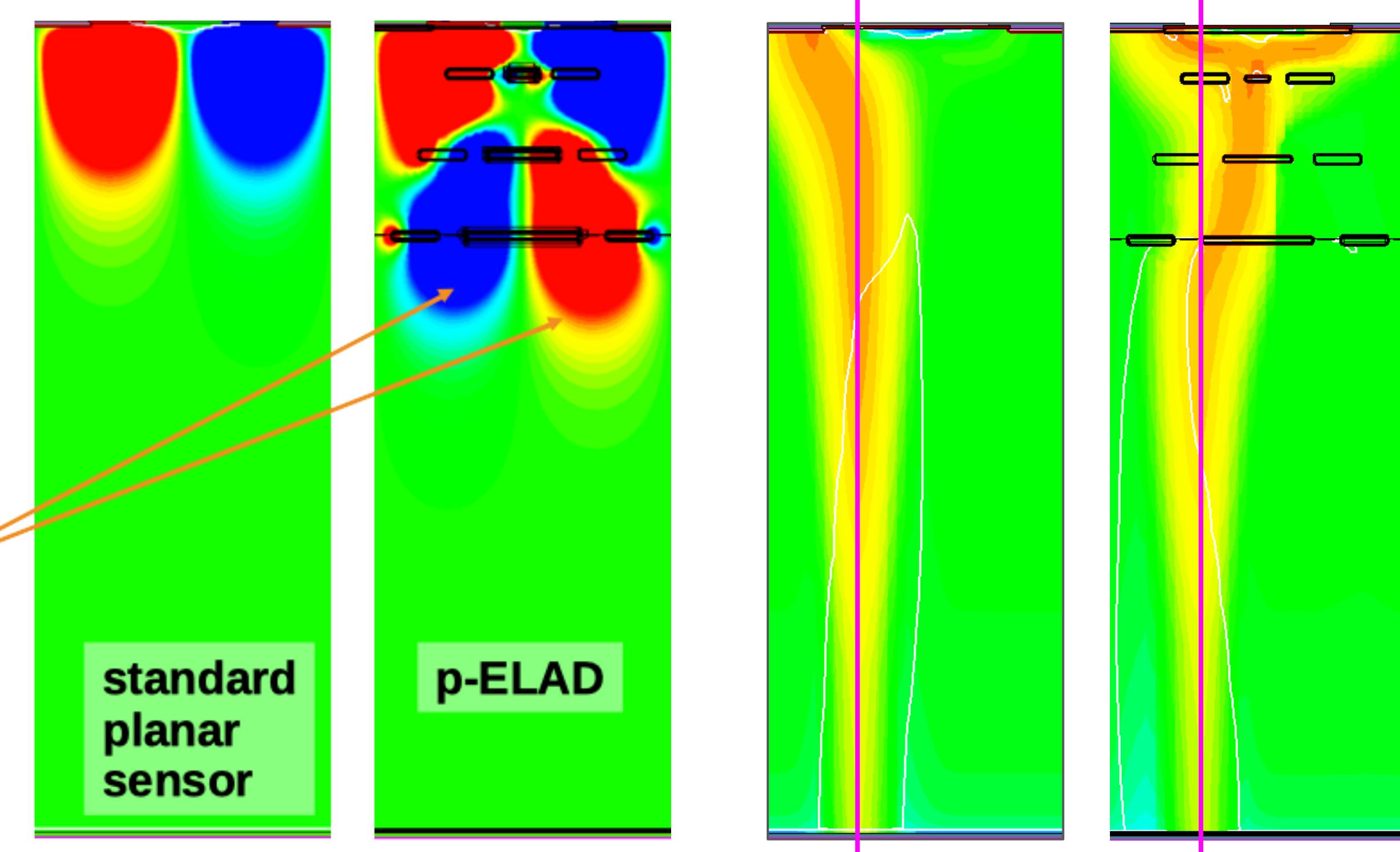


Concept of Enhanced Lateral Drift Detectors (ELAD)

- Wanted: thin & fast & precise pixel detectors
- Reality: thin & fast translates to ~binary resolution
- Goal: reach theoretical limit of position resolution at given pitch, SNR and threshold
- How: linear charge sharing
- Solution: dedicated charge sharing mechanism by engineering the E-field
- Requires: layer-by-layer process combining epitaxy and ion beam implantation



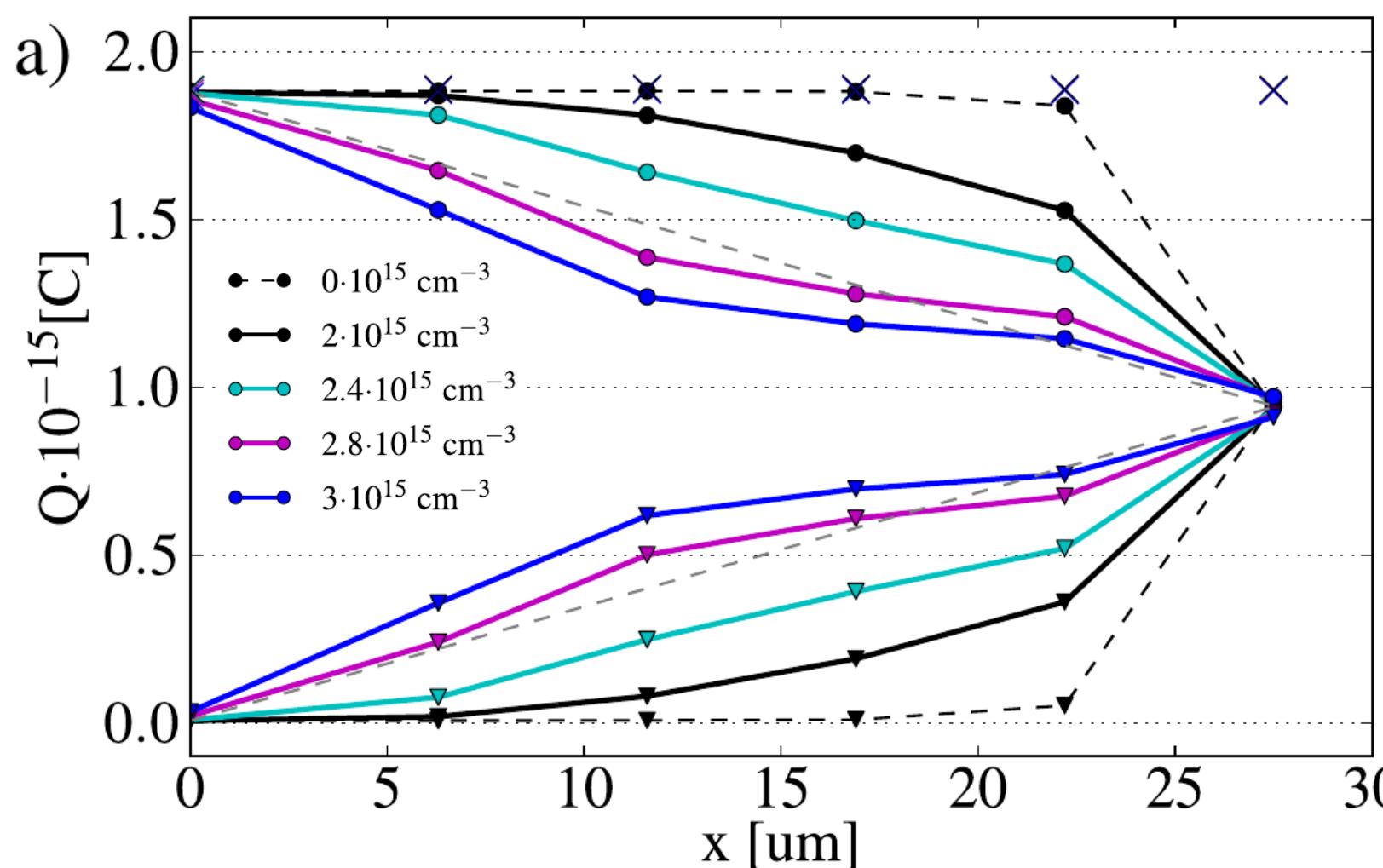
Electric field lines point to the centre!
Resulting field from deep implants.
Blue: e- move right
Red: e- move left



ELAD - TCAD / Detector Simulations

TCAD

Charge sharing vs. MIP position
n-ELAD @ 280 V

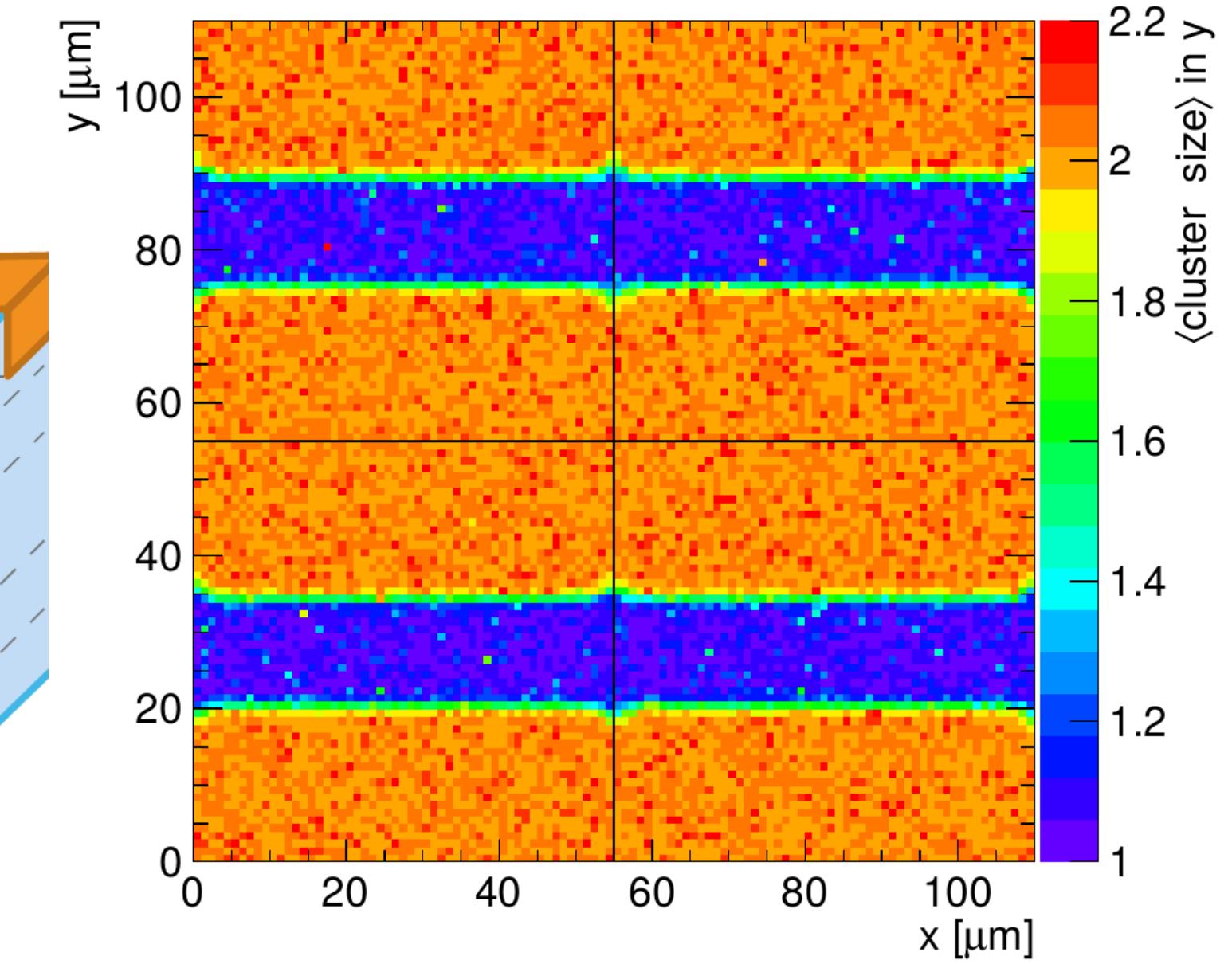
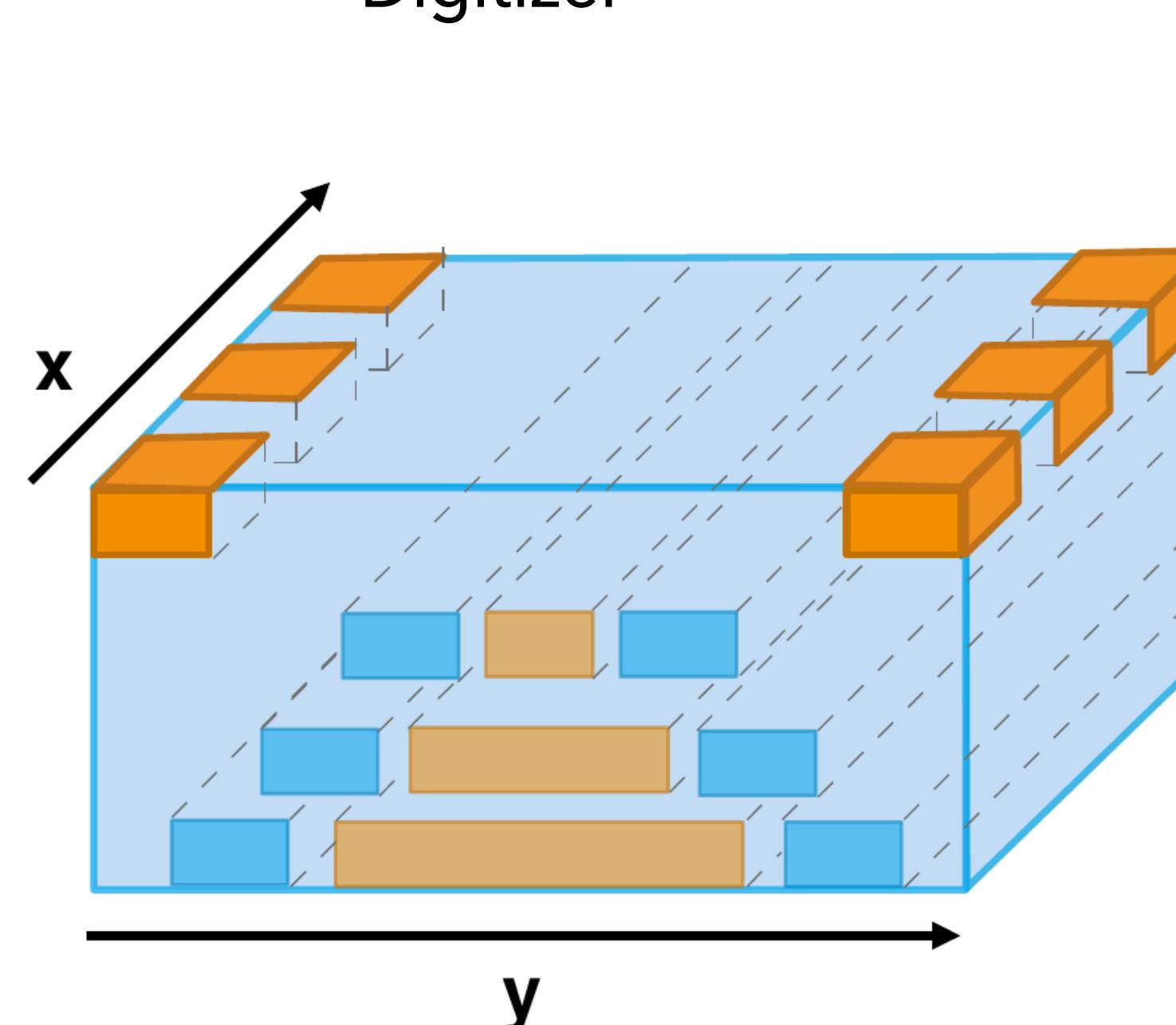


- ELAD design allows to tune charge sharing
- No charge loss (no low-field areas)
- Close to theoretical optimum

Patent granted: H. Jansen, DE102015116270B4
H. Jansen, Nucl. Instr. Meth. A 831 242 (2016)
A. Velyka, H. Jansen, TIPP 2017 proceedings

AllPix2

Study impact of buried implants on the spatial resolution
→ Final step of the optimisation scheme after TCAD
AllPix2: generic detector simulation framework
→ Monte Carlo particles from Geant4
→ Charge deposition
→ Charge drift/diffusion (import TCAD E-field)
→ Digitizer



orange = clustersize 2
blue = clustersize 1

Improvement in resolution up to a factor 3!

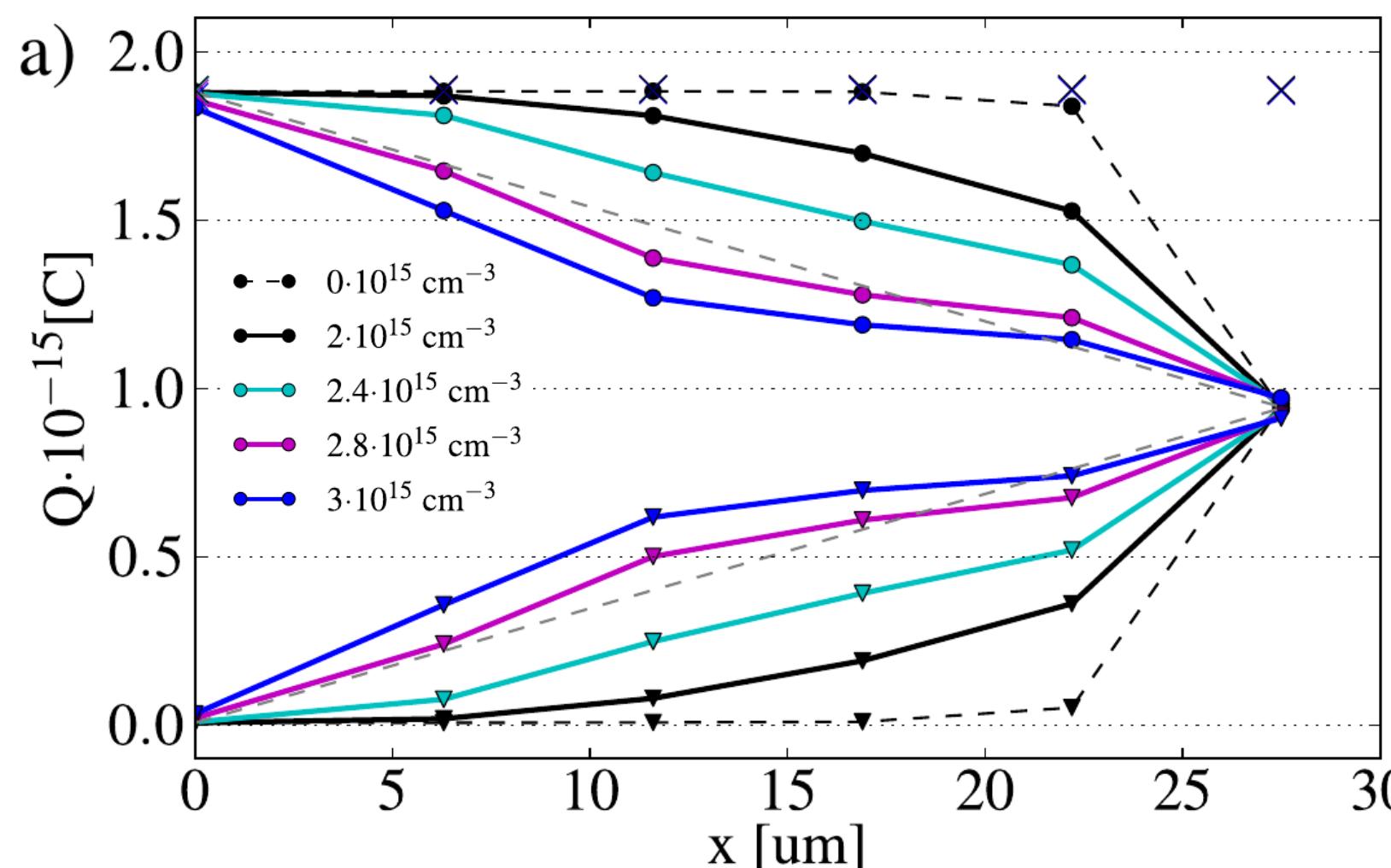


ELAD - TCAD / Detector Simulations



TCAD

Charge sharing vs. MIP position
n-ELAD @ 280 V



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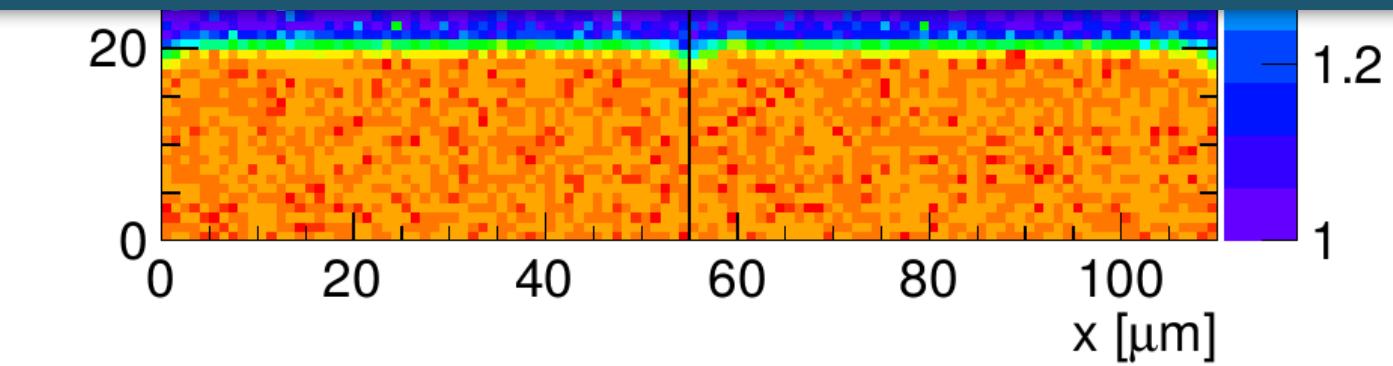
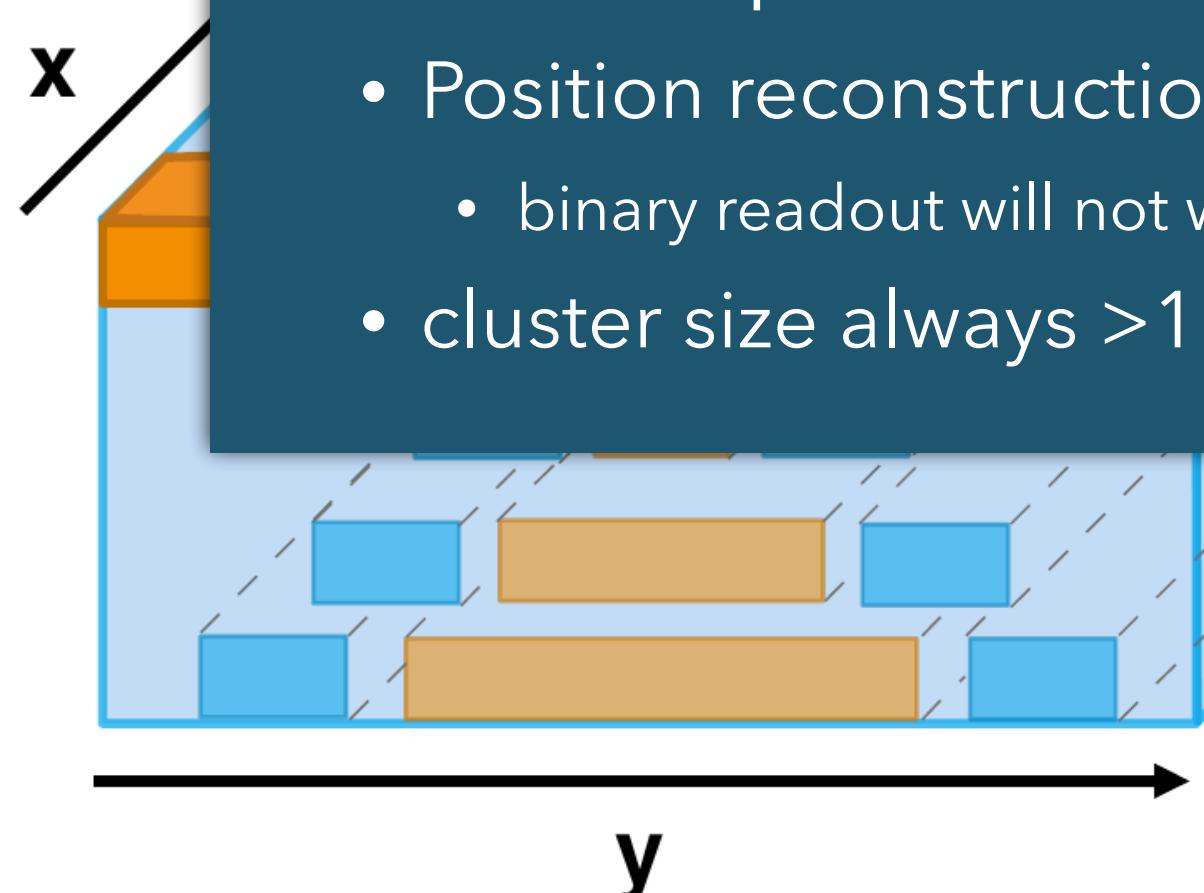
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AllPix2

Study impact of buried implants on the spatial resolution
→ Final step of the optimisation scheme after TCAD
AllPix2: generic detector simulation framework

However...

