

Status of STCF Software

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On behalf of STCF software group

The 2021 Workshop on future Super c-tau factories

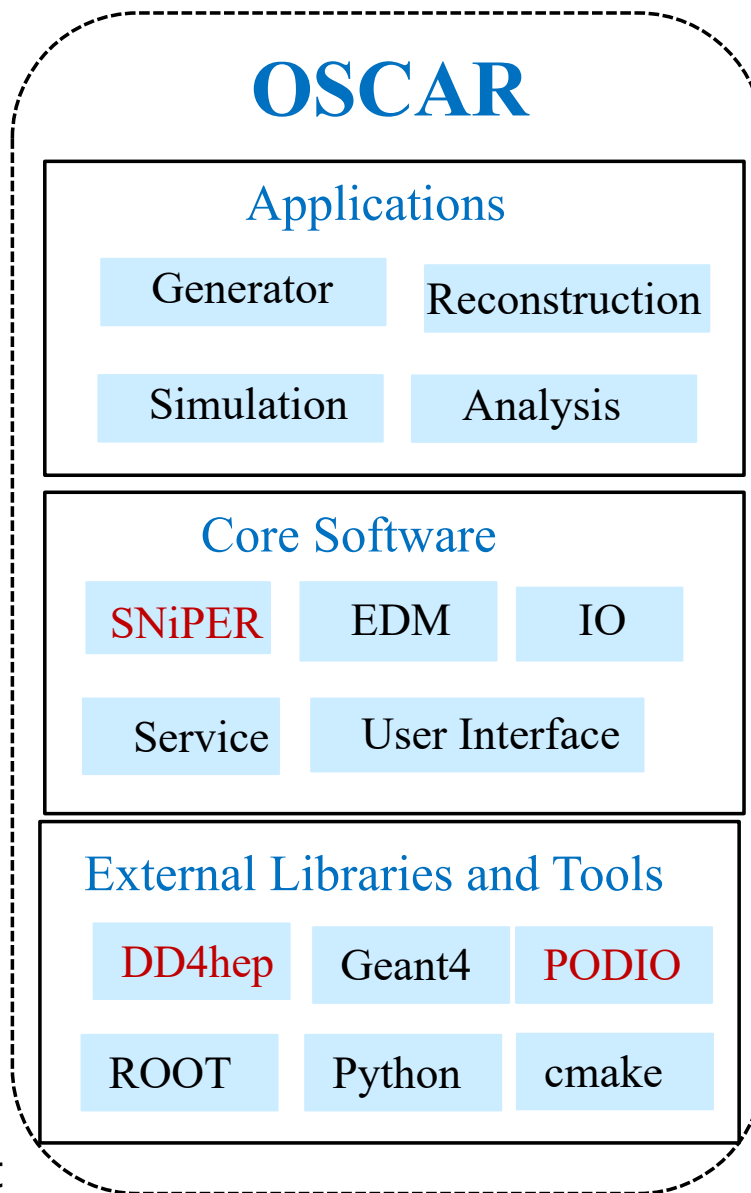
November 15-17, 2021 (online)

Outline

- ❖ Introduction
- ❖ Core software (EDM)
- ❖ Detector Geometry and Simulation
- ❖ Reconstruction Algorithms
- ❖ Validation System
- ❖ Visualization Tool
- ❖ Summary and Future Plan