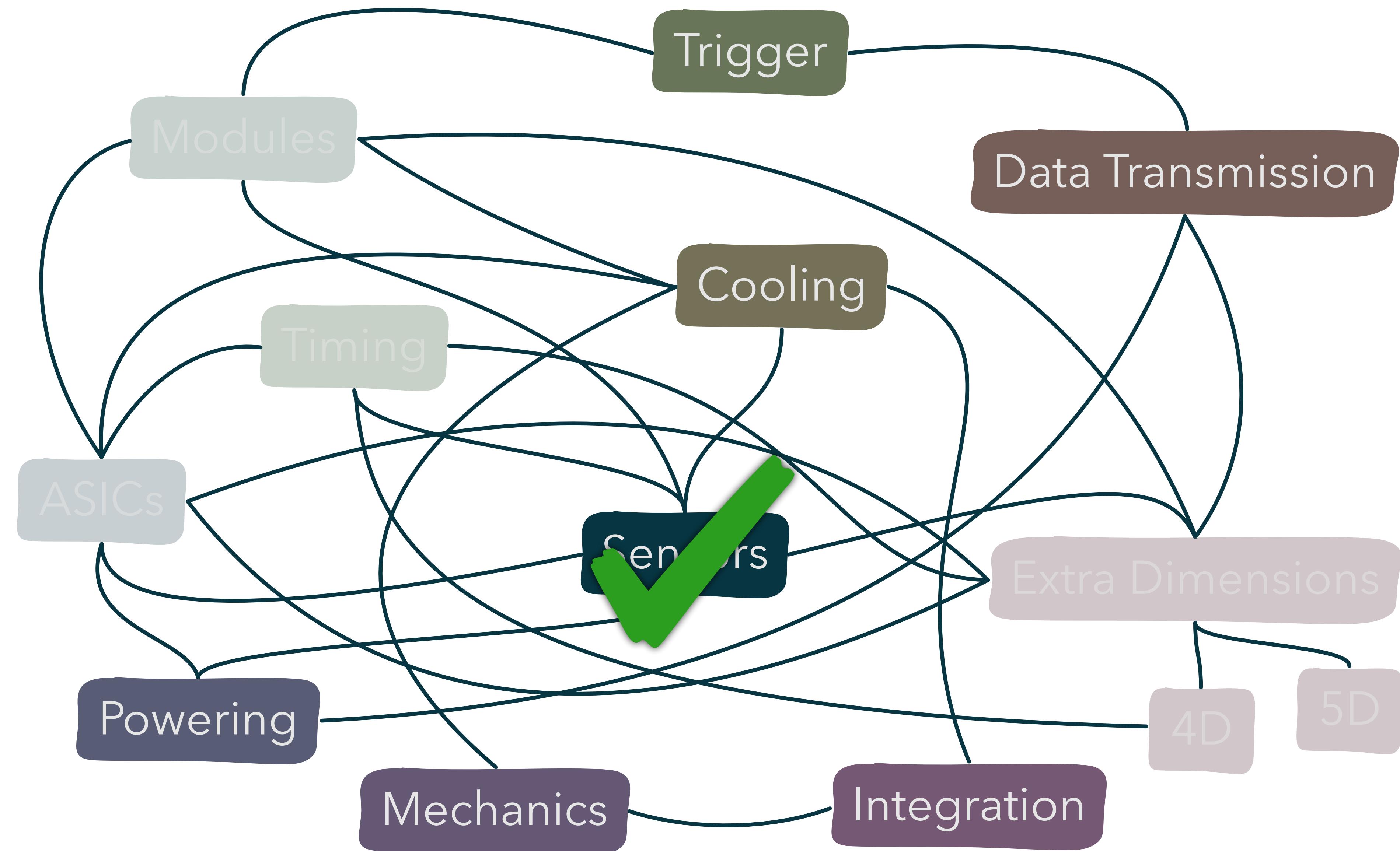
- Irradiation will change deep implant doping concentration
 - charge sharing probably changes with irradiation
 - to be checked with first prototype sensors
 - ELADs might not be suitable for hh machines
- Fewer strips on sensor but more data per cluster
 - Position reconstruction requires amplitude information
 - binary readout will not work
 - cluster size always > 1



orange = clustersize 2
blue = clustersize 1

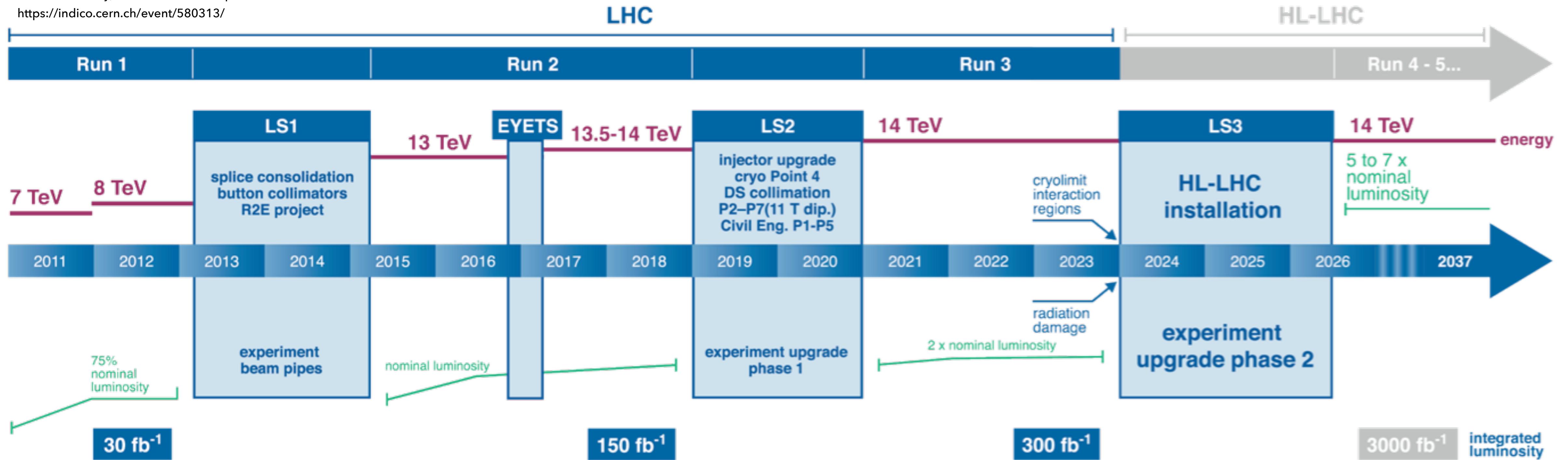
Improvement in resolution up to a factor 3!

Outline



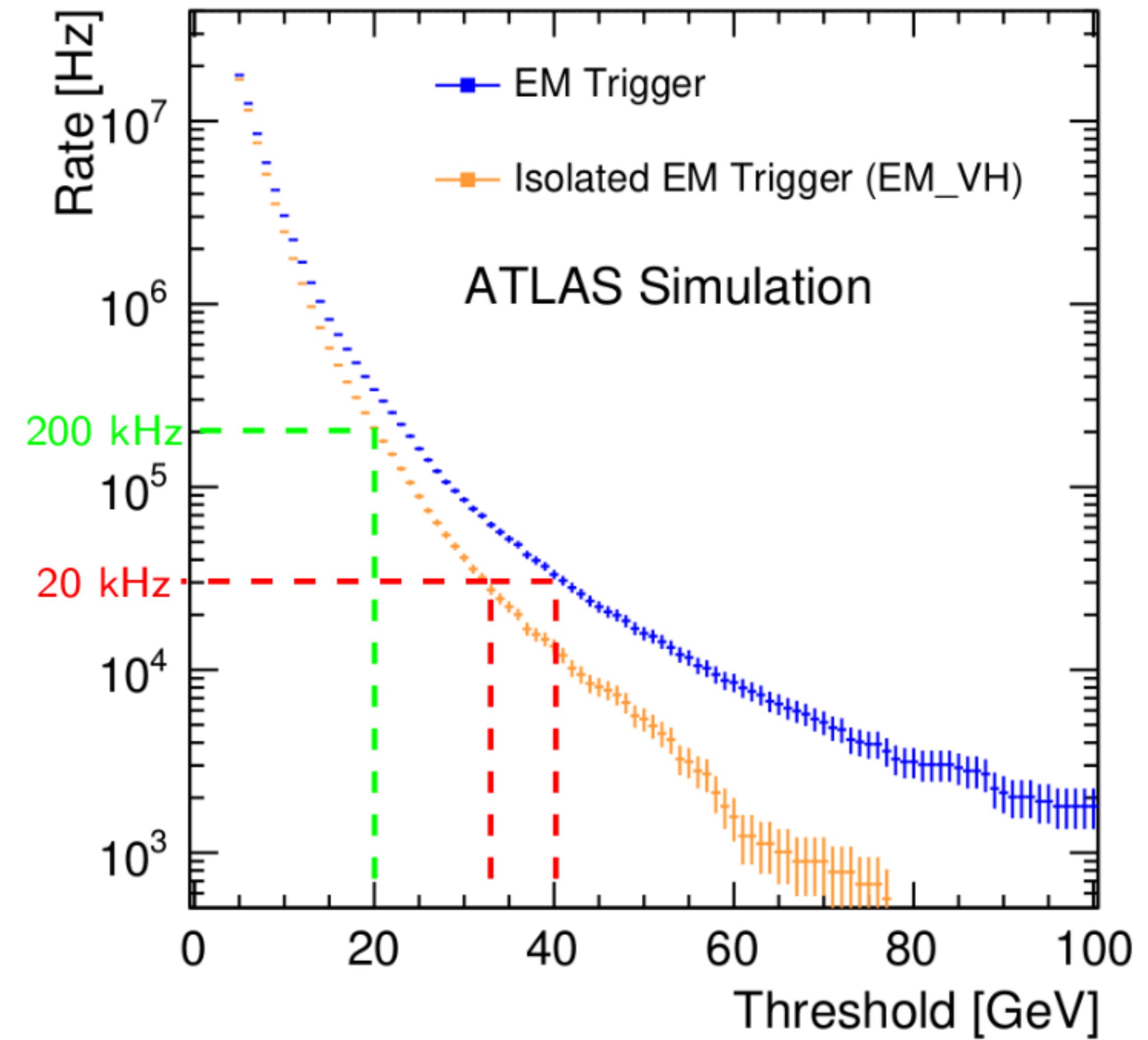
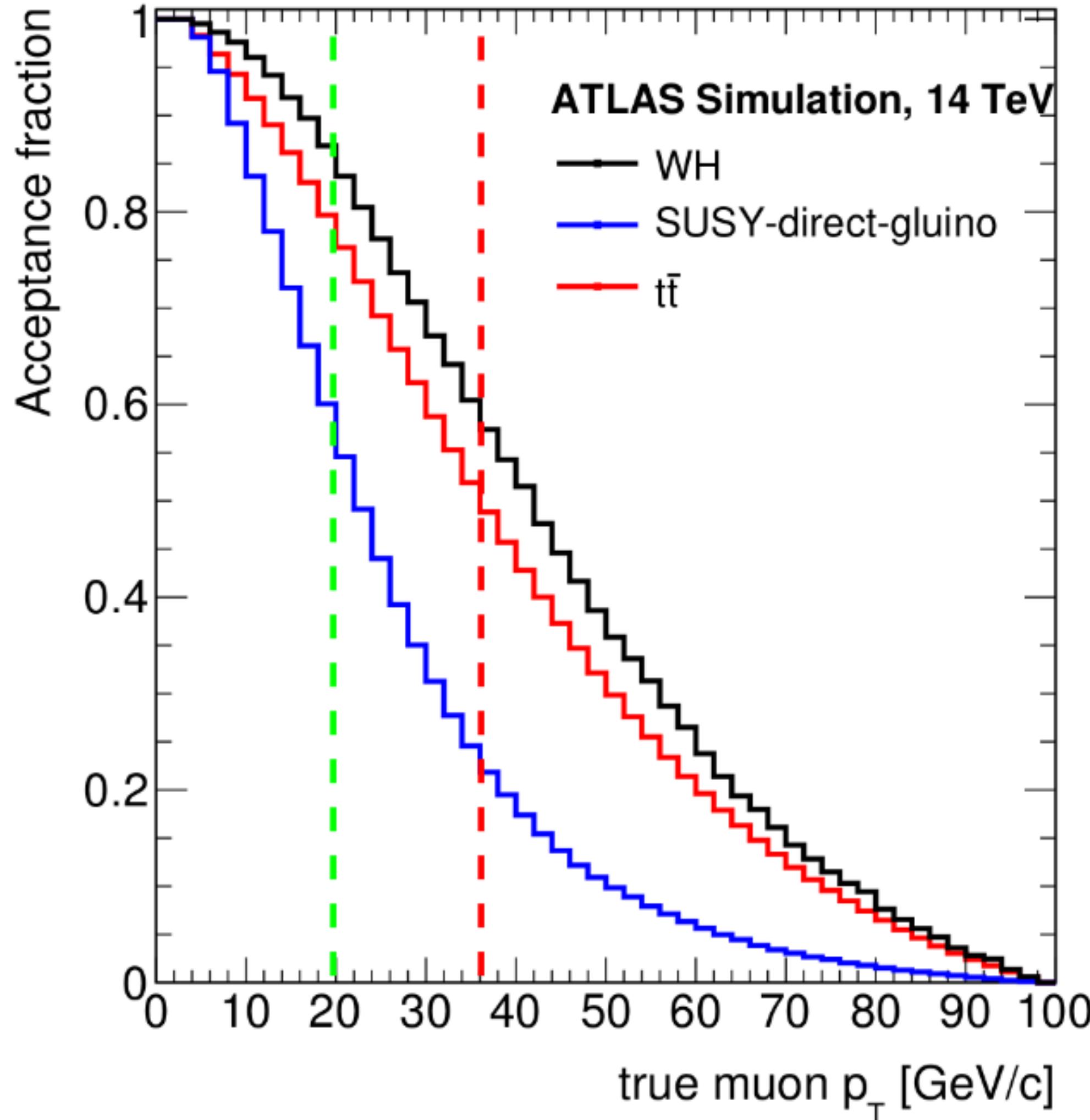
High-Luminosity LHC

Frédéric Bordry, Chamonix Workshop 2017
<https://indico.cern.ch/event/580313/>



- Exploit full potential of LHC and to collect up to 4000 fb⁻¹
 - Upgrades of accelerator and detectors are necessary to reach this ambitious goal
 - Primary motivation of all upgrades is to maximise physics reach, which drives the design choices for the detector upgrades
- Future trackers have to deal with
 - higher radiation levels → sensor & electronics design, cooling
 - pile up of up to 200 at 7.5x10³⁴ cm⁻²s⁻¹ → higher bandwidth, use of tracker information at early trigger stage
 - higher track density → increased granularity
- LS3 will start 2025 as we heard yesterday

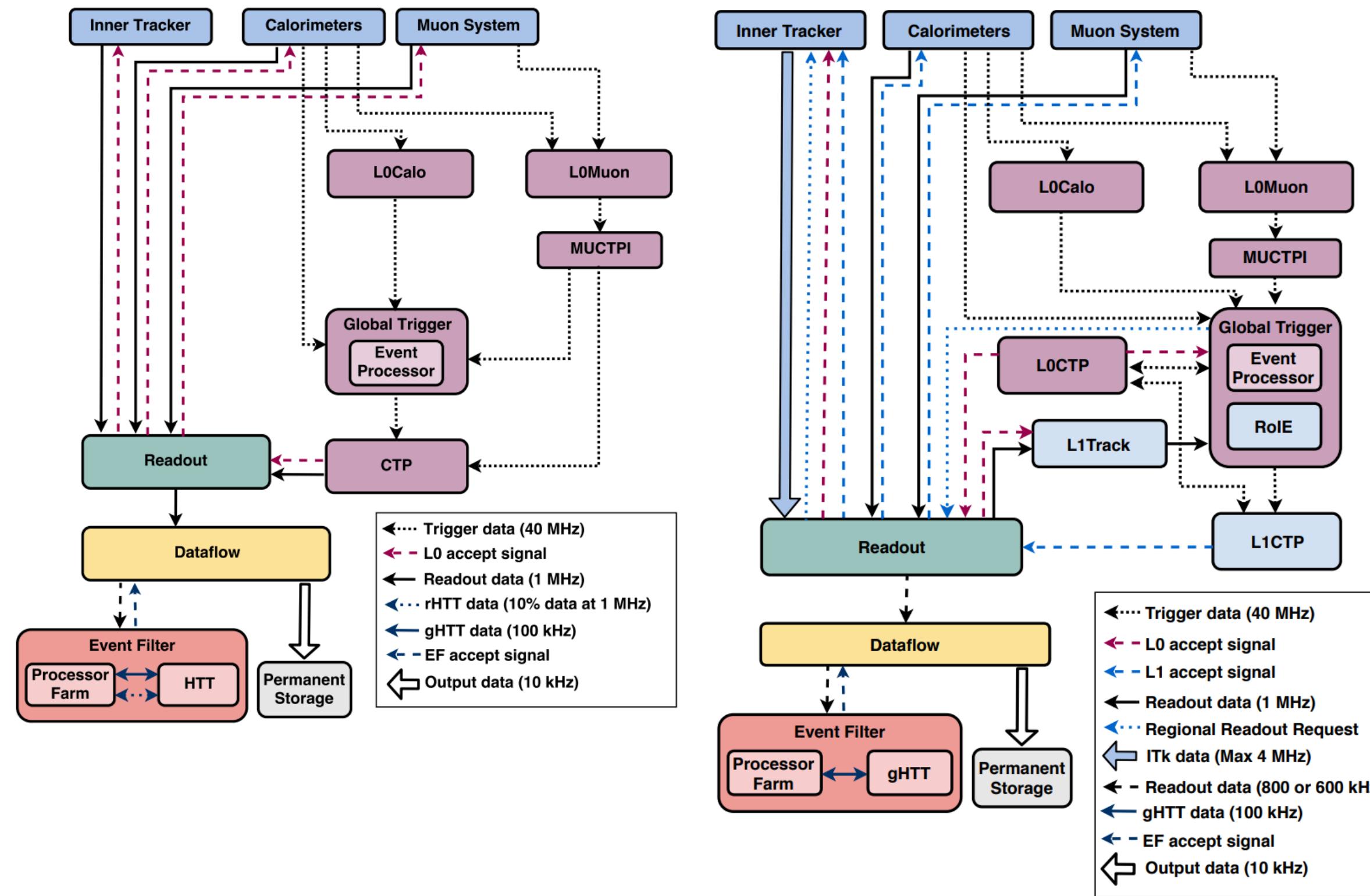
Triggering at HL-LHC



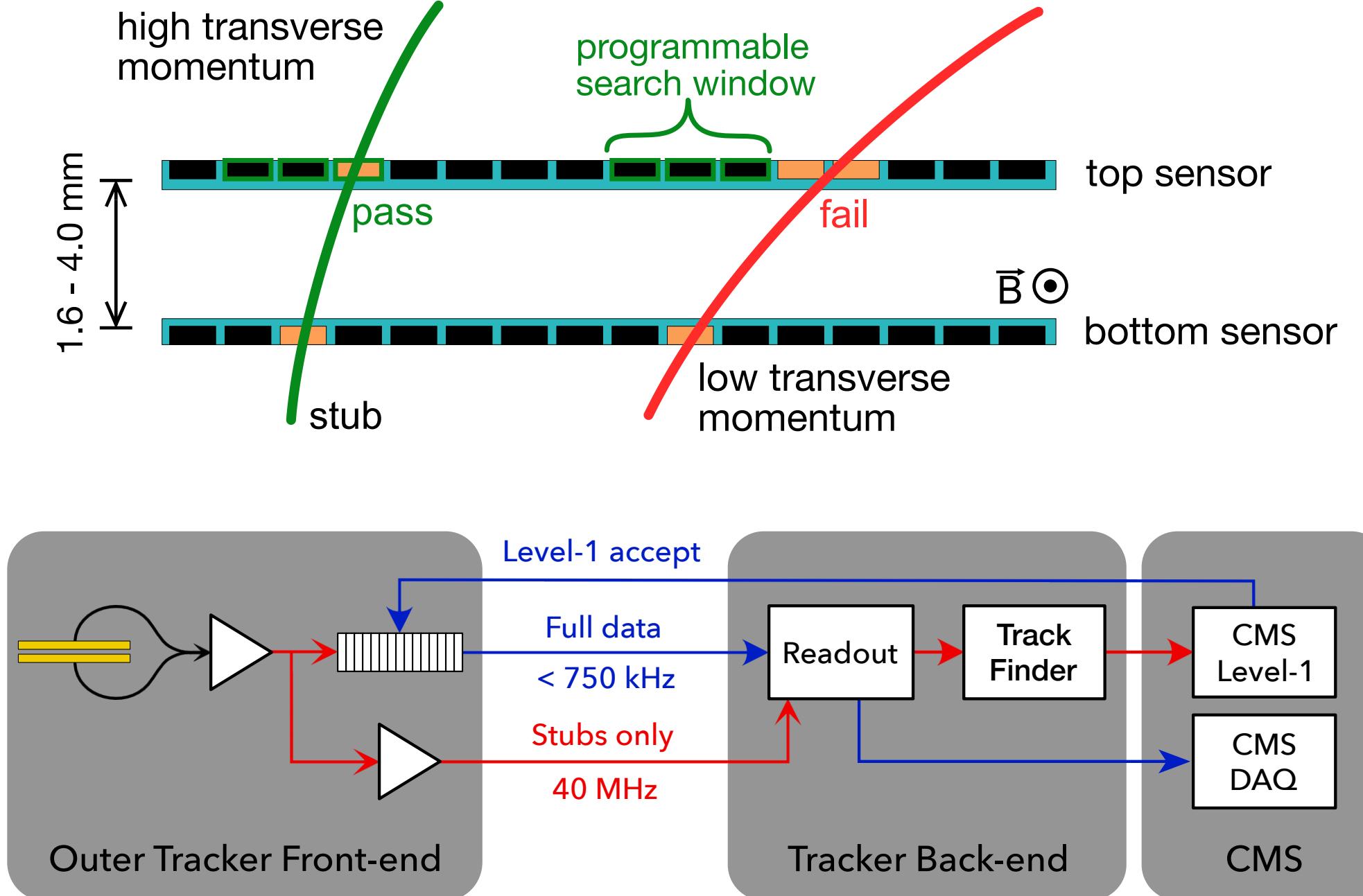
- Increasing the trigger p_T threshold to lower the rate would limit the physics reach
- Trigger has to become 'smarter' → use tracker information in an early trigger stage

Track Trigger Implementations

ATLAS



CMS

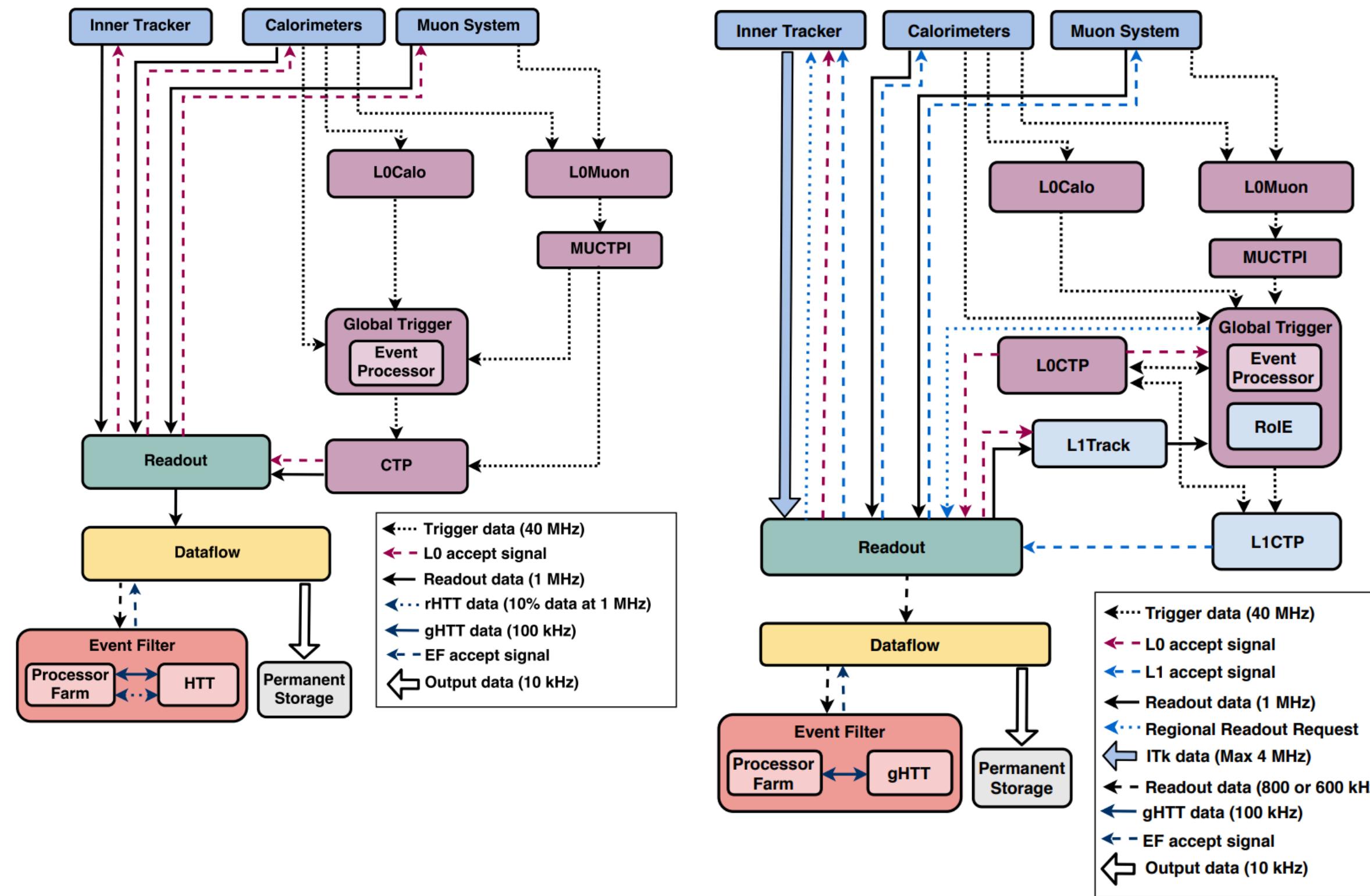


- Level-0 (L0): Muon and Calo trigger
- Two options:
 - L0 only, full detector readout and regional tracking in Event Filter
 - L0 and L1-Track
 - L0 initiates regional readout
 - regional data is used in track trigger

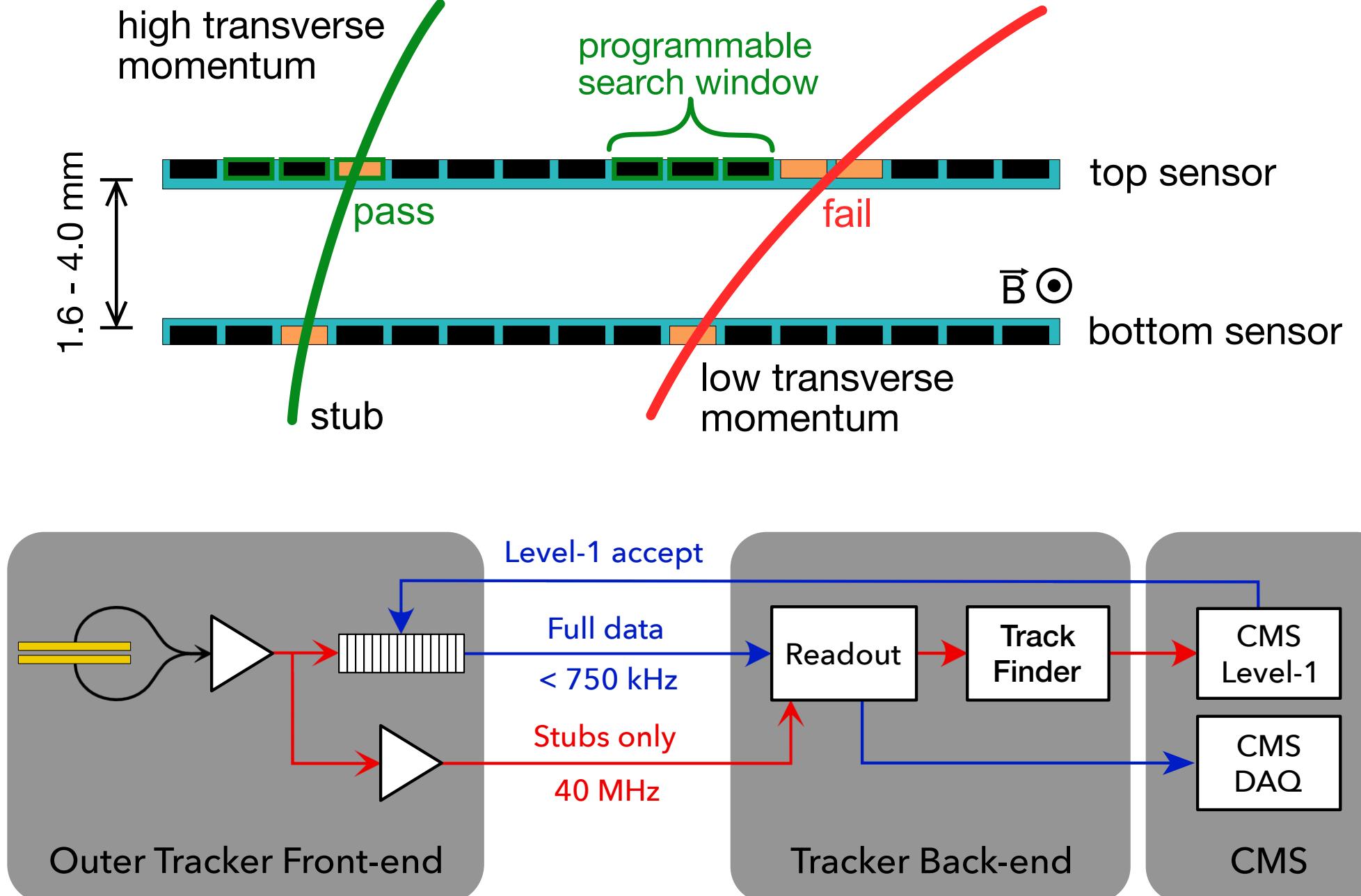
- Modules consist of two closely spaced sensors for local pT discrimination
- Minimalistic information for high-pT tracks is transferred to track trigger at 40 MHz
- Information from Track Trigger is used in Level-1 trigger

Track Trigger Implementations

ATLAS



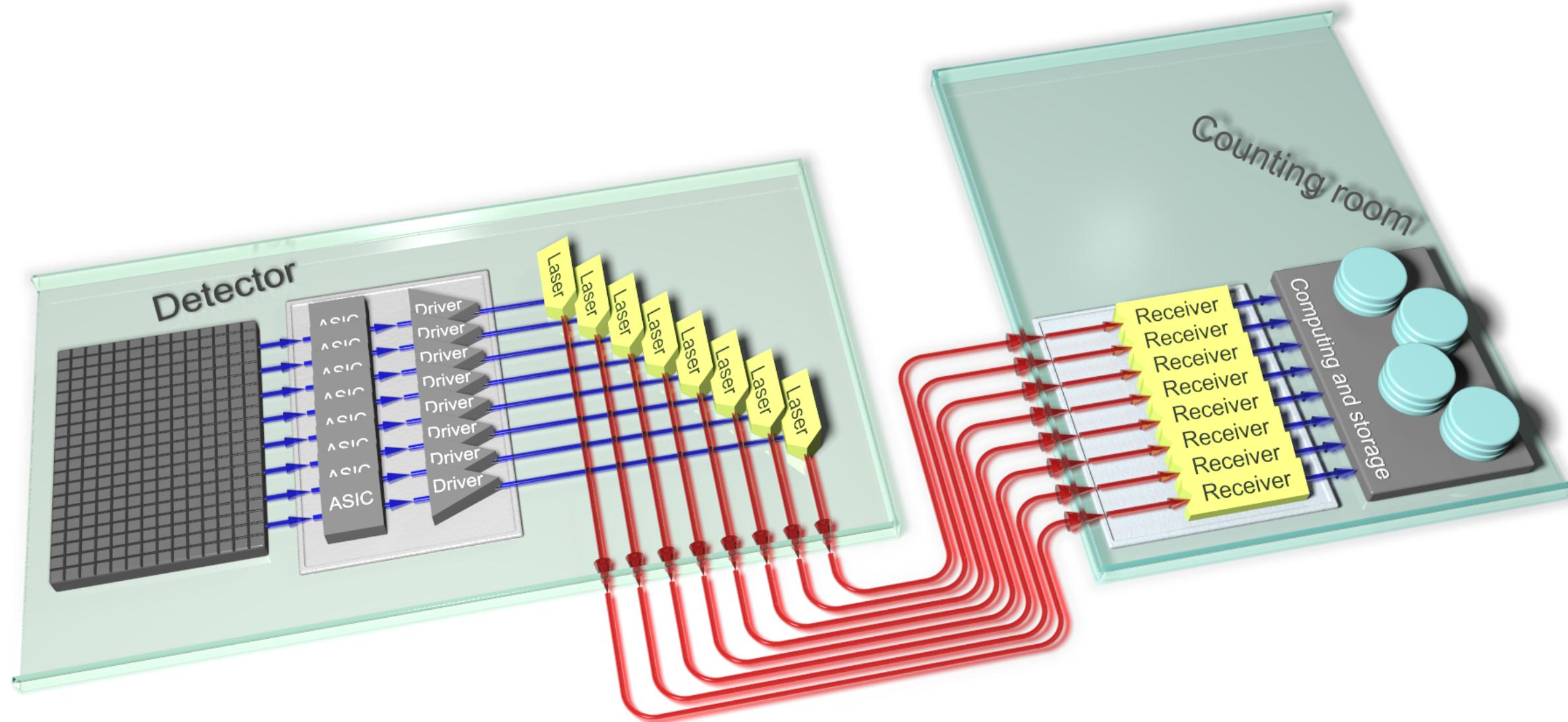
CMS



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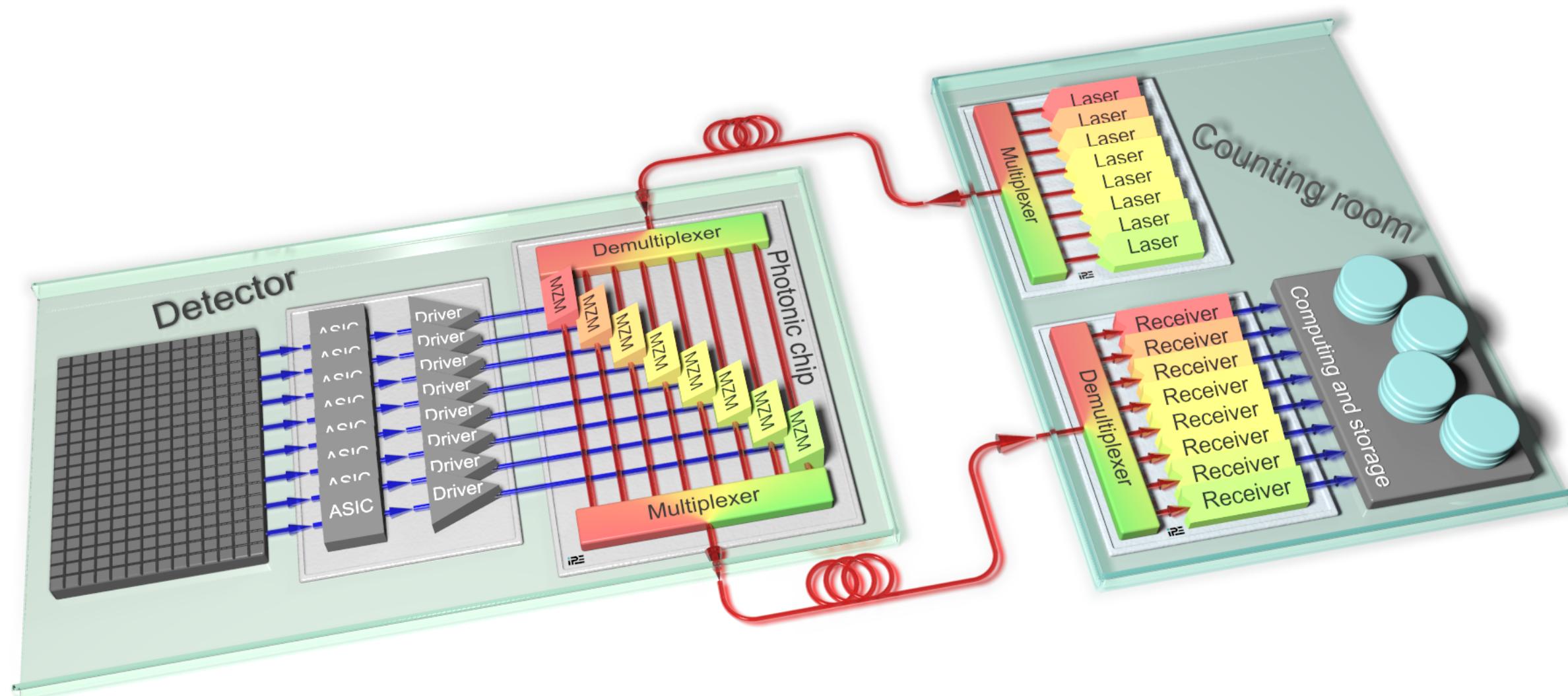
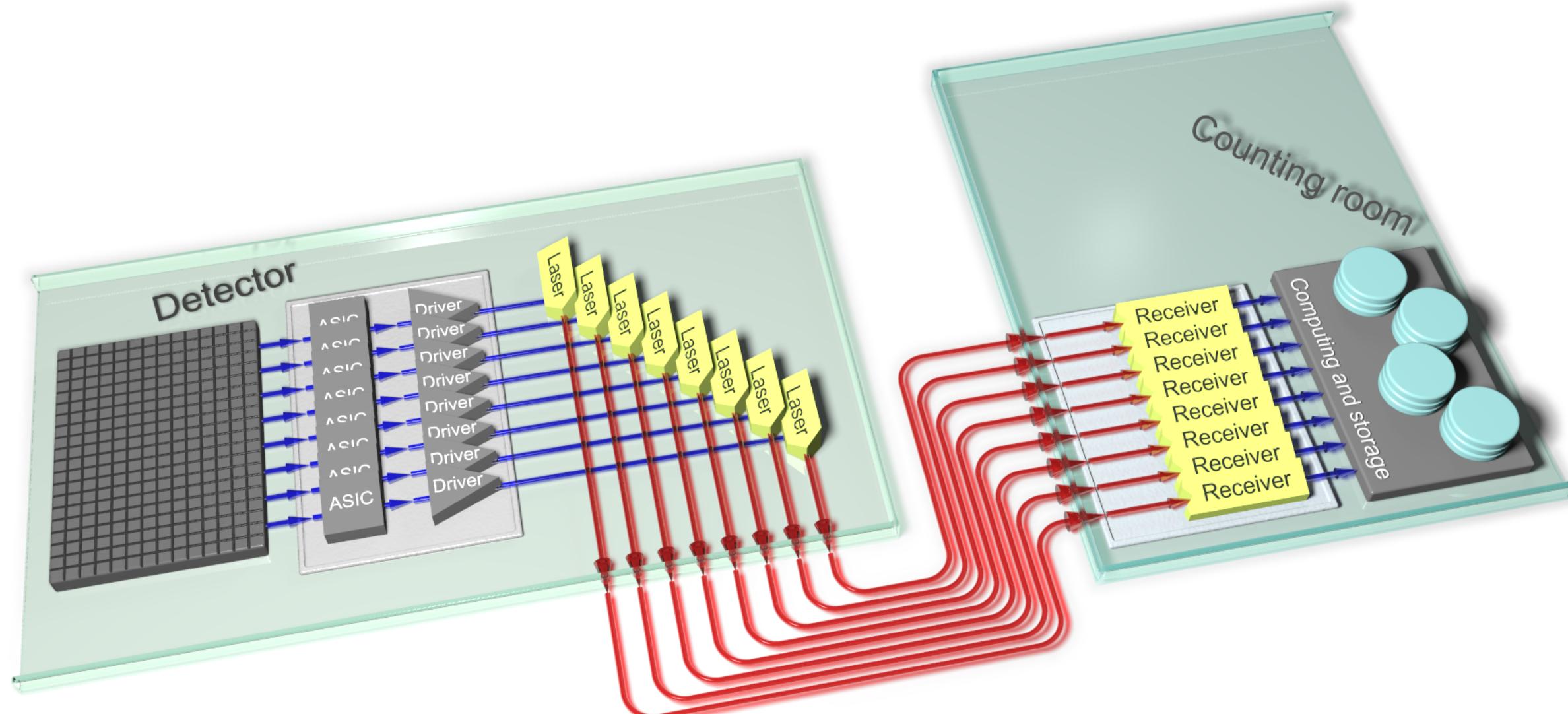
- Modules consist of two closely spaced sensors for local pT discrimination
- M. Jeitler - *The Phase-2 Upgrade of the Hardware Trigger of CMS at the LHC*
- Information from Track Trigger is used in Level-1 trigger

The Future of Optical Links



- Current link implementation based on vertical cavity surface emitting lasers (VCSEL)
 - Information is encoded by varying the laser current
 - bandwidth limited to 10 Gbit/s per fibre
 - faster prototypes are under development but
 - only one modulated signal per fibre
 - radiation tolerance of the VCSEL is an issue