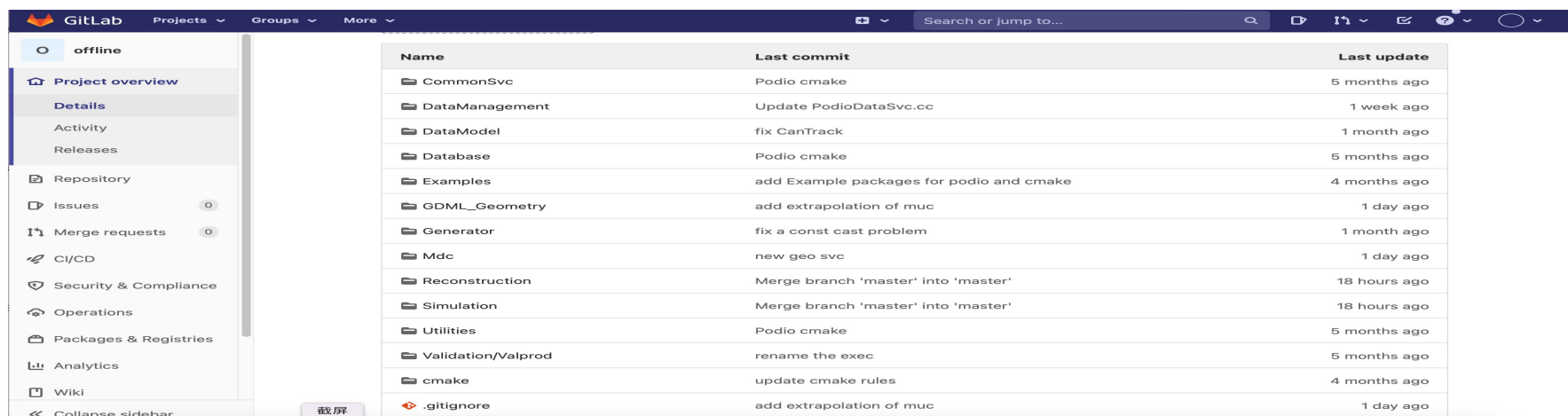
Introduction

- ❖ The **Offline Software of Super Tau-Charm Facility (OSCAR)** was developed based on SNiPER framework since Oct. 2018.
 - Core software
 - Applications
 - External libraries and tools
- ❖ **SNiPER**
 - a light-weight framework
 - support both collider and non-collider HEP Exp.
 - adopted by JUNO, LHAASO, nEXO
 - define interfaces to all software components and controls their execution.
- ❖ Partially based on **Key4hep**
 - PODIO: a generic event data model toolkit
 - DD4hep: a common geometry description toolkit



Development environment

- ❖ Supported Operating System: **SLC 7 and CentOS 7**
- ❖ Programming Language: **C++ 11, Python 2.7**
- ❖ Configuration Language : **Python**
- ❖ Software Management Tool : **CMake**
- ❖ Version Control Tool : **Gitlab**
 - The webpage: <http://202.141.163.203:8009/oscar>
 - 15 developers part-time working on development of OSCAR
 - The pull-request mechanism is used to synchronize all developers' work
- ❖ Users' Guide: <http://202.141.163.203:8009/oscar/documents>

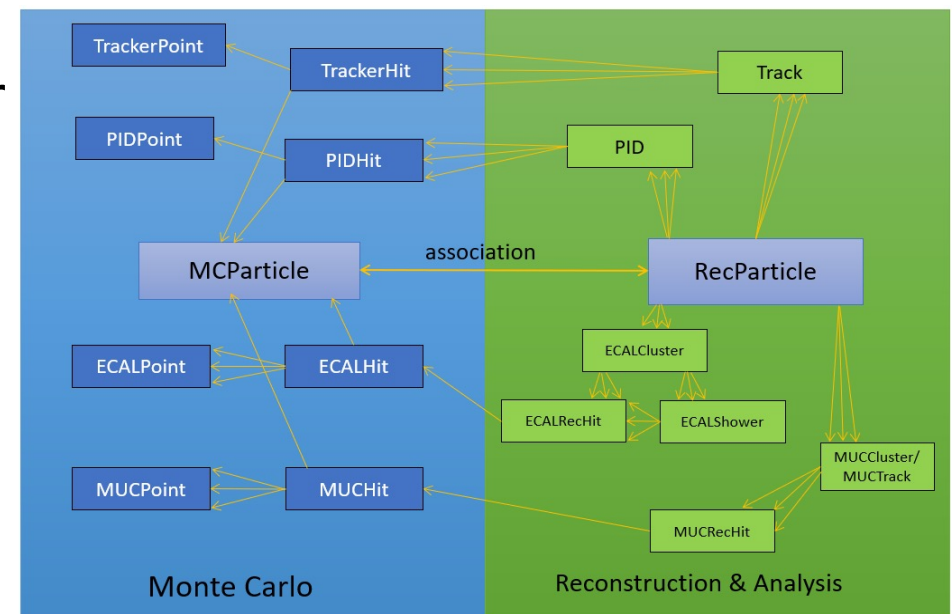


The screenshot shows the GitLab web interface. On the left is a sidebar with navigation links: offline, Project overview, Details, Activity, Releases, Repository, Issues (0), Merge requests (0), CI/CD, Security & Compliance, Operations, Packages & Registries, Analytics, Wiki, and Collapse sidebar. The main content area displays a table of files and their commit history.