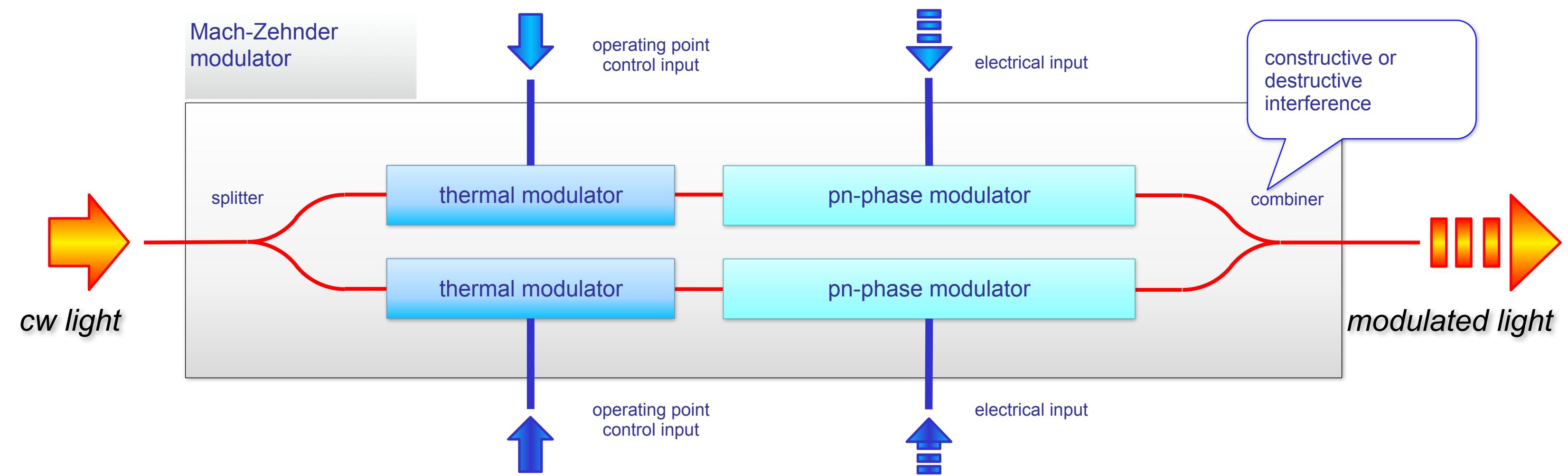
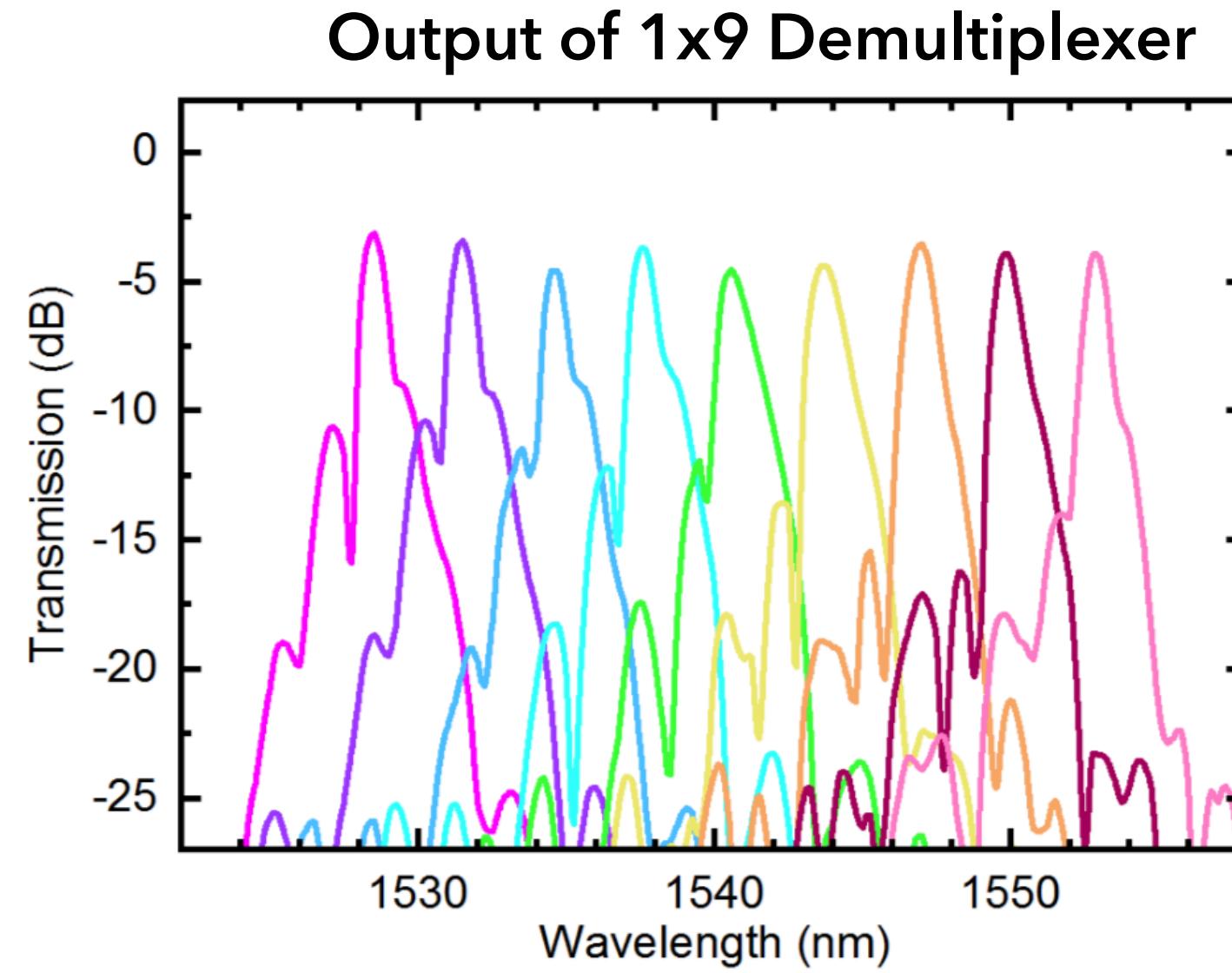
The Future of Optical Links



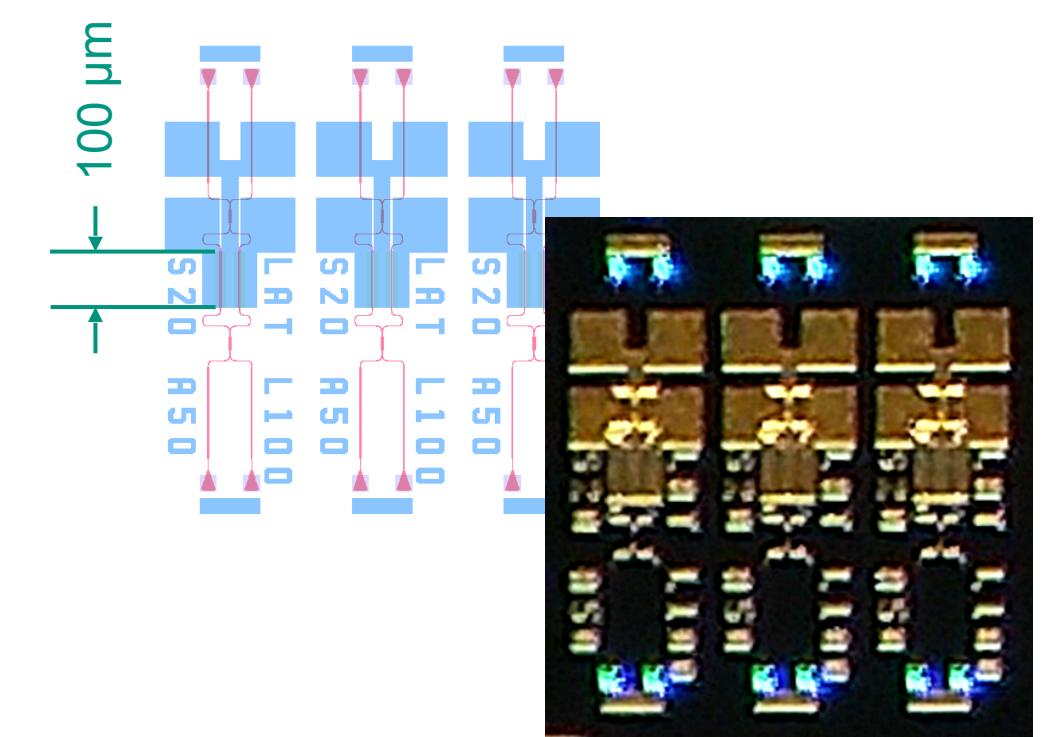
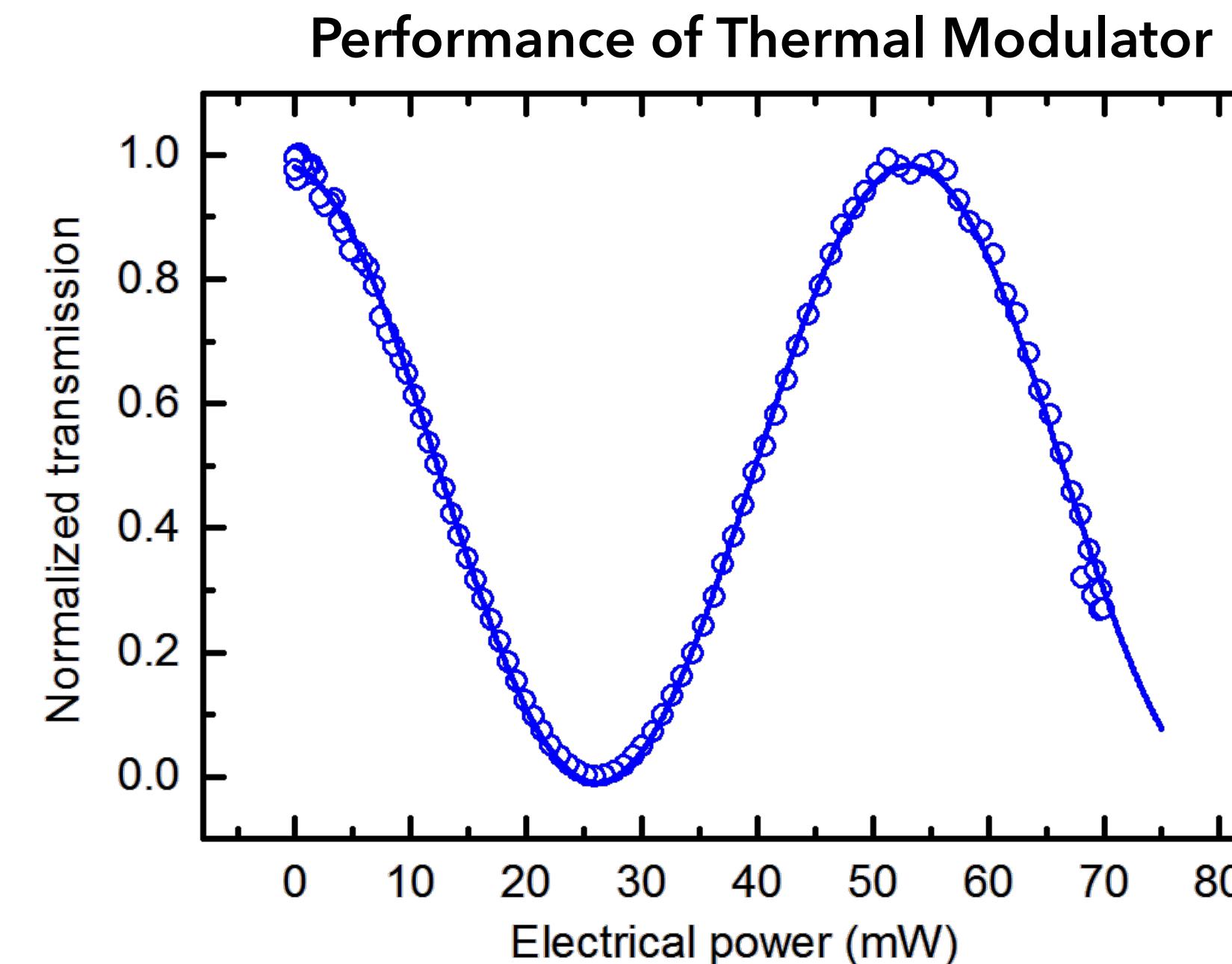
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- Even higher bandwidth requirements in future detectors expected
- Could be addressed by silicon photonics and Wavelength Division Multiplexing (WDM) technology
 - optical multiplexer combine light from stabilized lasers
 - optical carriers are separated by wavelength through Echelle grating demultiplexer in the front end
 - individual optical carriers are modulated by Mach-Zehnder modulators (MZMs)
 - modulated optical signals are multiplexed by second Echelle grating and transmitted to the back end

The Future of Optical Links



- Length of thermal modulator is only $100 \mu\text{m}$
- 2π -shift at $\approx 58 \text{ mW}$
- Potential to reduce power needed for data transmission
 - no laser diodes in front-end



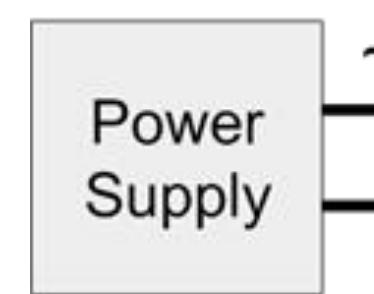
Powering Schemes

- DC-DC powering widely accepted in HEP as a viable powering scheme
- Serial powering will be used in Phase-2 pixel detectors
 - space constraints
 - material budget

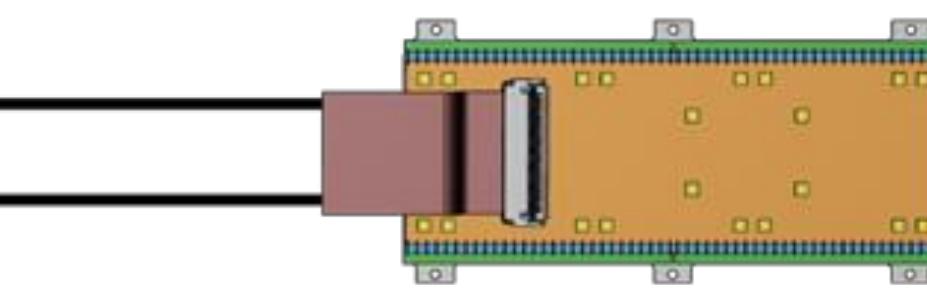
Certainly not complete
Many simplifications

Experiment	Sub-detector	What	How	Where
CMS	Outer Tracker	Strip modules, LpGBT, VTRx+	DC-DC	Front-end
	Phase-1 pixel	Pixel modules	DC-DC	Patch panel
	Phase-2 pixel	LpGBT, VTRx+	DC-DC	Patch panel
		Pixel modules	Serial	
	Endcap calorimeter	Silicon modules, LpGBT, VTRx+	DC-DC	Patch panel or front-end
	Barrel calorimeter	Crystal ADC	DC-DC	Front-end
	Muon system (GEM)	Chambers	DC-DC	Front-end
ATLAS	Timing detector	Readout, LpGBT, VTRx+	DC-DC	Front-end
	Strips	Strip modules, LpGBT, VTRx	DC-DC	Front-end
	Phase-2 pixel	LpGBT, VTRx+	DC-DC	Patch panel
		Pixel modules	Serial	
	Tile calorimeter	Electronics	DC-DC	Patch panel
	Liquid argon calorimeter	Electronics	DC-DC	Front-end
LHCb	Muon micromegas	GBTx, VTRx	DC-DC	Front-end
	Velo	Pixel modules, GBTx	DC-DC	Patch panel
ALICE	Fiber tracker	Fiber modules, GBTx, FPGA	DC-DC	Front-end
	Pixels	Pixel modules	DC-DC	Front-end
Belle 2	SVD	Silicon modules	DC-DC	Patch panel

Serial Powering for ATLAS & CMS Phase-2 Pixels



$\sim 1.2 \text{ V}$

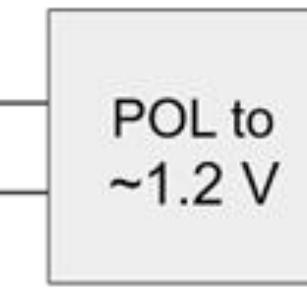


Direct powering

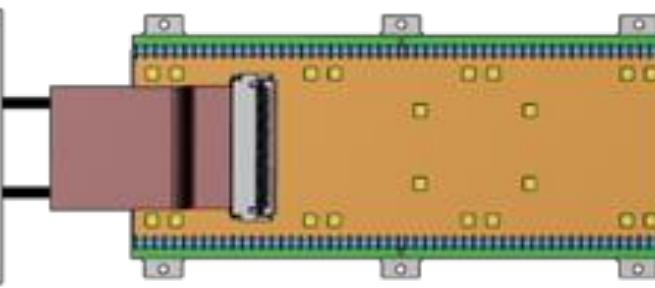
50kW/1.2V ~ 40kA
(20kg or 10% X_0 of Copper)



$\sim 12 \text{ V}$

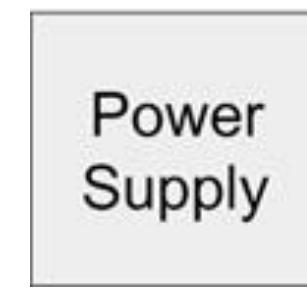


POL to
 $\sim 1.2 \text{ V}$



Local (POL) conversion

DCDC converters not enough radiation
hard, heavy and bulky (no space)



$\sim 1.2 \text{ V} \cdot n$

#1

#2

#n

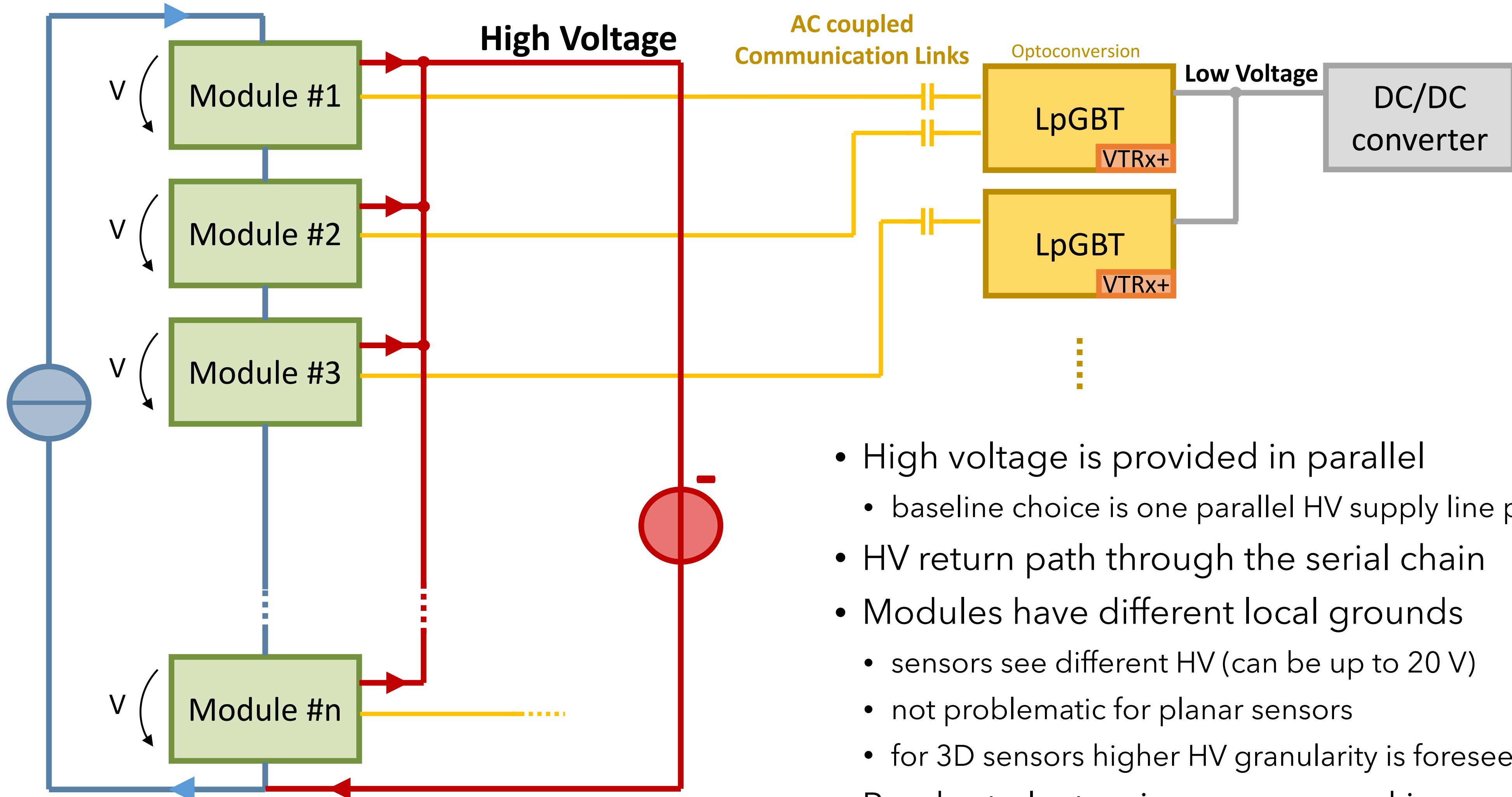
Serial powering!
40kA/(n~8-10)



- Numbers on this slide are for CMS, values for ATLAS are very similar
- Estimated power consumption of CMS Phase-2 Pixels is 50 kW
 - direct powering would result in substantial losses in cables and increase in mass due to cables
 - DC-DC converters are not radiation hard enough and there is no space for them anyway
- Serial powering is a viable solution
 - all the elements in a chain see the same current by construction
 - voltage is equally shared if all elements represent the very same and constant load, which is maintained by a Shunt LDO in the ROC
- However: three different powering/supply schemes mixed in a single system

Serial Powering for ATLAS & CMS Phase-2 Pixels

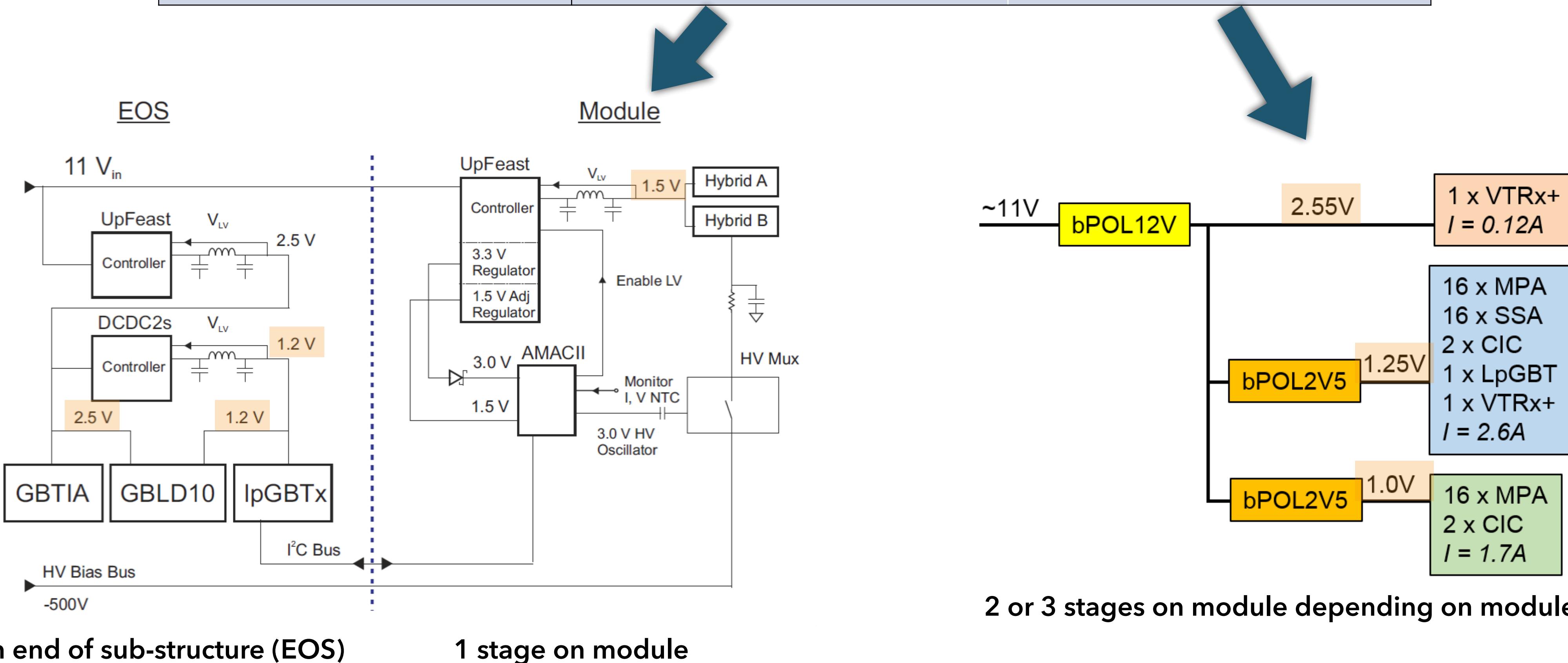
Constant current



- High voltage is provided in parallel
 - baseline choice is one parallel HV supply line per serial chain
- HV return path through the serial chain
- Modules have different local grounds
 - sensors see different HV (can be up to 20 V)
 - not problematic for planar sensors
 - for 3D sensors higher HV granularity is foreseen
- Readout electronics are powered in parallel with DC-DC converters
 - AC coupling of front-end ASICs required

DC-DC Low Voltage Powering Schemes

	ATLAS	CMS
Supply voltages	1.5 V for ROCs 2.55 V for VTRx+ 1.25 V for LpGBT, VTRx+, ...	1.25 V and 1.0 V for ROCs 2.55 V for VTRx+
Number of modules	17 888	13 296
Total front-end power	70kW	85kW

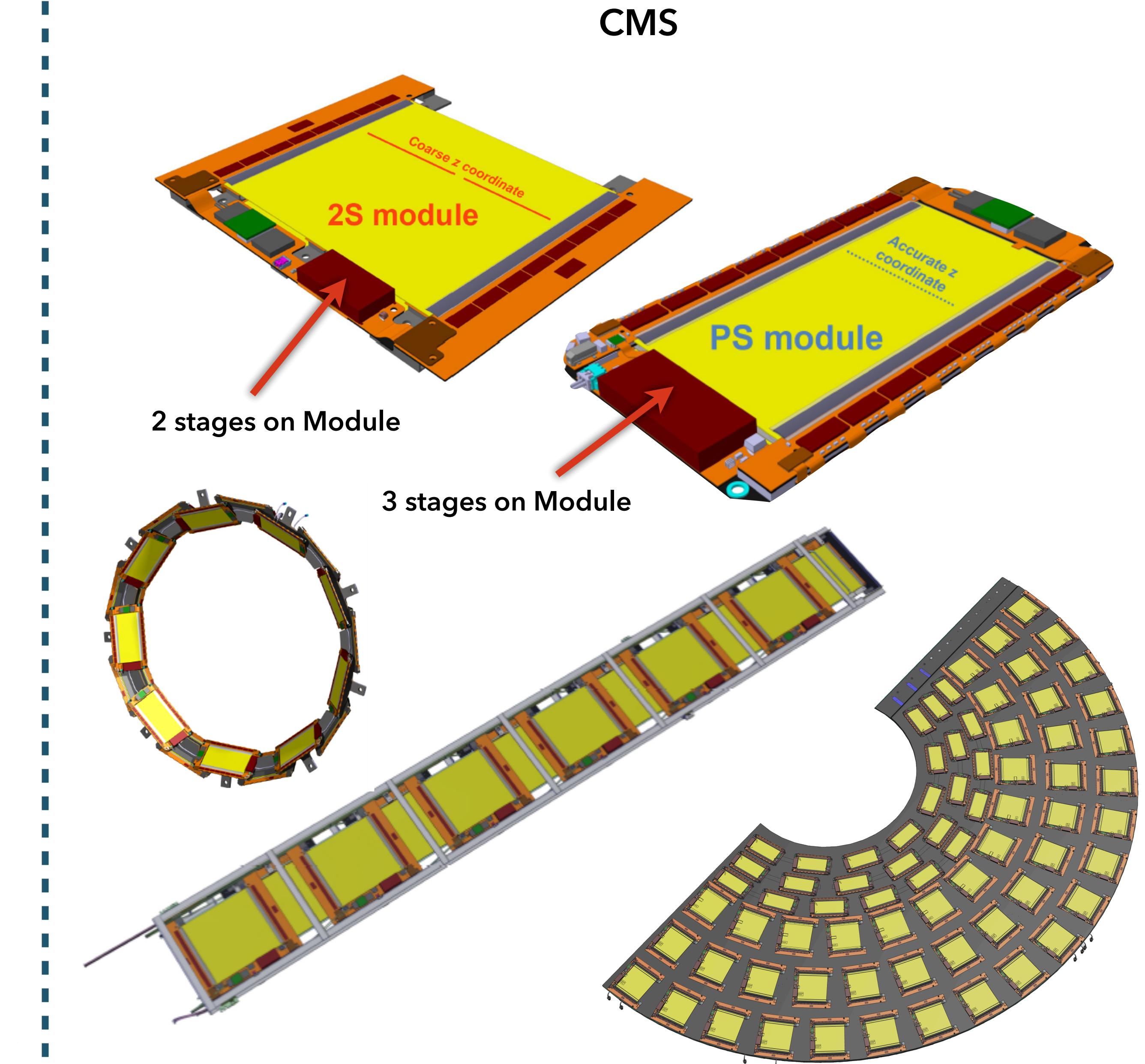
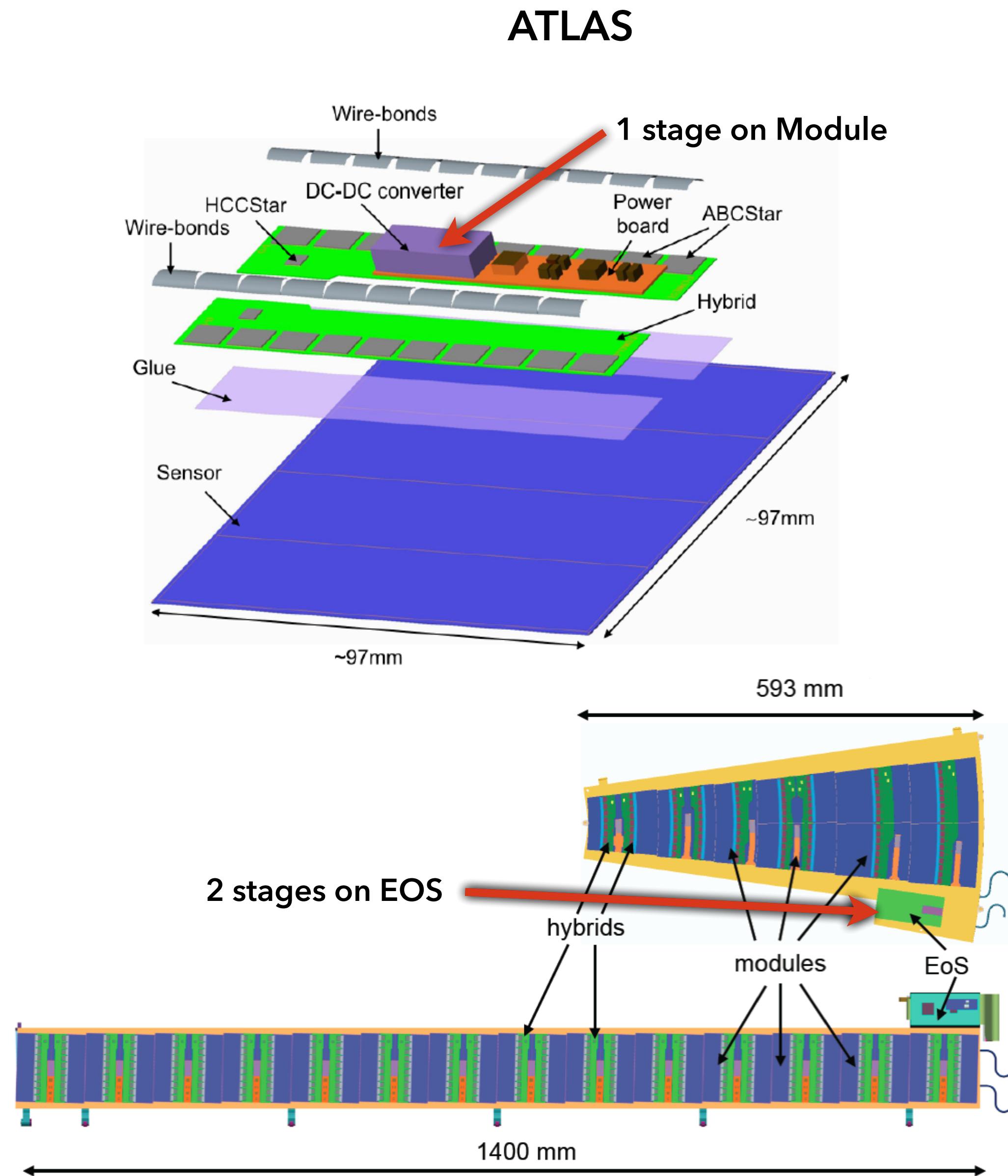


2 stages on end of sub-structure (EOS)

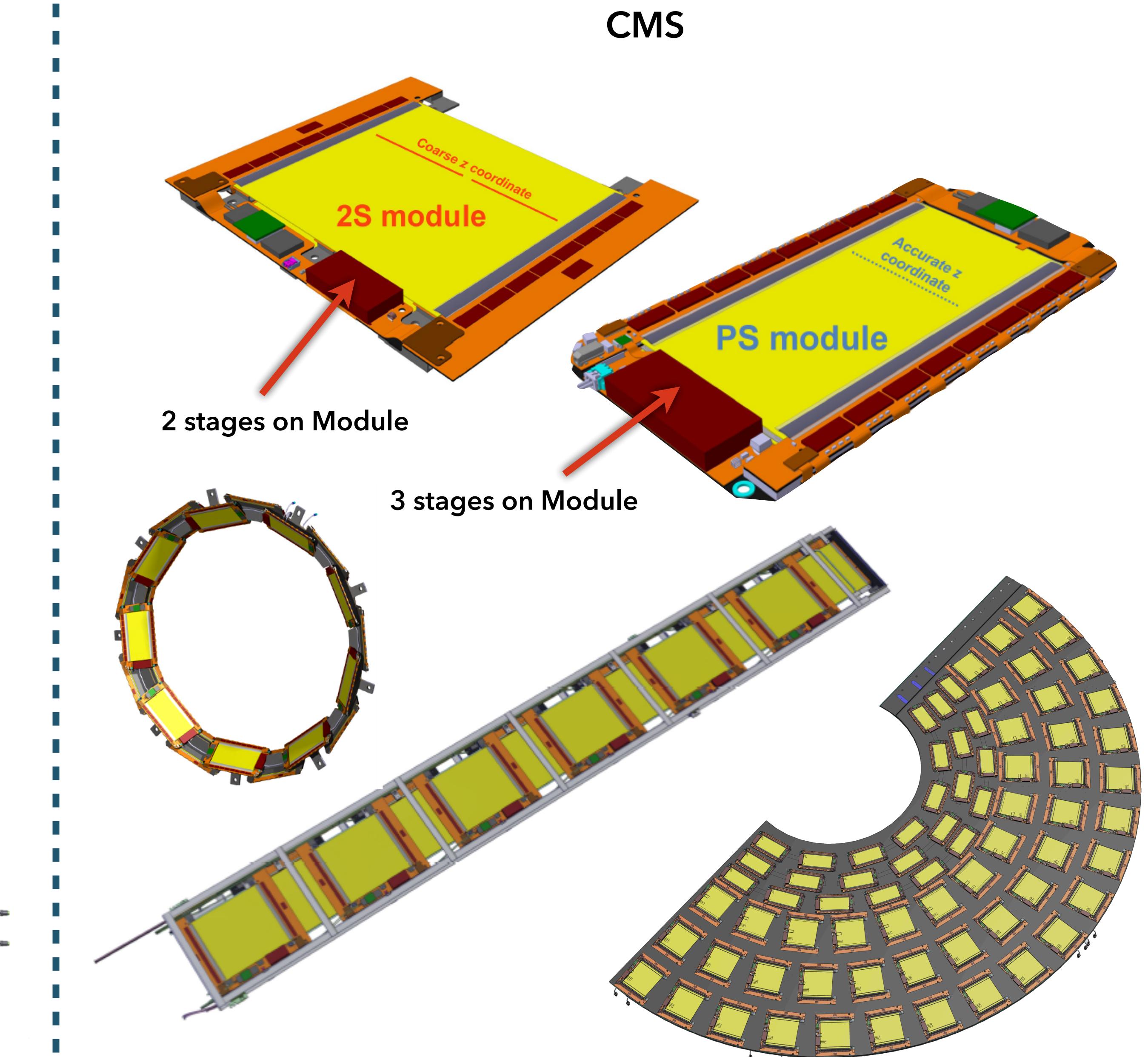
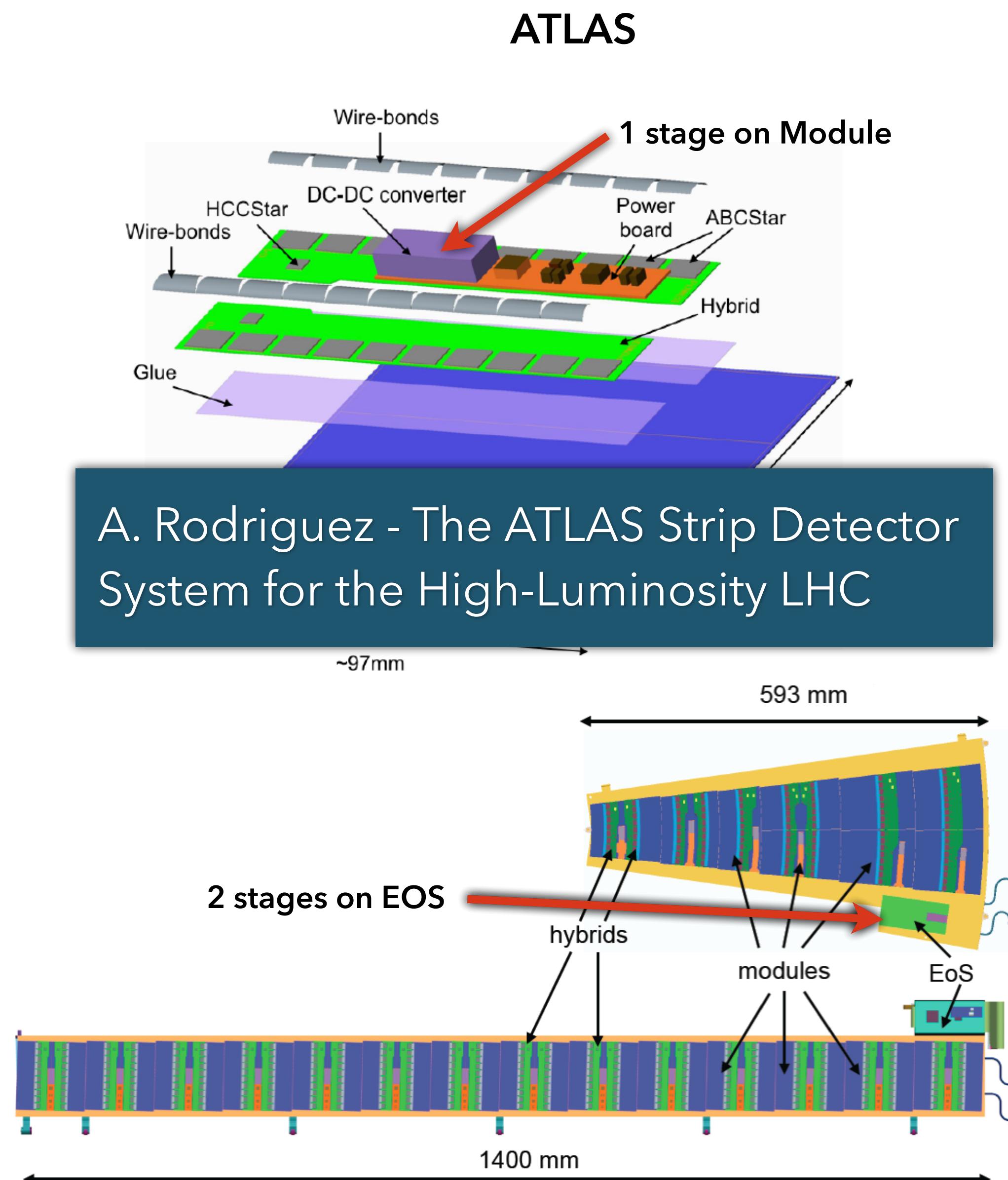
1 stage on module