Name	Last commit	Last update
CommonSvc	Podio cmake	5 months ago
DataManagement	Update PodioDataSvc.cc	1 week ago
DataModel	fix CanTrack	1 month ago
Database	Podio cmake	5 months ago
Examples	add Example packages for podio and cmake	4 months ago
GDML_Geometry	add extrapolation of muc	1 day ago
Generator	fix a const cast problem	1 month ago
Mdc	new geo svc	1 day ago
Reconstruction	Merge branch 'master' into 'master'	18 hours ago
Simulation	Merge branch 'master' into 'master'	18 hours ago
Utilities	Podio cmake	5 months ago
Validation/Valprod	rename the exec	5 months ago
cmake	update cmake rules	4 months ago
.gitignore	add extrapolation of muc	1 day ago

Event Data Model: updated from ROOT to PODIO

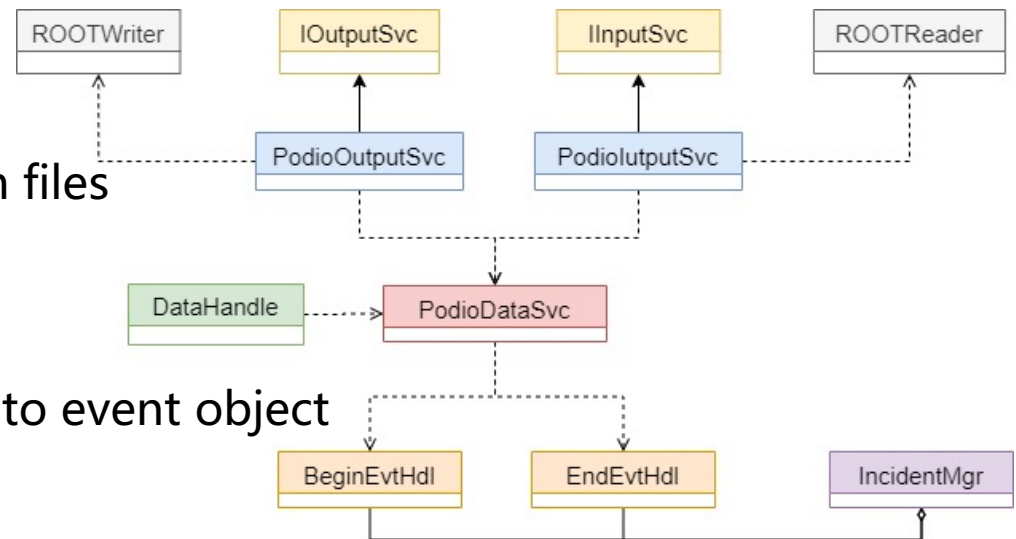
- ❖ PODIO: new Event Data Model toolkit developed by HEP community, and used by FCC, CEPC, SCT...
 - Simple memory model
 - support concurrency when design
 - excellent I/O : ROOT, SIO , HDF5
- ❖ With PODIO, common core classes is described in YAML file and C++ code is automatically generated
- ❖ Re-designed EDM with PODIO for simulation and reconstruction
 - EDM for each sub-detectors is implemented separately with no inheritance relationship
 - Build up one to one/many relations between different POD objects



Event Data Management System

❖ Developed a new EDM system to integrate PODIO within OSCAR

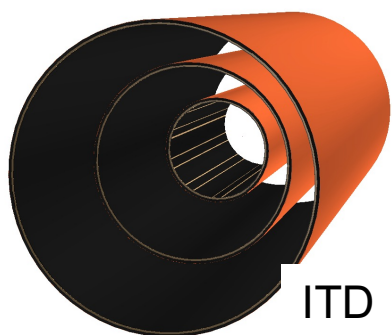
- PodioDataSvc
 - memory management
- PodioInputSvc
 - read the PODIO objects from files
- PodioOutputSvc
 - write PODIO objects to files
- Two datahandles provide access to event object
 - getRWColl(...)
 - getROColl(...)



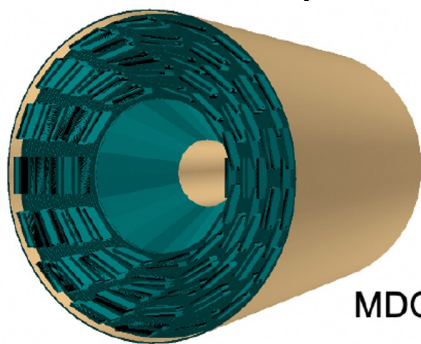
```
ITDHitCollection*      itdhits = getROColl(ITDHitCollection, "ITDHitColl");
ECALHitCollection*     ecalhits = getRWColl(ECALHitCollection, "ECALHitColl");
ECALPointCollection*   ecalpoints = getRWColl(ECALPointCollection, "ECALPointColl");
```

Detector Geometry Description

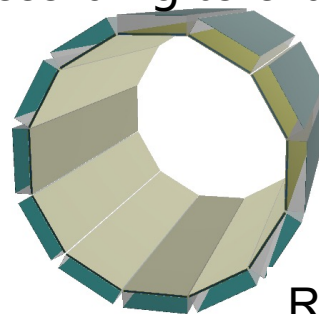
- ❖ The Full STCF Detector is described with DD4hep
 - Use a single source for detector simulation, reconstruction and visualization
 - Each sub-detector is implemented with a single compact file
 - The version number is used for different design options
 - Optimizing the detector geometry according to changes of the detector design