2 or 3 stages on module depending on module type

DC-DC Low Voltage Powering Implementation

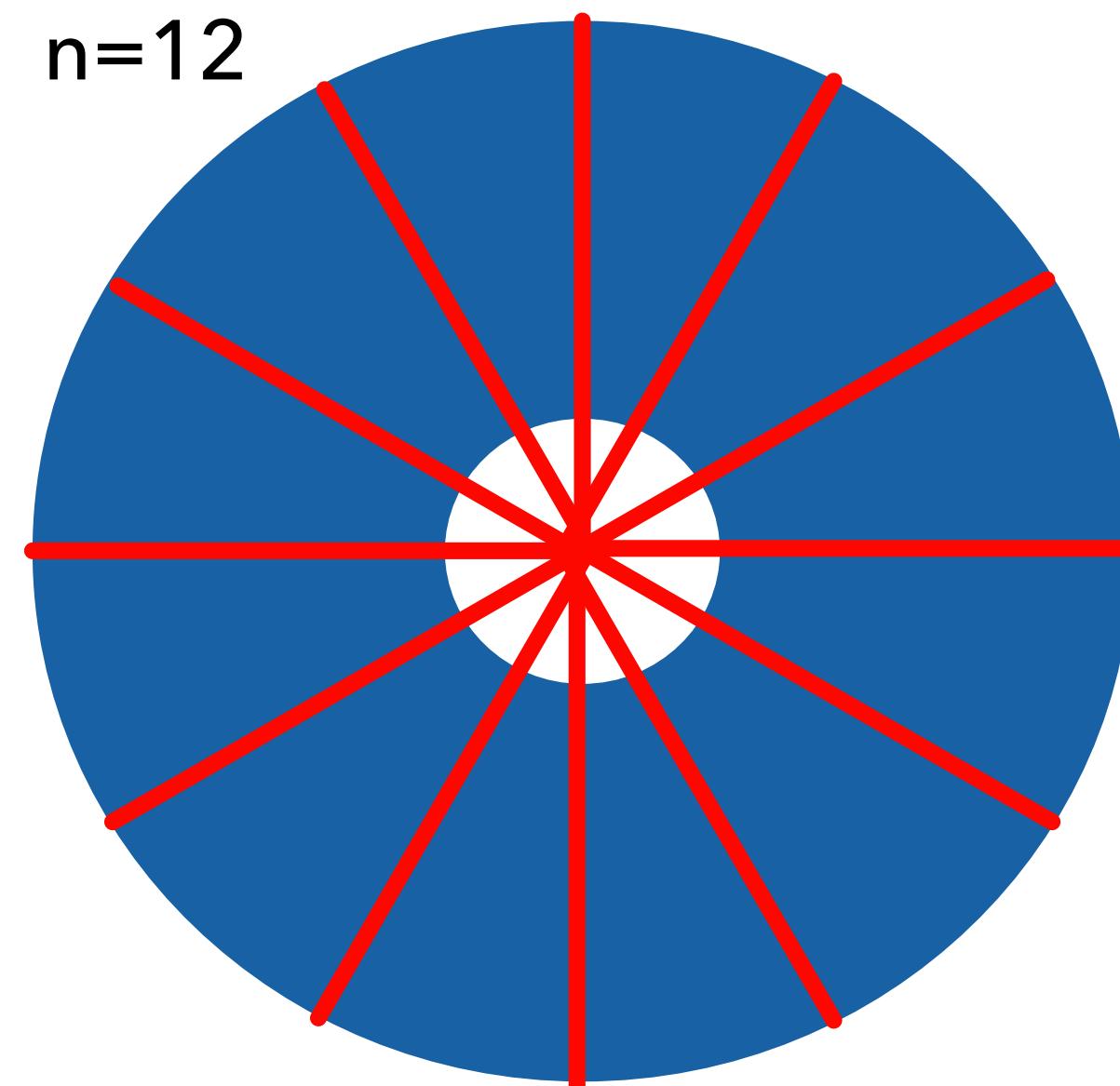
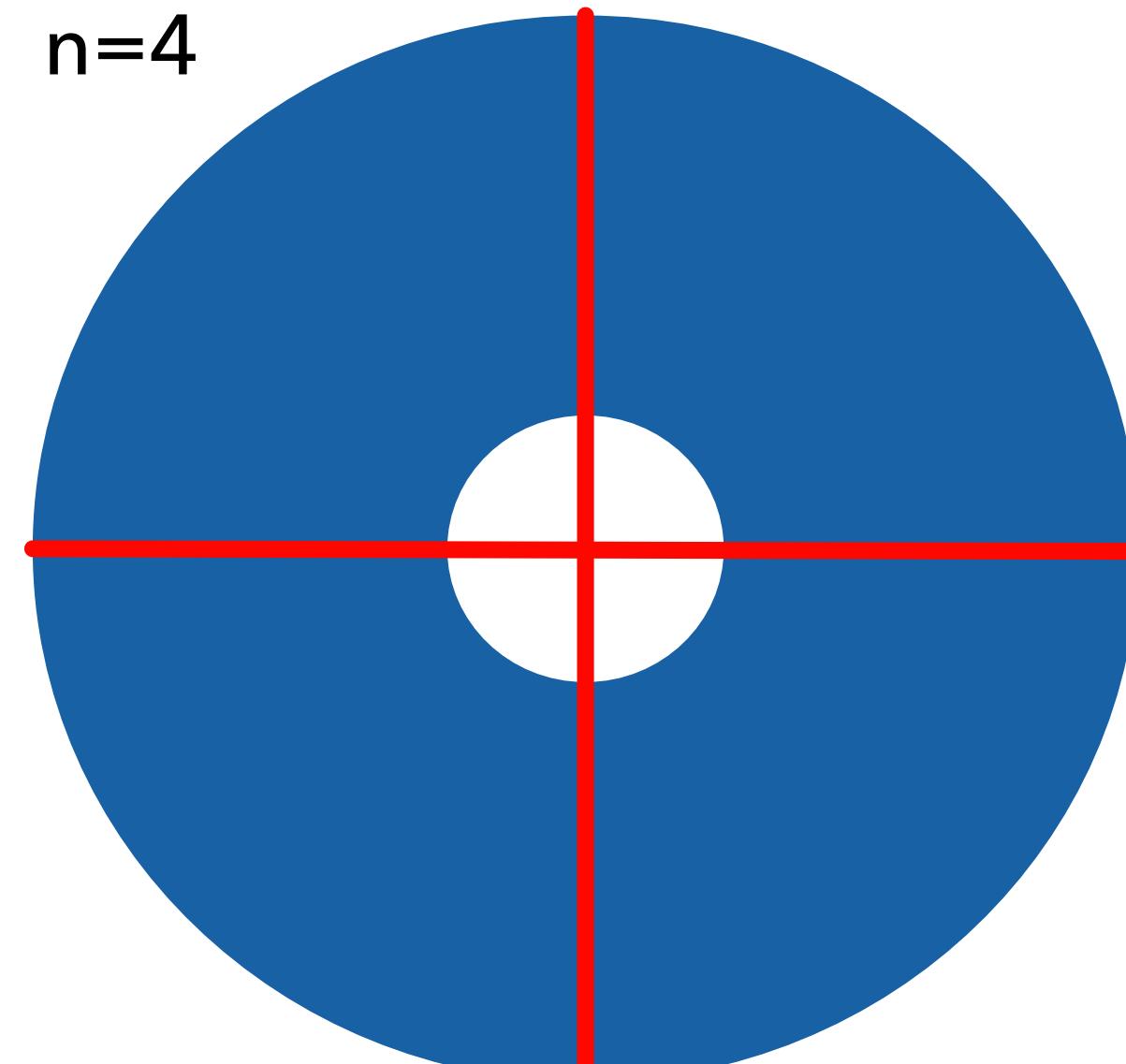
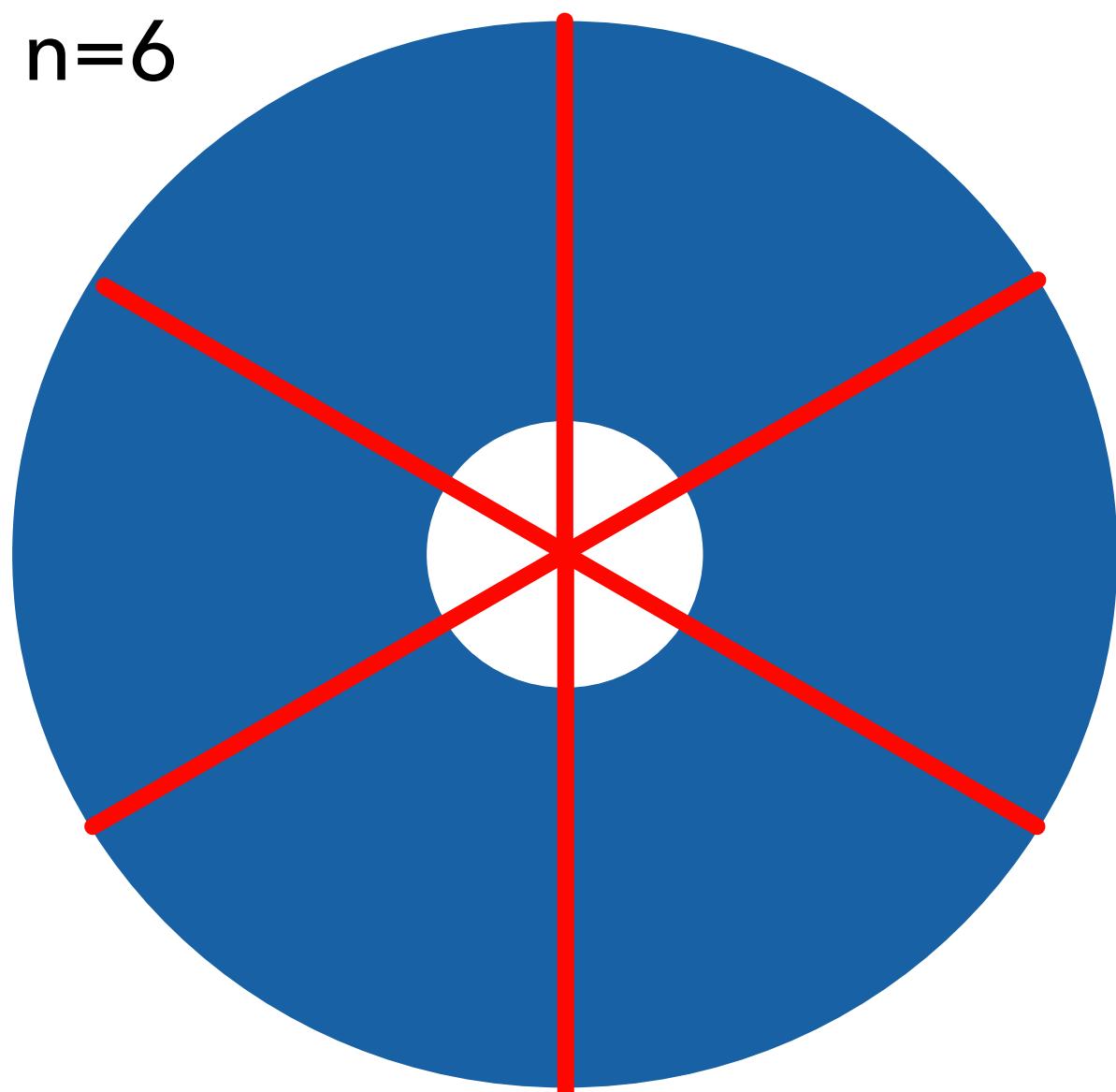
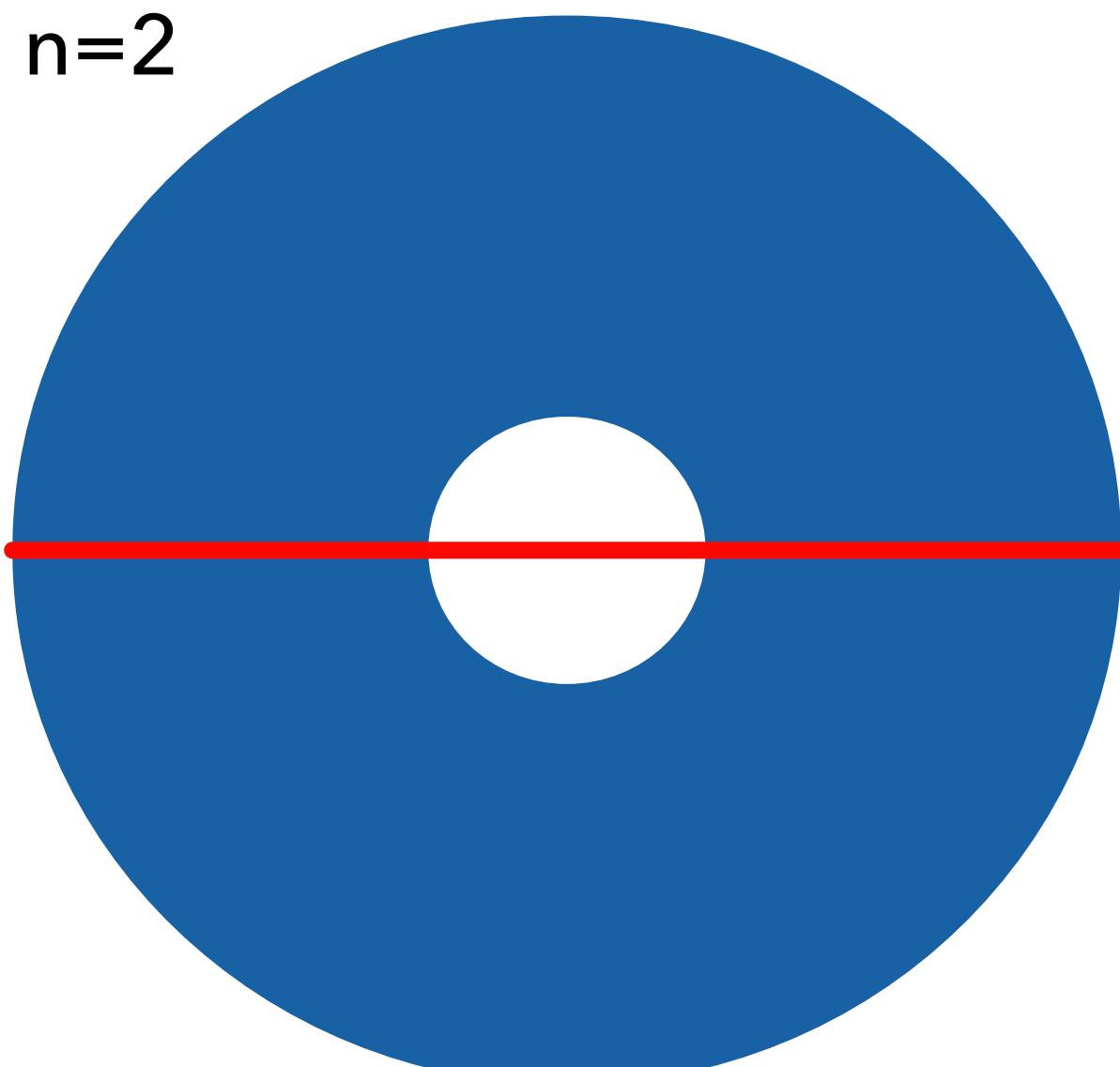


DC-DC Low Voltage Powering Implementation



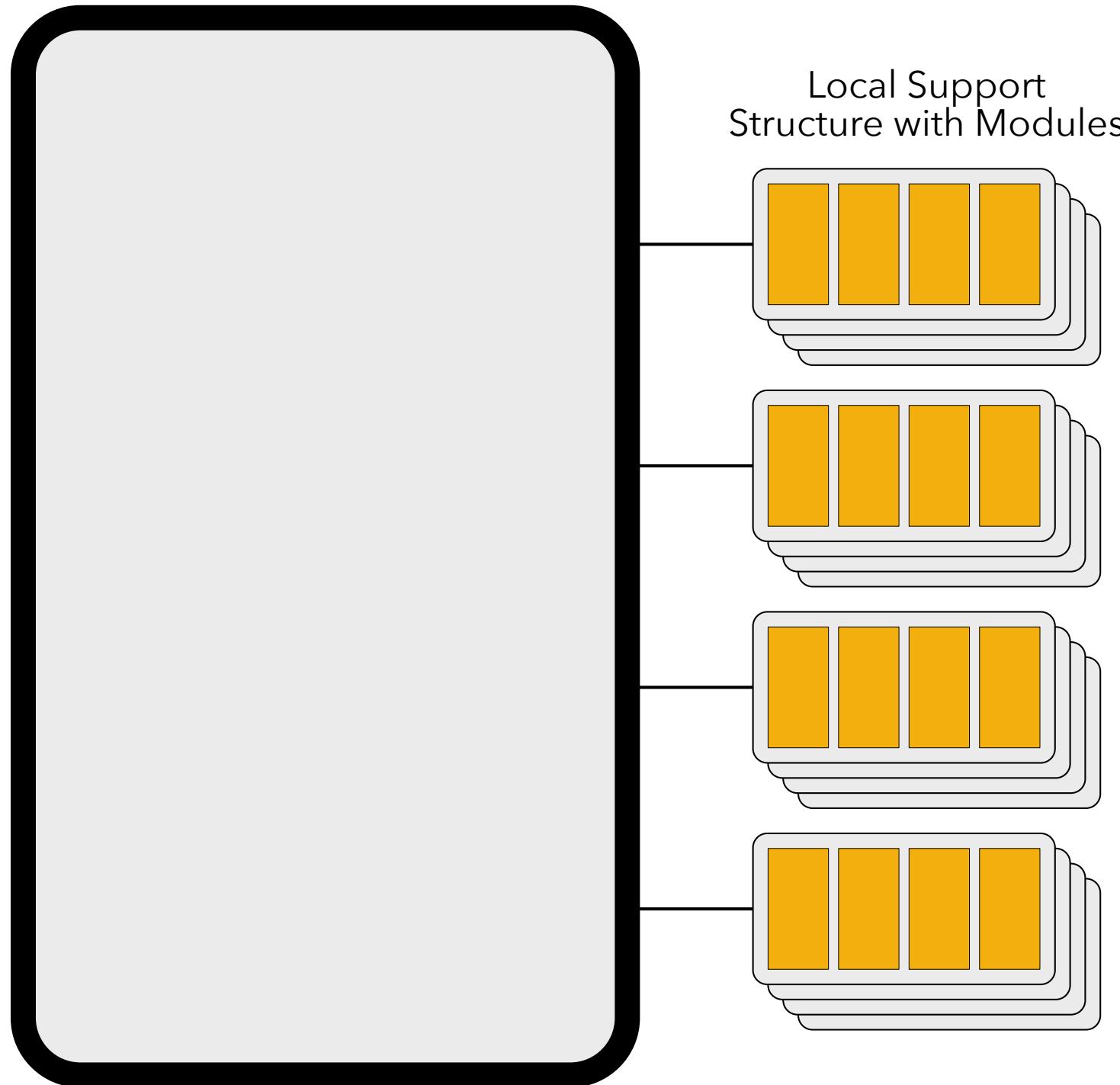
ATLAS & CMS End Caps - A Conceptual Comparison

- A single disk support structure would be ideal in terms of overlaps
- With a diameter of over 2 m this becomes a tricky business
 - production requires really special/large autoclaves and machines
 - large number of modules per structure is challenging from a handling point of view
- Divide structure in n parts
 - number of modules per ring must be dividable by n
 - more overlaps \rightarrow additional mass
 - handling becomes easier with increasing n
- $n = 2$ and $n = 4$: still fairly large in terms of handling
- $n > 6$: overlaps become an issue
 - transition to wedge-shaped sensors needed

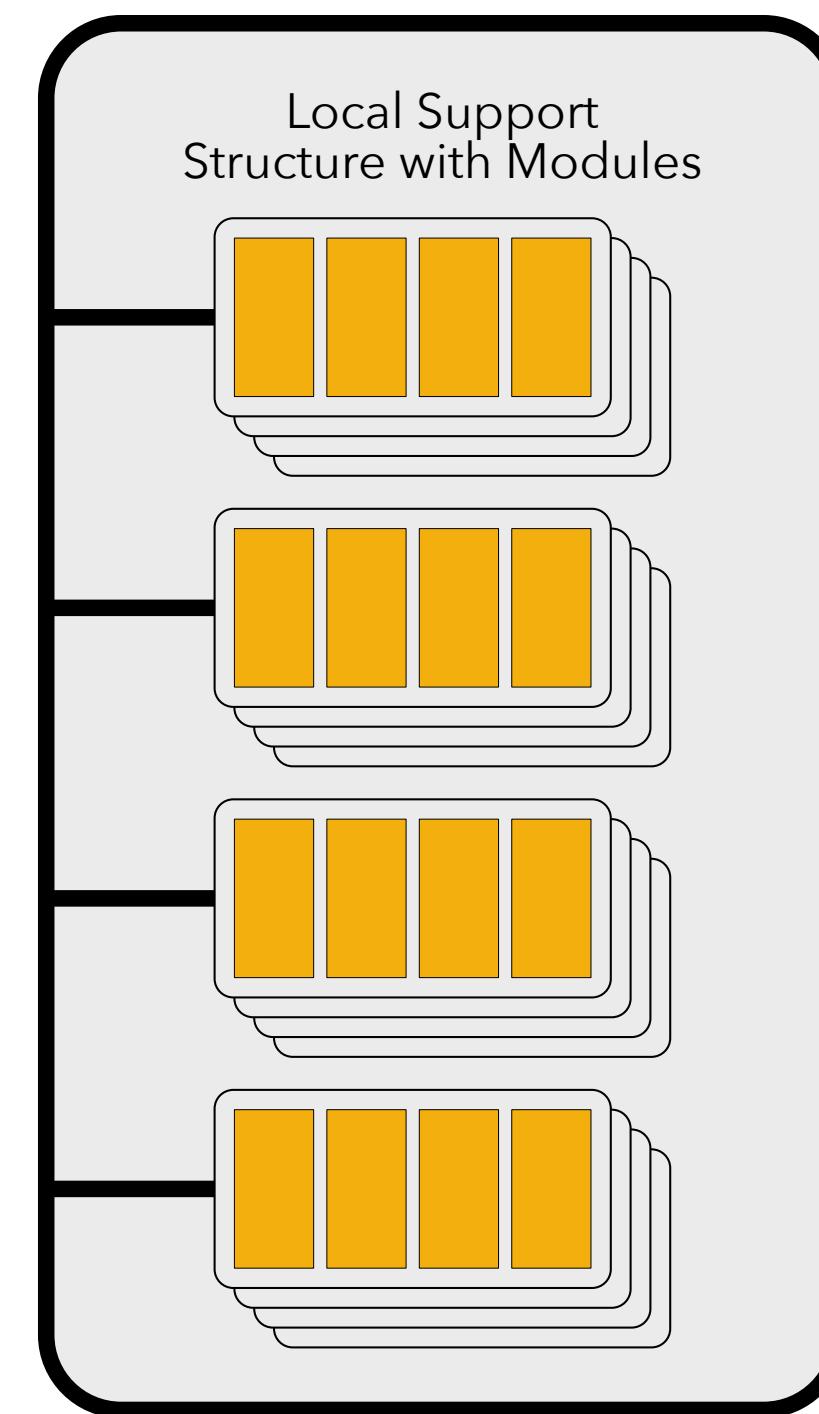


ATLAS & CMS End Caps - A Conceptual Comparison

$n > 2$



$n = 2$

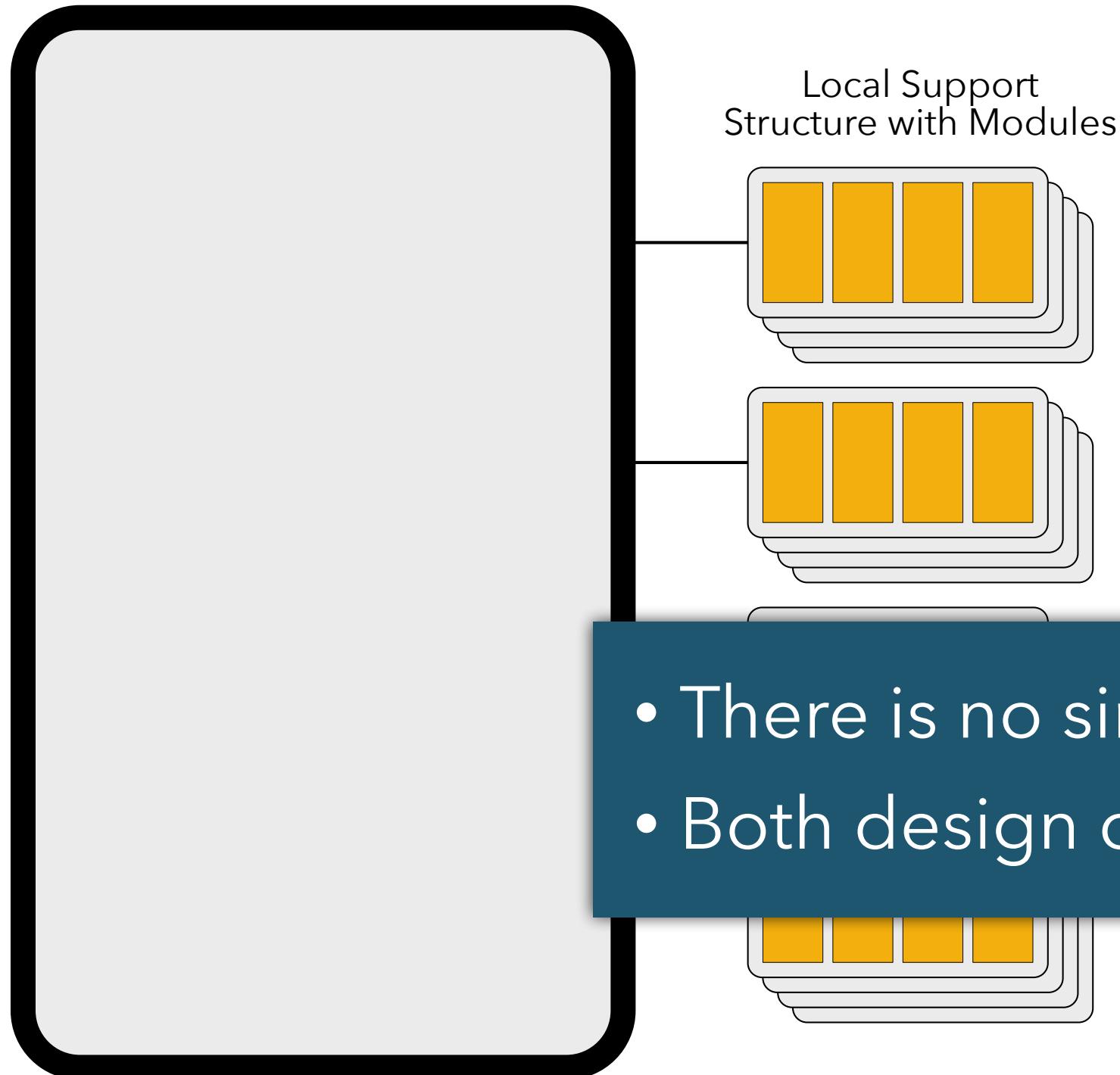


- Local supports with modules are inserted into mechanical super structure
- Super structure has to carry full load
- Integration is straight forward
- In ATLAS: $n = 16$

- Local supports are integral part of mechanical design
 - Load is shared among all mechanical components
 - Super structure can be lighter
- Mechanically stable object only exists after last integration & assembly step
- In CMS: $n = 2$

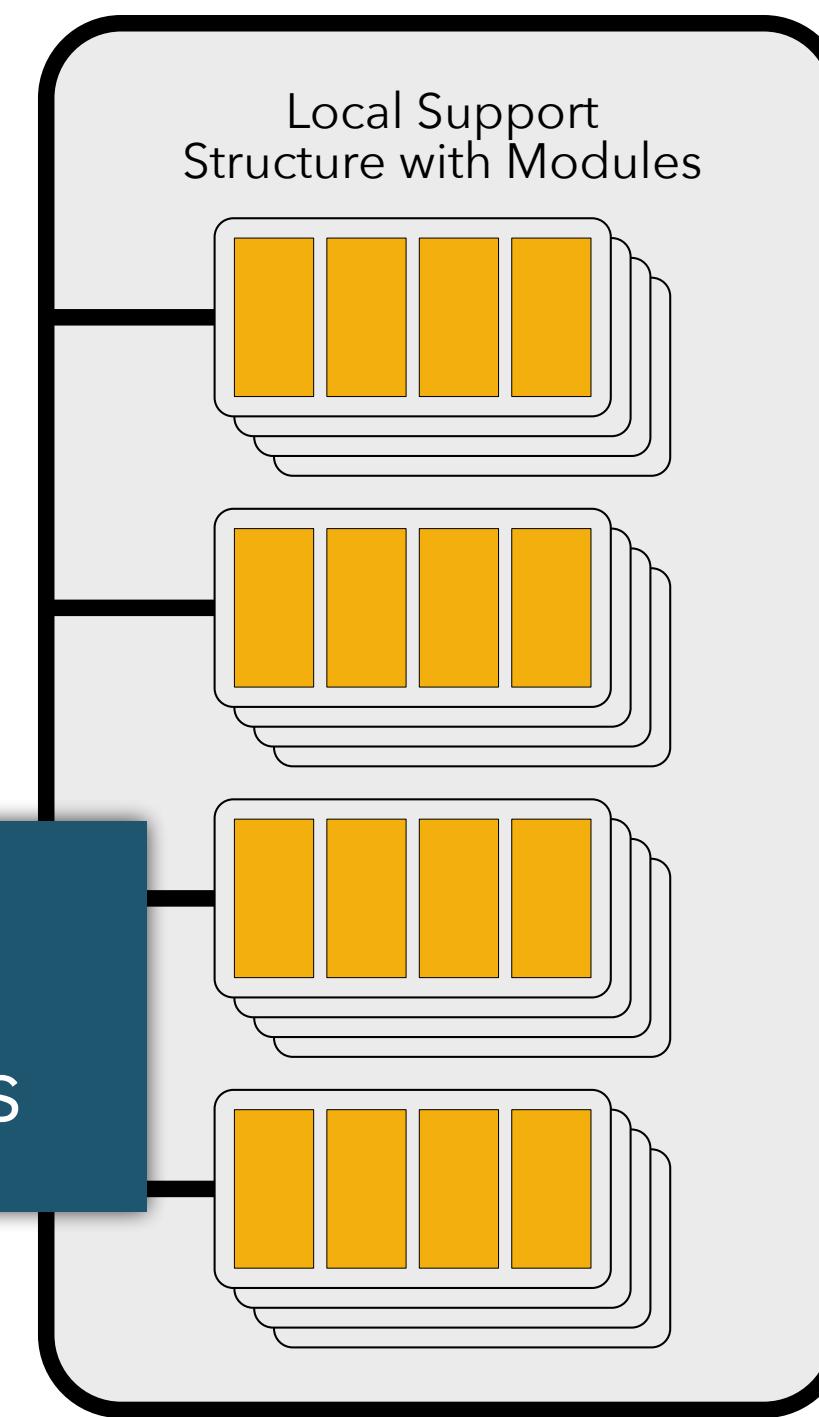
ATLAS & CMS End Caps - A Conceptual Comparison