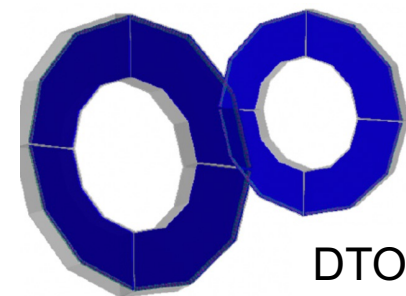
ITD



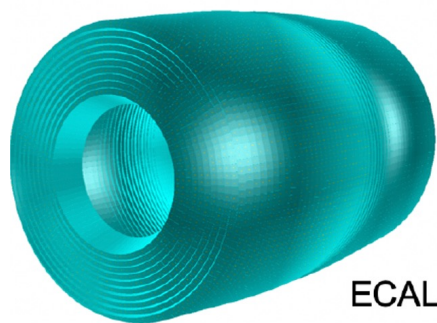
MDC



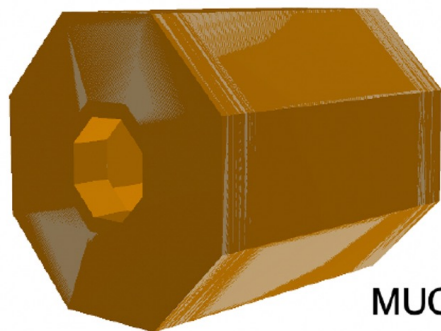
RICH



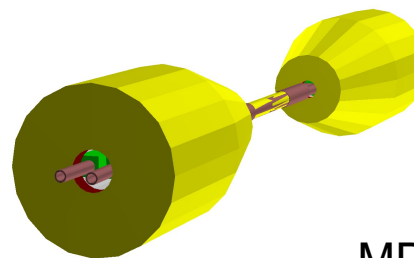
DTOF



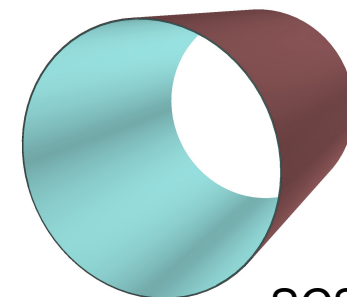
ECAL



MUC



MDI

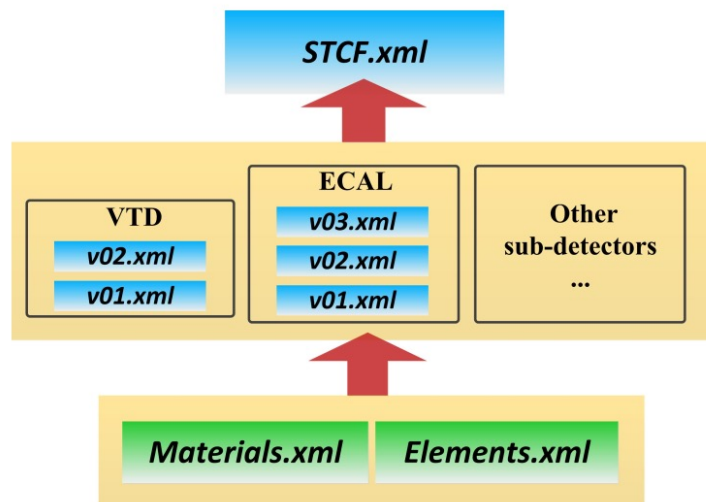


SCS

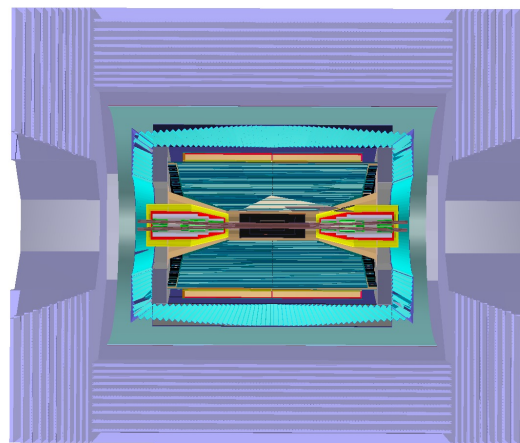
Detector Geometry Management

- ❖ Developed the detector geometry management system (GMS)*
 - The full detector can be easily build up with different sub-detector design options
 - Support single sub-detector simulation and the full detector simulation

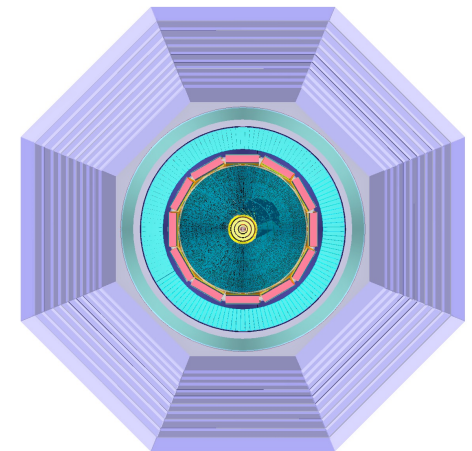
**More details in
next talk by He**



Structure of the geometry parameters repository



cross view in the r-z plane



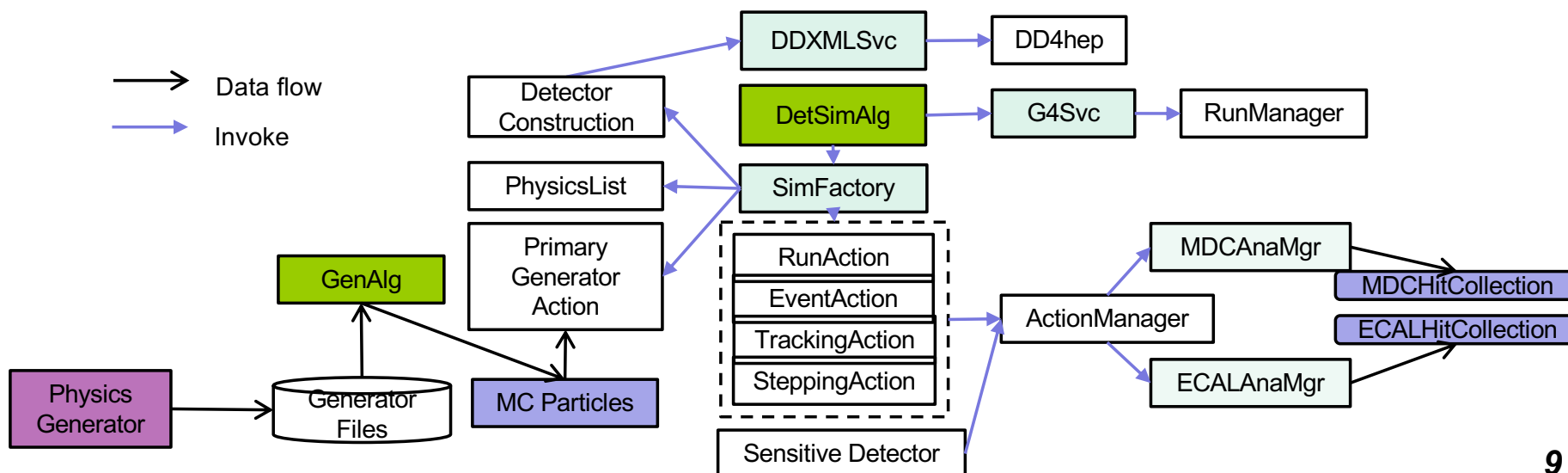
cross view in the x-y plane

* “Detector geometry management system designed for Super Tau Charm Facility offline software”, published on JINST 2021_JINST_16_T04004