$n > 2$



- There is no single best solution
- Both design choices have their pros and cons

$n = 2$

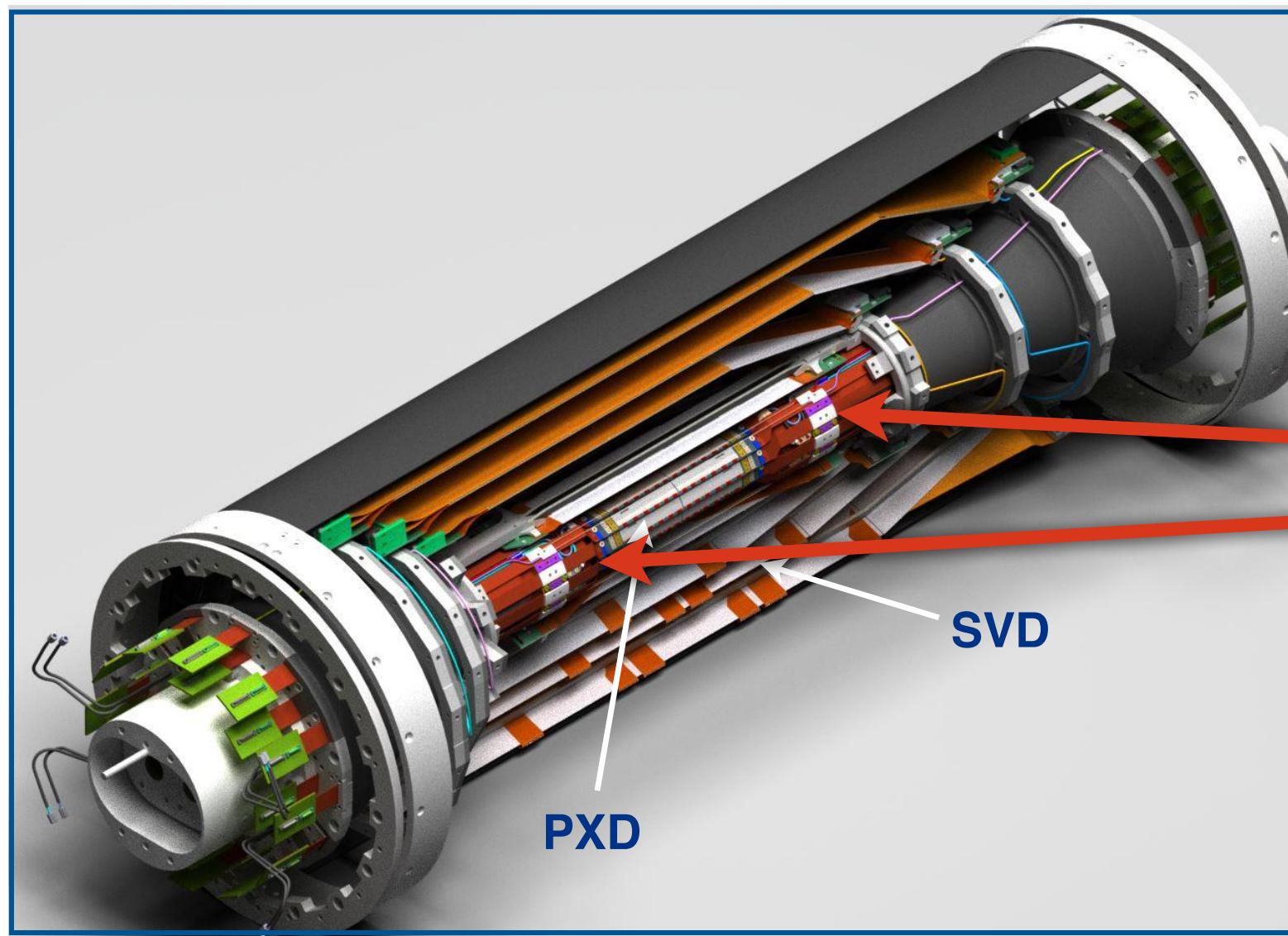


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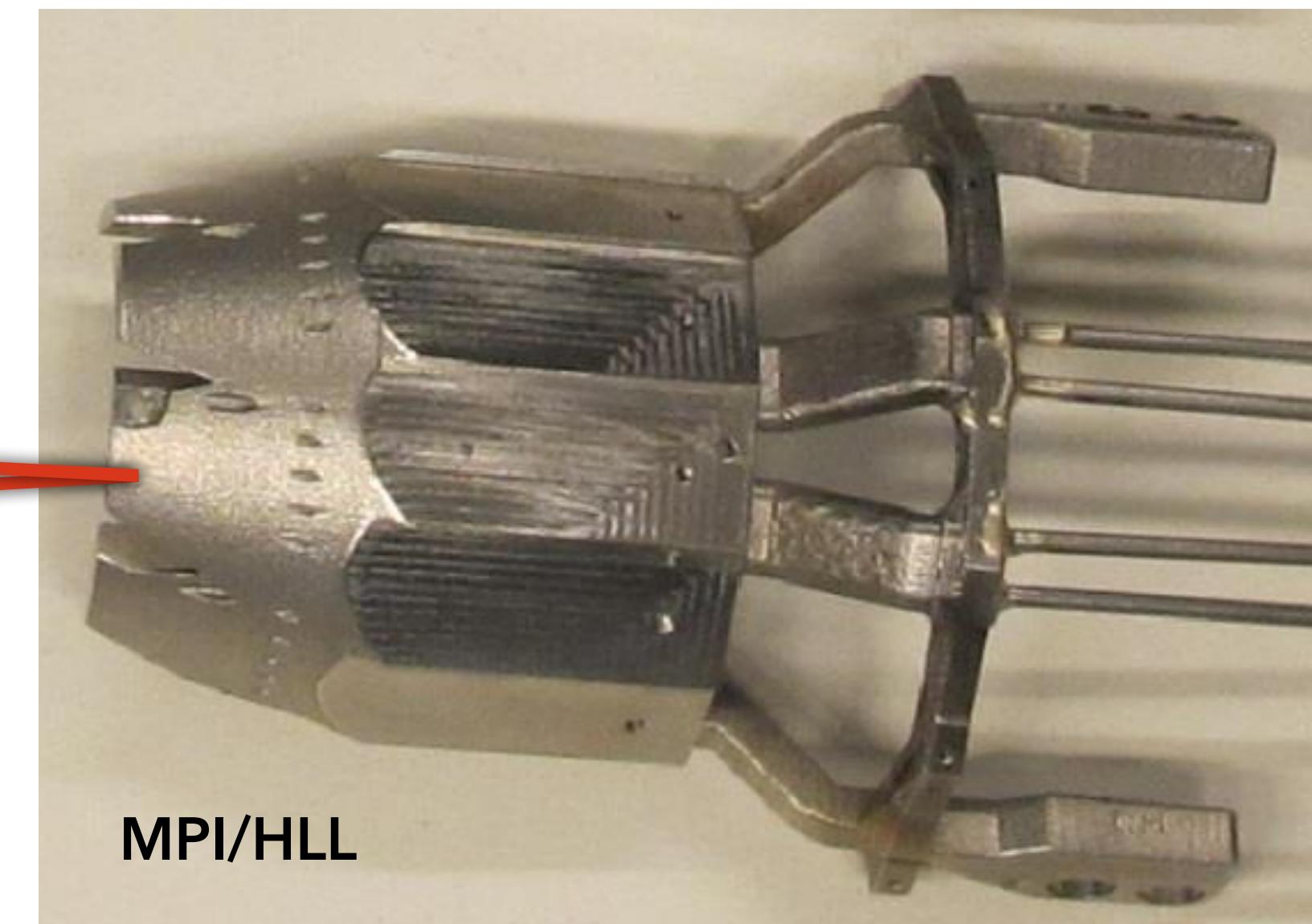
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Mechanics & Cooling Continued

Belle II PXD & SVD



PXD Support and Cooling Block (SCB)

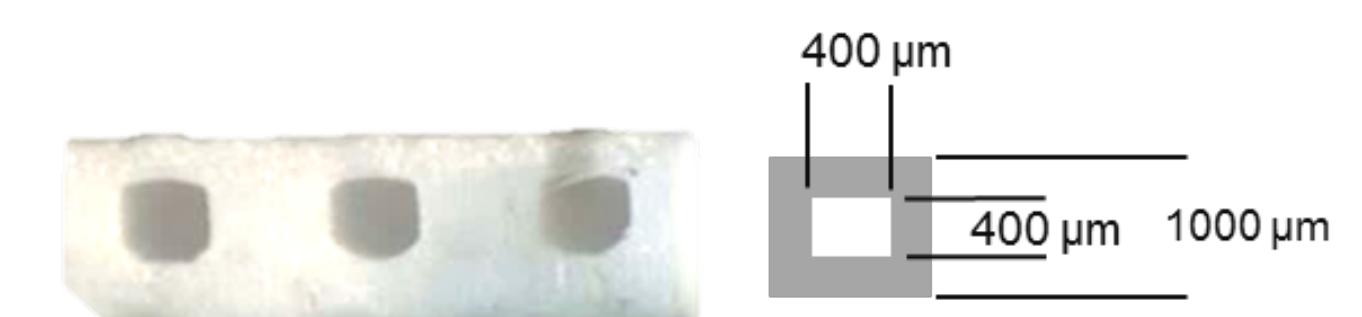


- Belle II PXD Support and Cooling Block (SCB) printed in stainless steel
 - integrated CO₂ and N₂ channels
 - outside acceptance
- potential of additive manufacturing has to be exploited also inside trackers



stainless steel printed on cooling pipe with
2.5 mm OD and 150 µm wall thickness

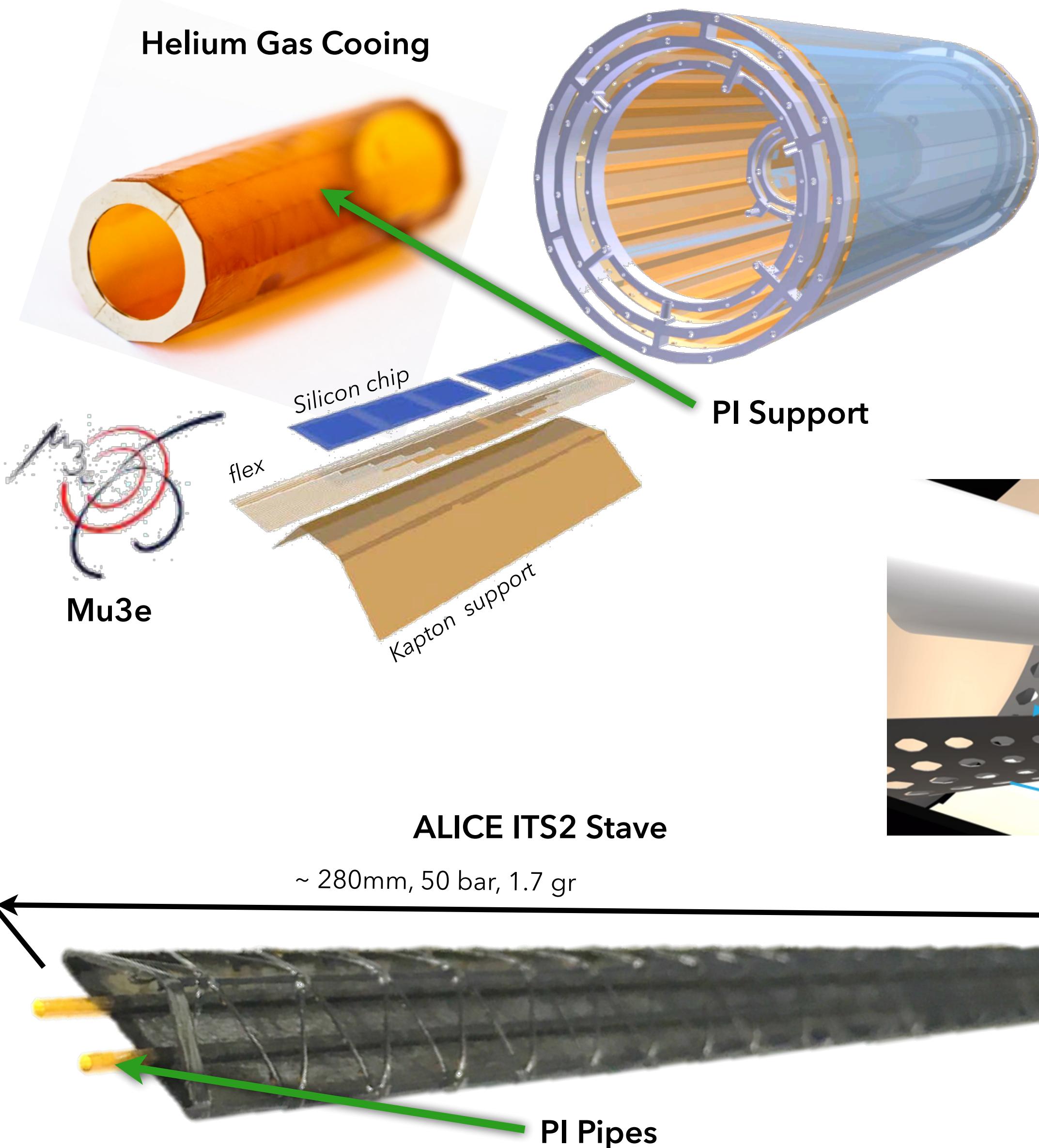
3D printed ceramic
→ Engineering for CTE compatibility



C. Gargiulo, A. Onnela (CERN)

Mechanics & Cooling Continued

Helium Gas Cooling

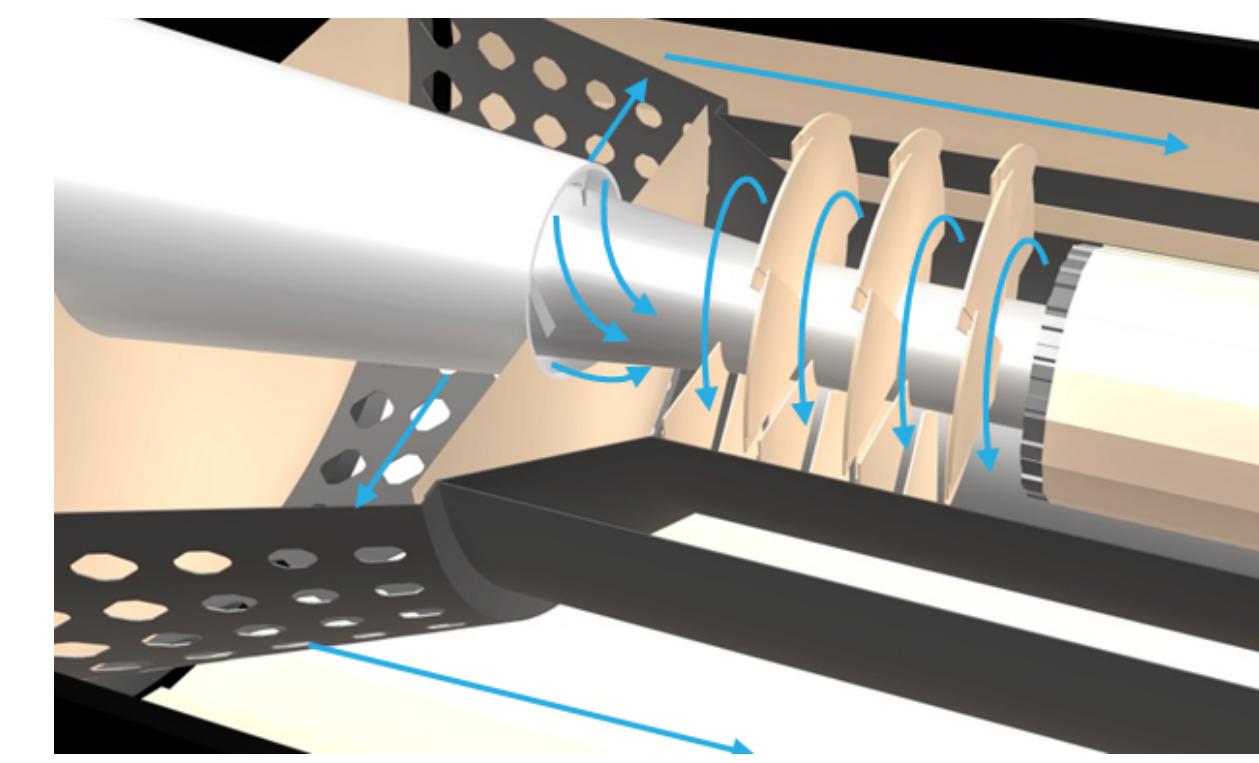
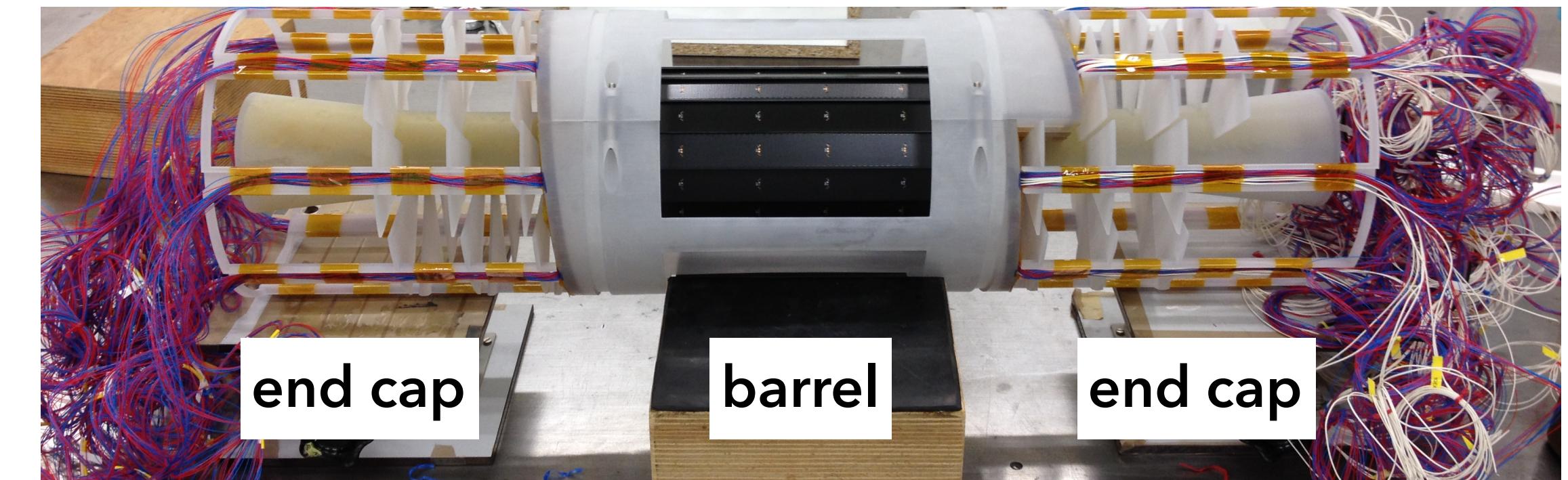