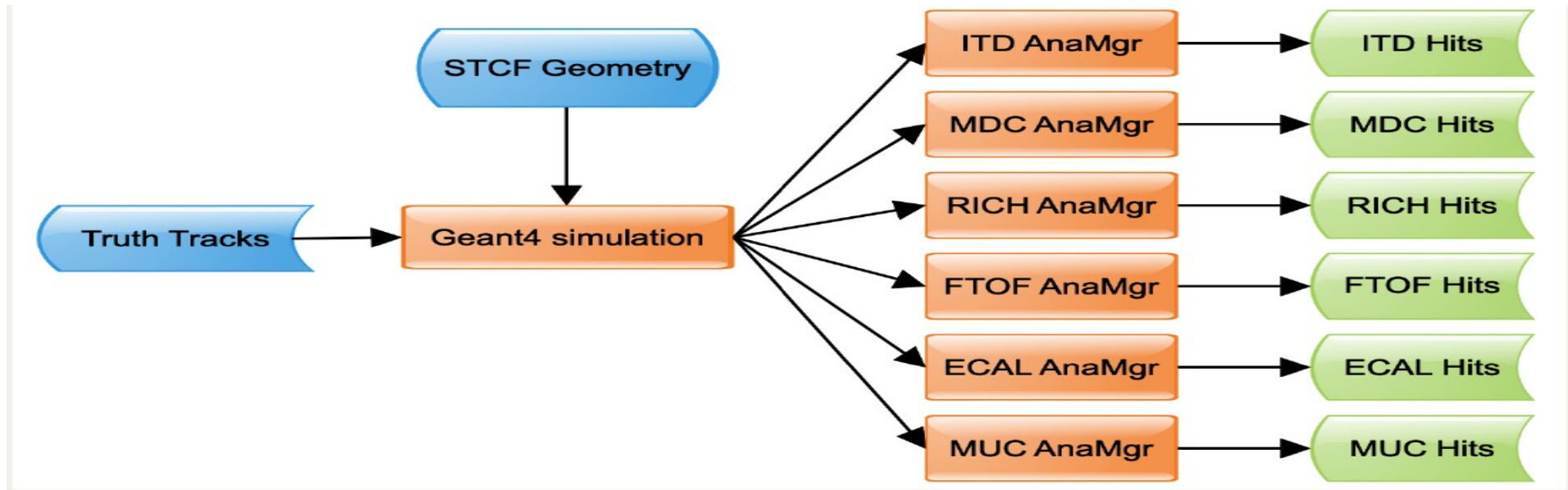
Detector Simulation

❖ The whole detector simulation chain is completed

- Developed a unified generator interface to configure different physics generators
 - Babayaga, Phokhara, KKMC, EvtGen, DIAG 36, etc.
- developed a new service (DDXMLSvc)
 - Deliver detector geometry from DD4hep to both Geant4 and recon. algorithms
 - Provide the user interface to configure Sensitive Detector
- One analysis manager is mandatory for each sub-detector to retrieve Geant4 simulation information and save them into the PODIO objects



Single Sub-detector or Full Detector Simulation



❖ Only record simulation information from ECAL

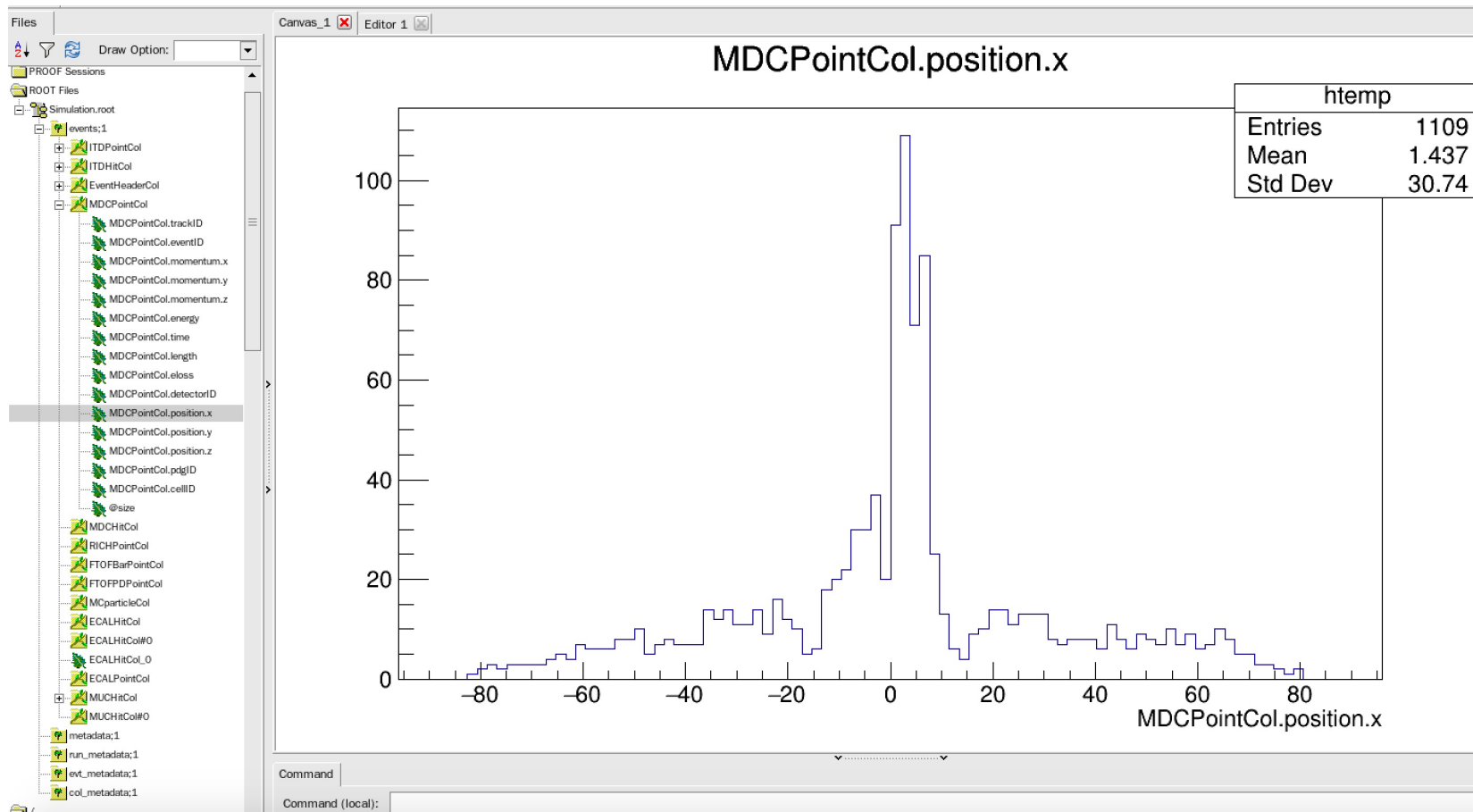
```
factory = task.createSvc("FullSimFactory/FullFactory")  
factory.property("AnaMgrList").set(["GeneratorMgr", "ECALAnaMgr"])
```

❖ Record simulation information from Full detector

```
factory = task.createSvc("FullSimFactory/FullFactory")  
factory.property("AnaMgrList").set(["GeneratorMgr", "ITDAnaMgr", "MDCAnaMgr", "FTOFAnaMgr", "RICHAnaMgr", "ECALAnaMgr", "MUCAnaMgr"])
```

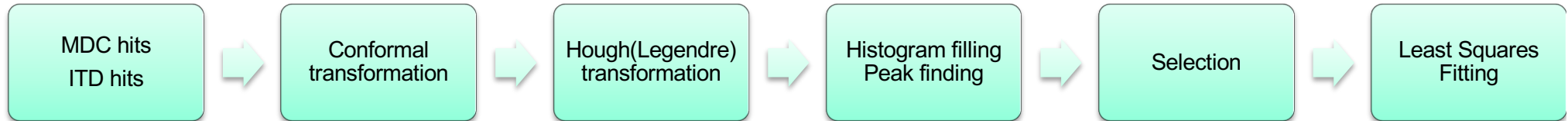
Finished Transition from ROOT EDM to PODIO

- ❖ All simulation algorithms have been updated
- ❖ New simulated results are consistent with old ones
- ❖ Found one bug of PODIO and asked developers to fix it

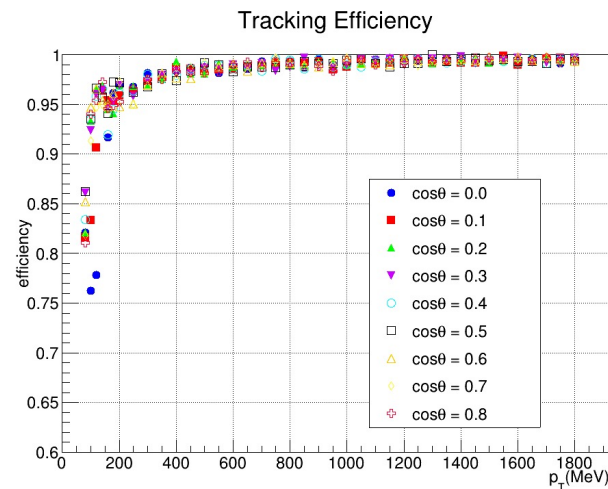


Tracker Reconstruction

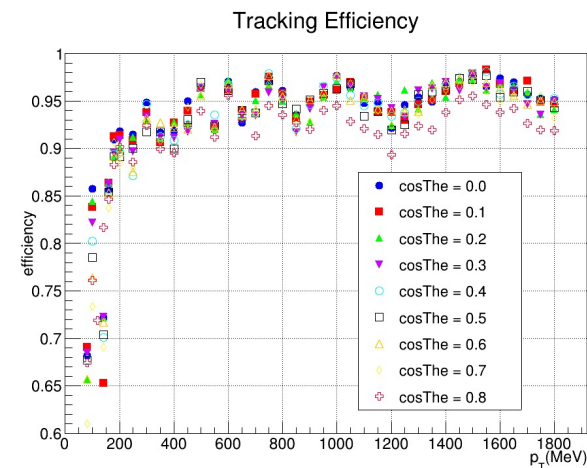
- ❖ Developed Track finding algorithm based on Hough transformation



- ❖ Track fitting algorithm is performed by the Deterministic Annealing Filter (DAF) method, an extension of Kalman Filter , in GENFIT2
- ❖ Performance study with/without noise