ALICE ITS2 Stave

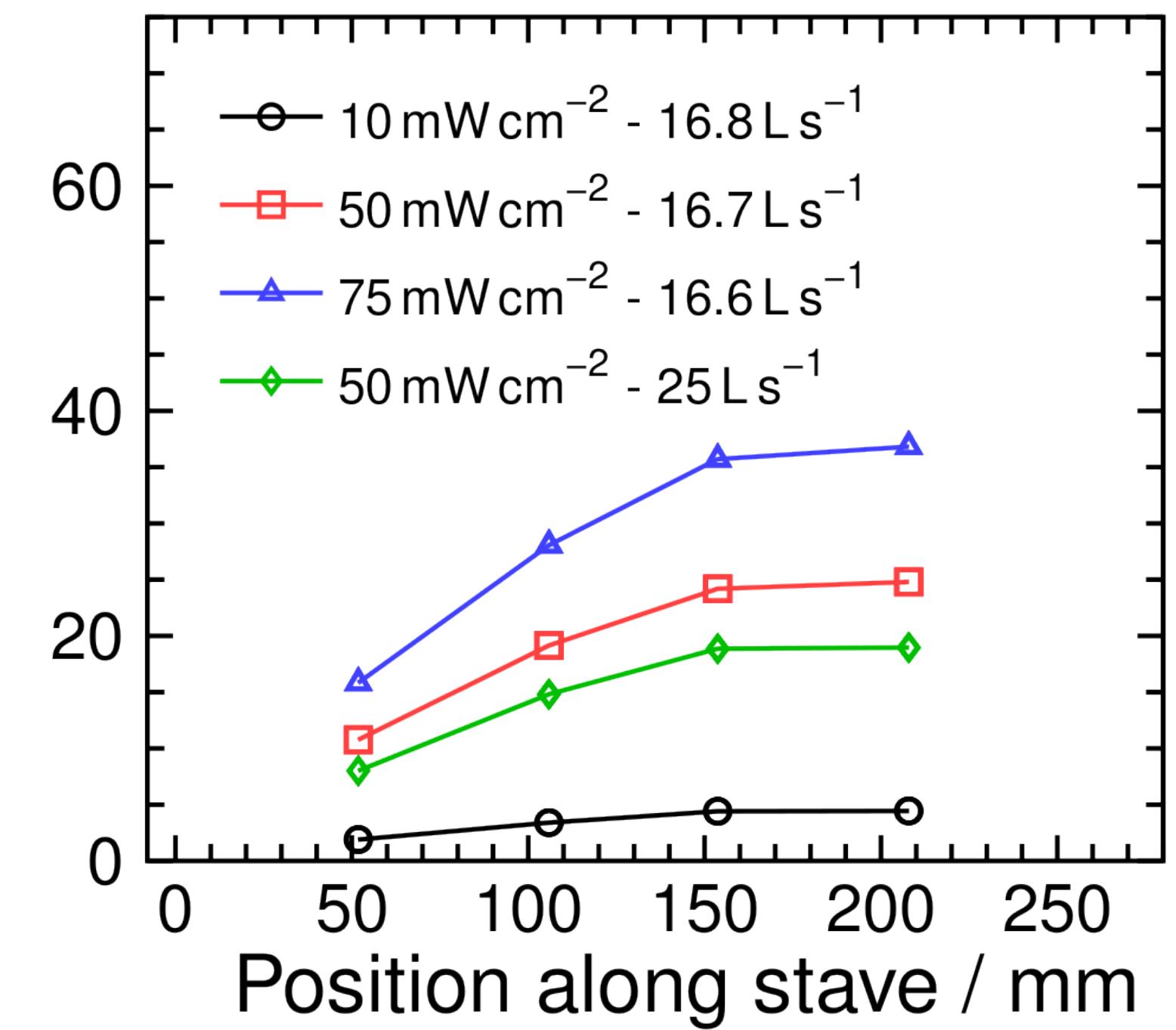
~ 280mm, 50 bar, 1.7 gr

PI Pipes

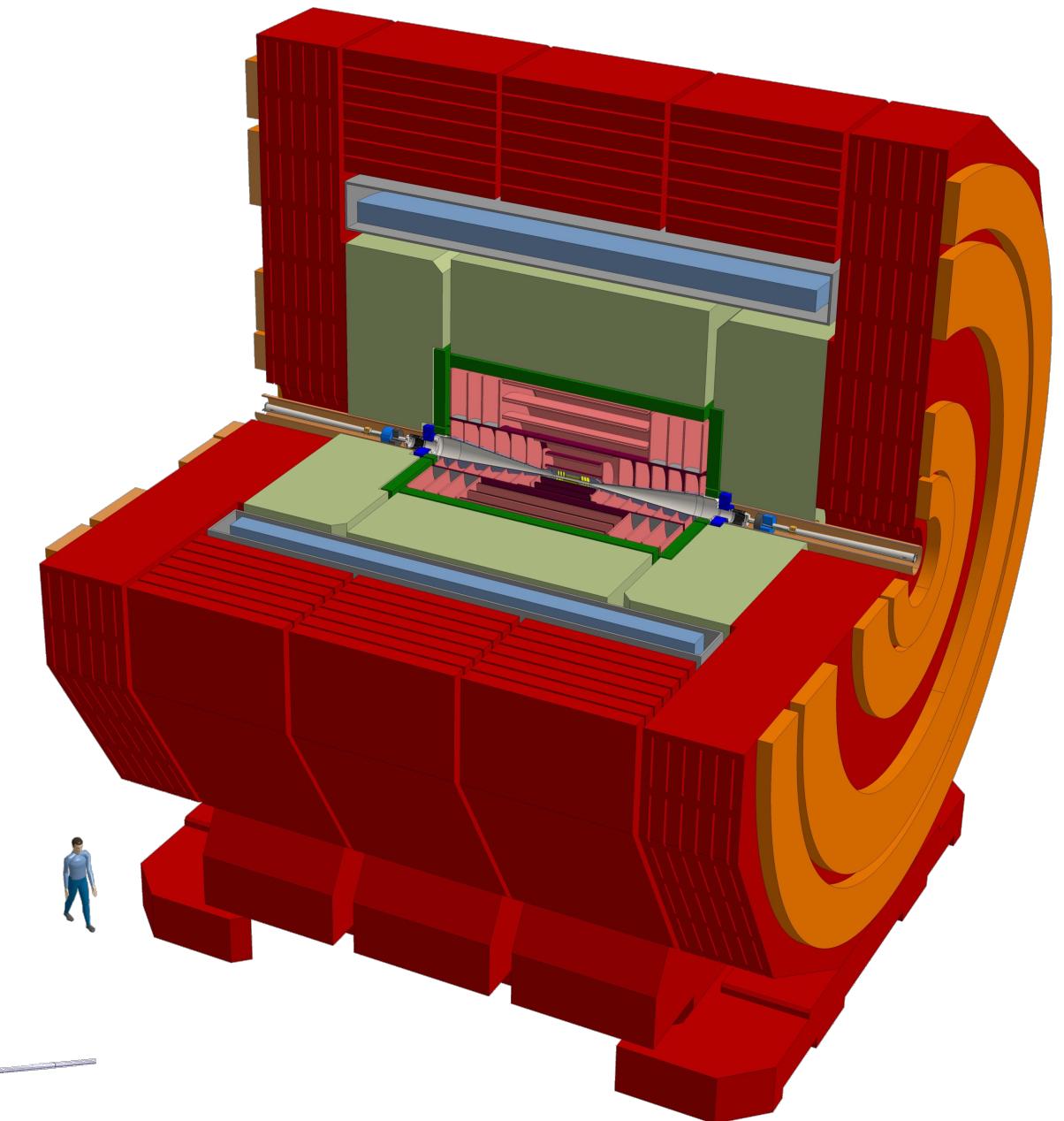
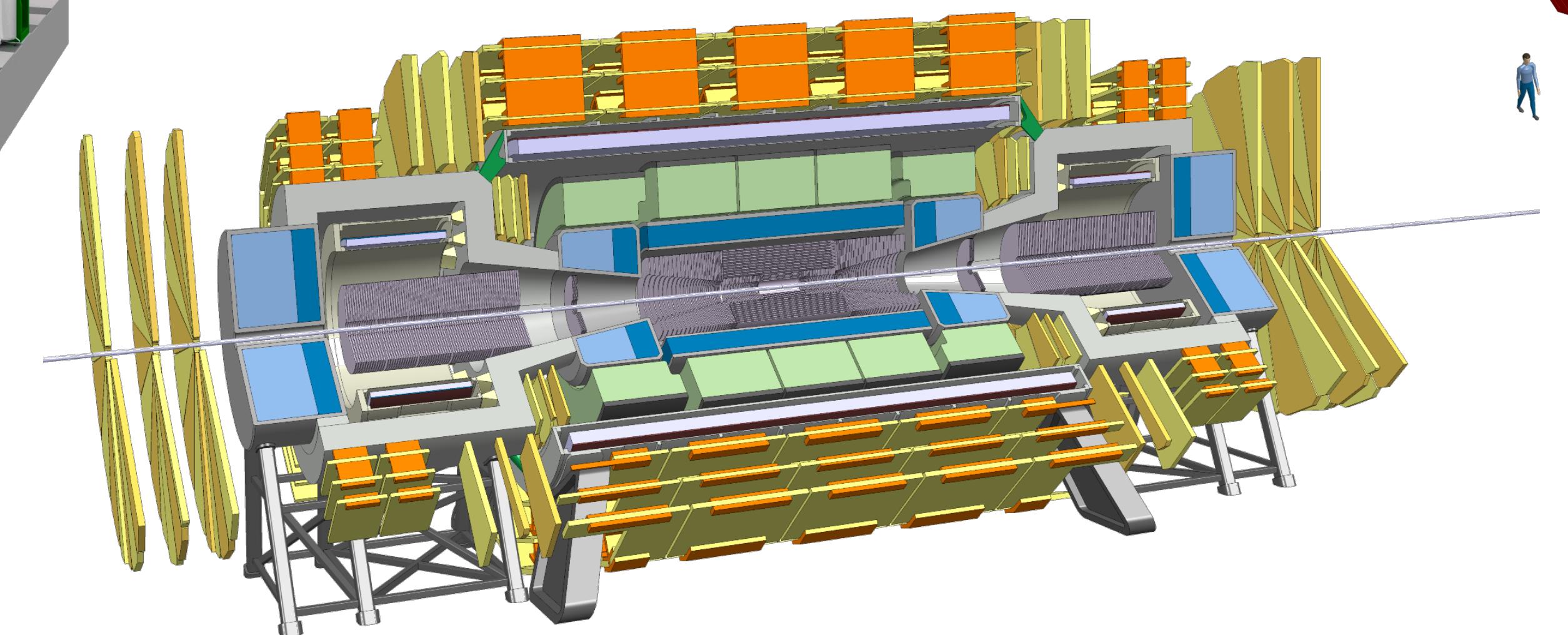
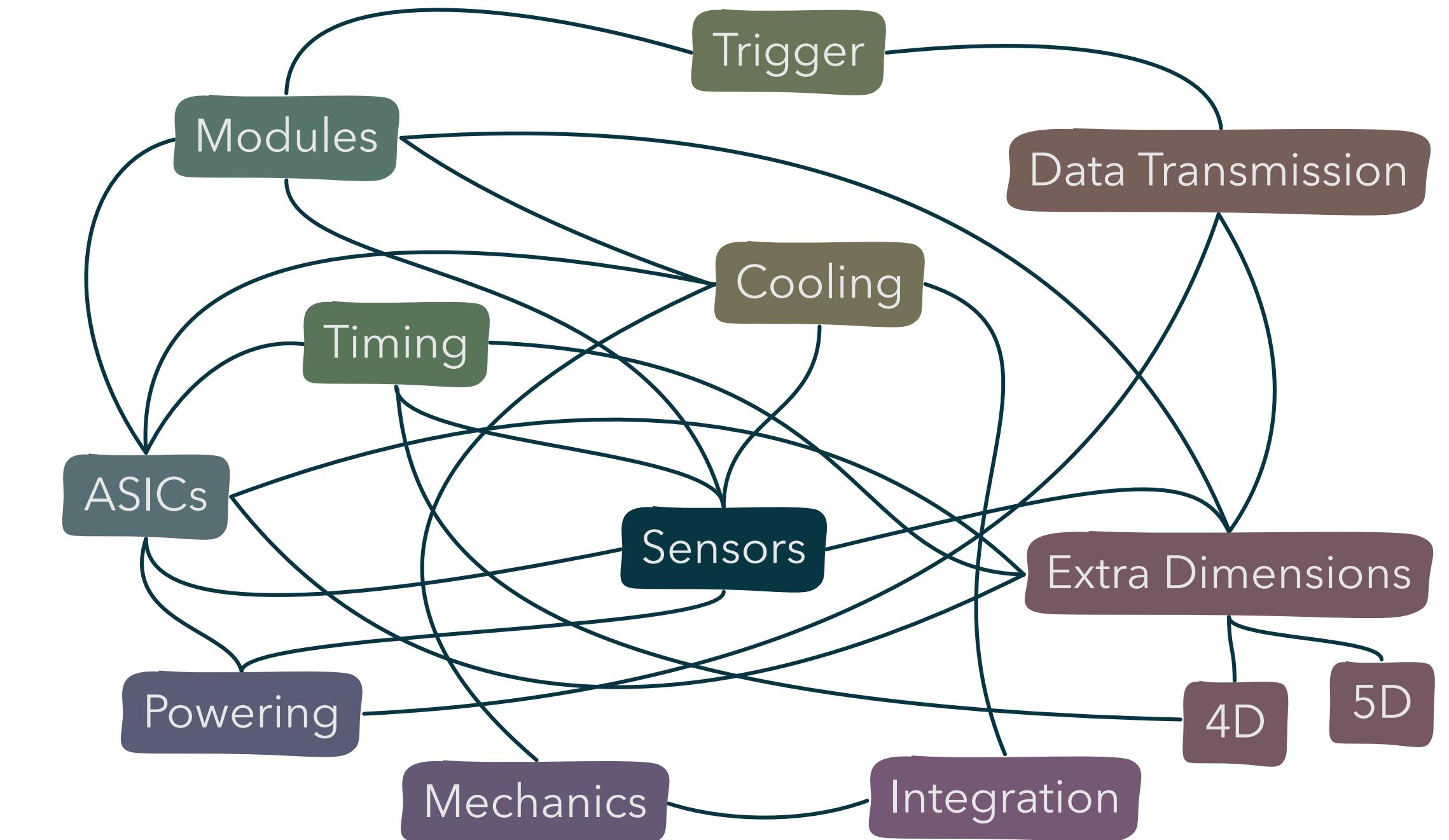
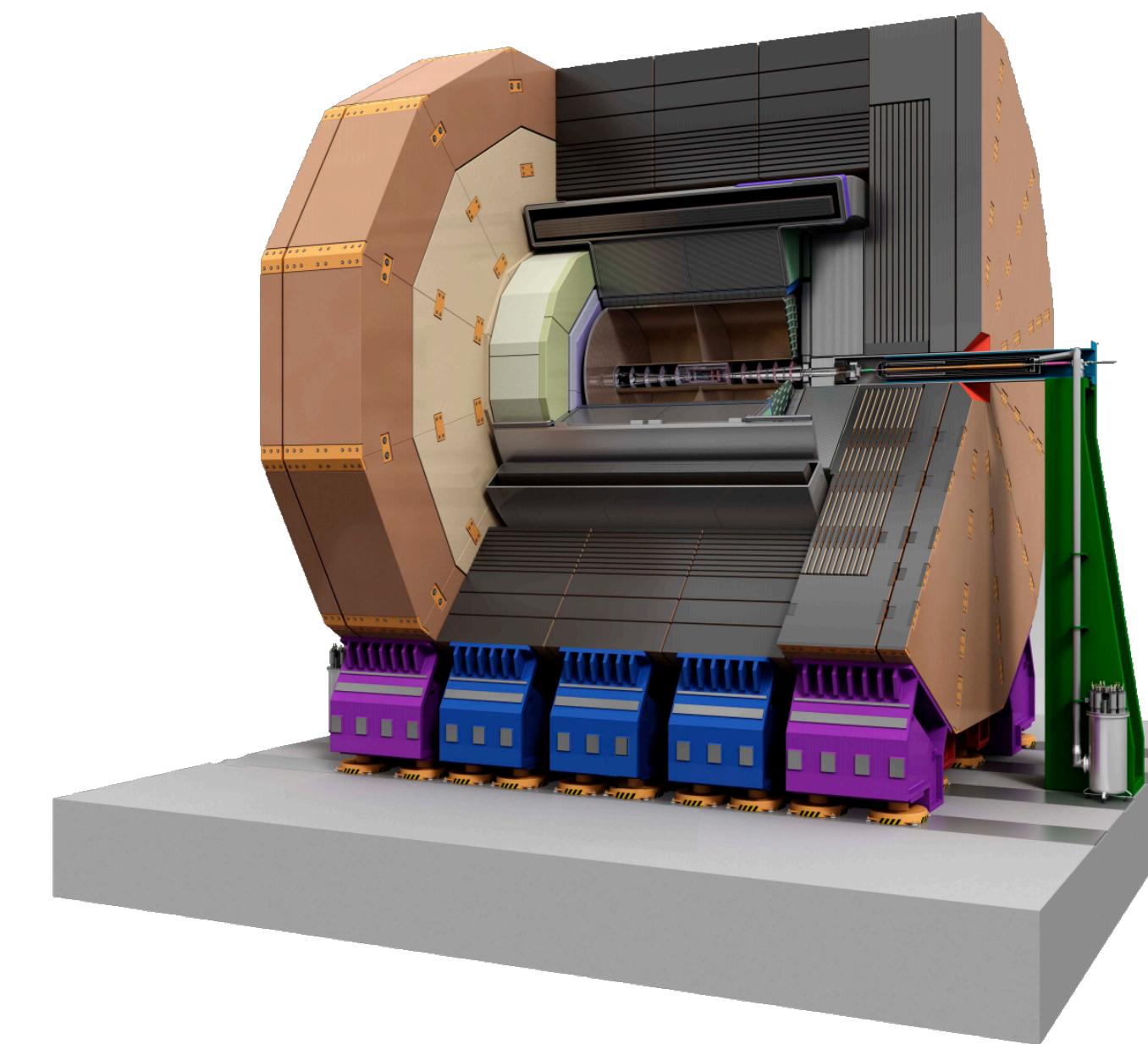
CLICdet Vertex Forced Air Cooling



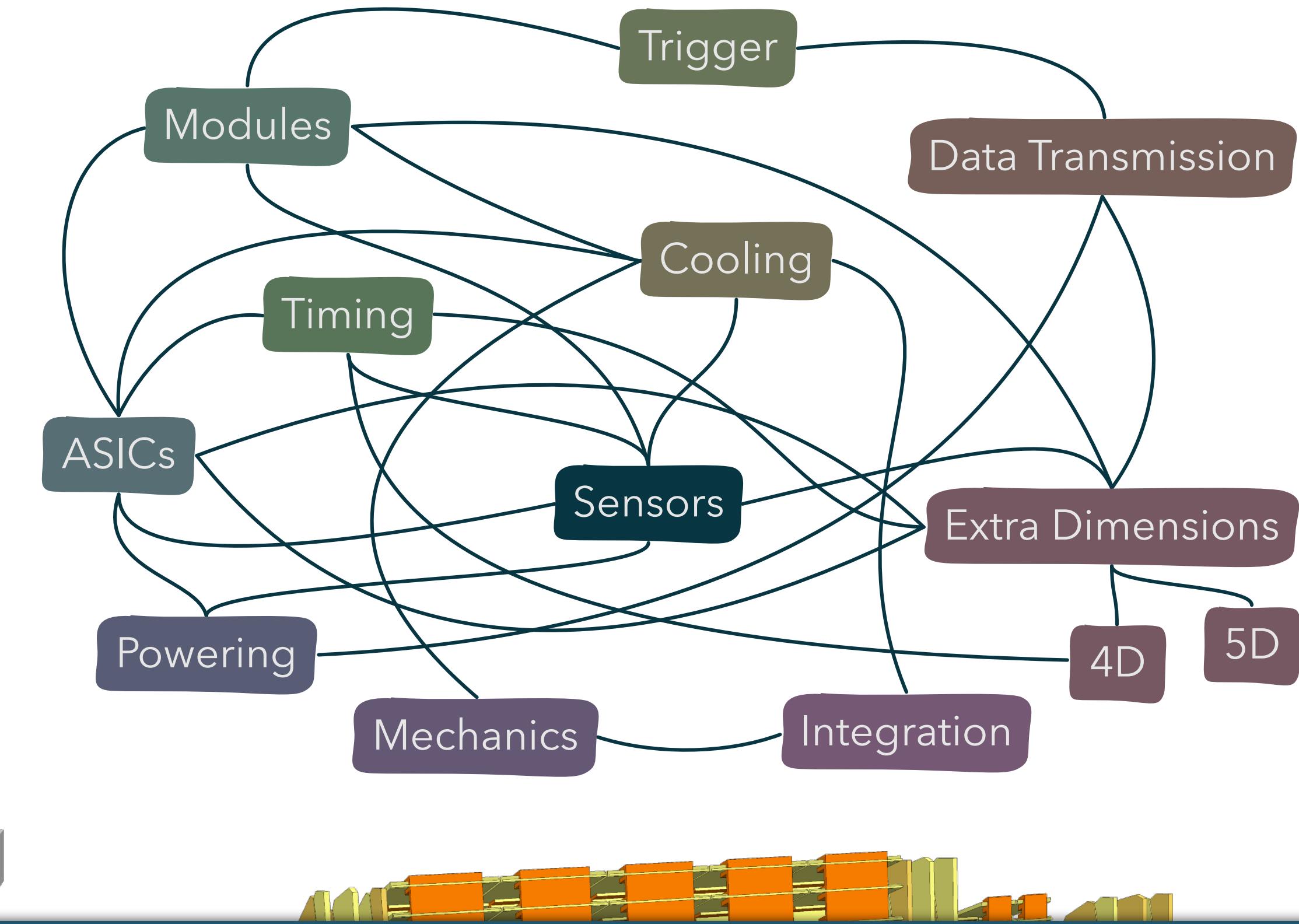
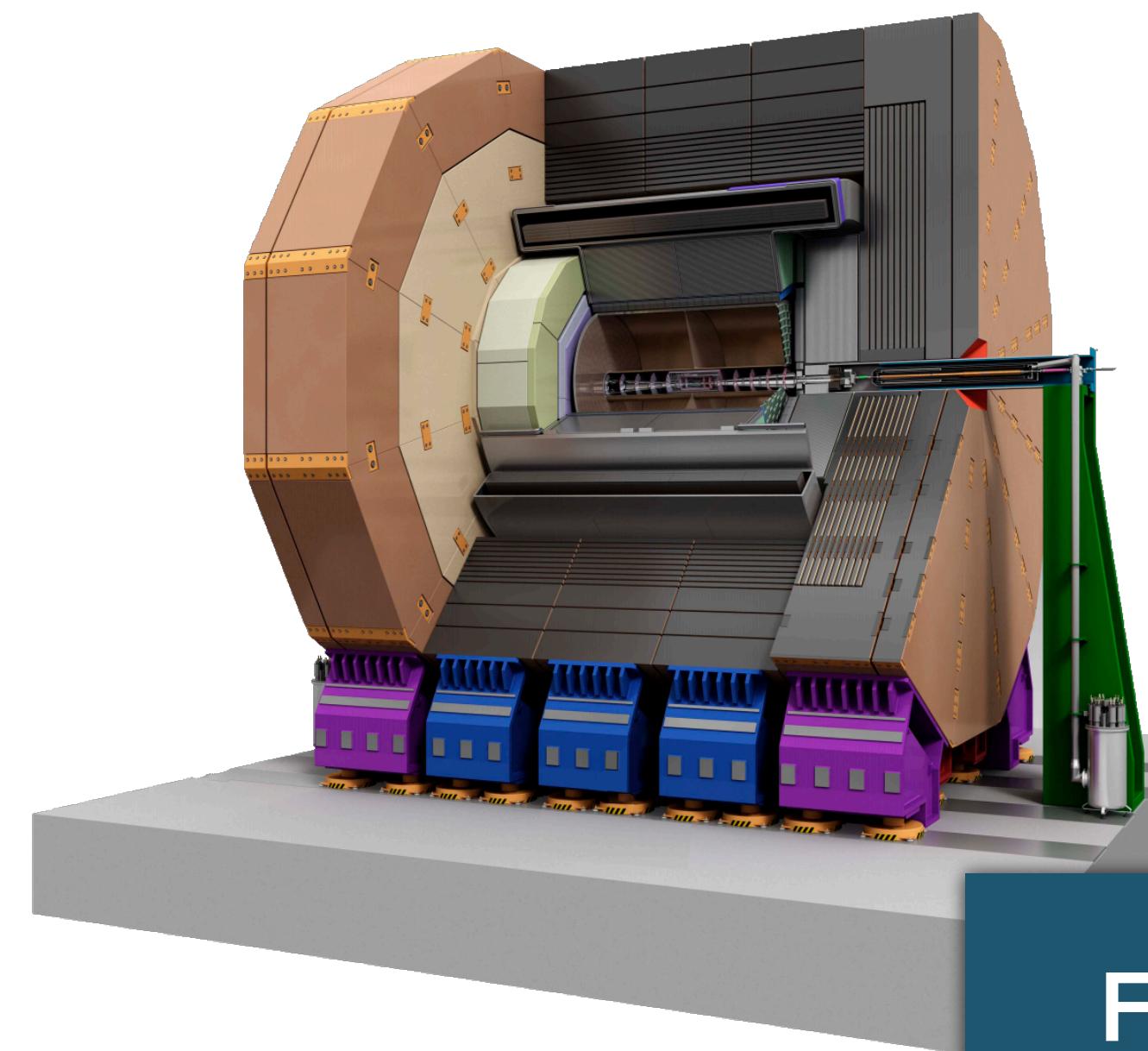
Avg. temp. increase / K



Summary



Summary



Forum on Tracking Detector Mechanics 2020
25-27 May 2020
INFN - LNF Frascati