No noise

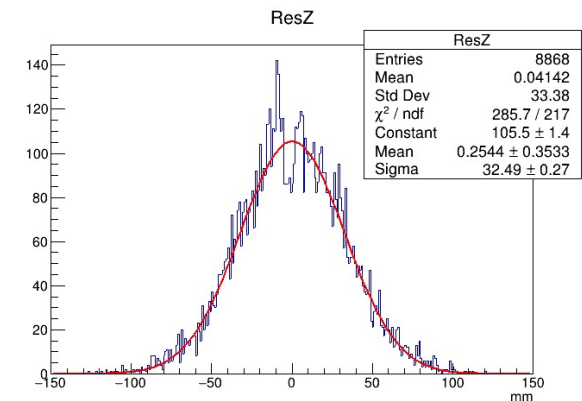
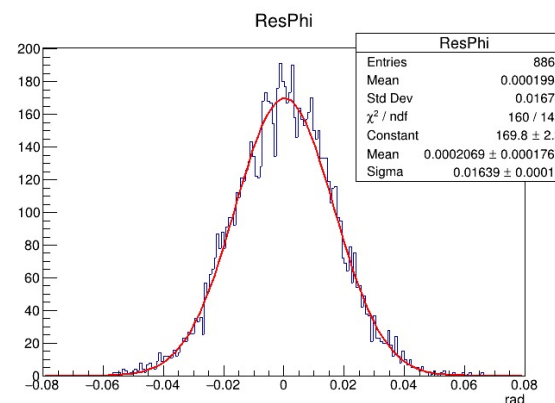
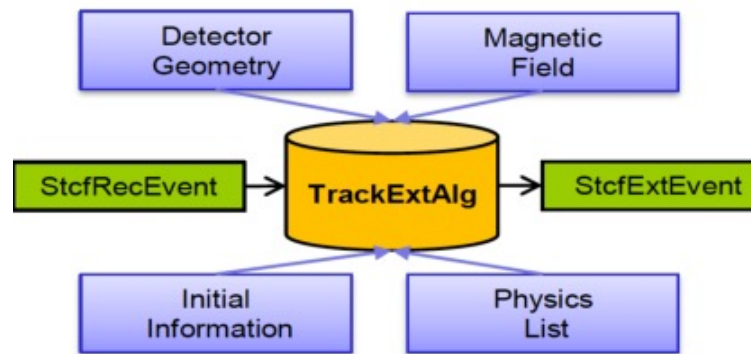


Approximately 800 MDC noise hits

Tracking efficiency for single π^+

Track Extrapolation

- ❖ A Geant4-based track extrapolation algorithm is imported from BESIII
 - Extrapolating the MDC fitting track into outer sub-detectors
 - Support 5 hypotheses: e, mu, pi, K, p
 - Has been used by other sub-detectors



Pt=1.0GeV mu-, Theta=90 extrapolation position vs truth position

Extrapolate to **MUC**

RICH Reconstruction

❖ A likelihood-based PID method is studied

- The photon collected in each anode pad follows the Poisson distribution:

$$pdf_{i,h} = \text{Poisson}(N_i + 10^{-3}, avg_{i,h} + 10^{-3}),$$

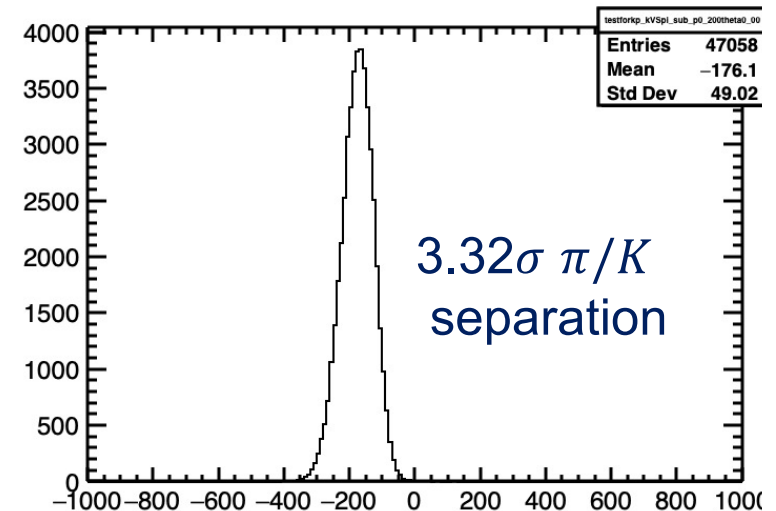
More details in Qian's talk

- The Likelihood of h hypothesis:

$$\ln \mathcal{L}_h = \sum_i^{npads} \ln pdf_{i,h} \quad (h: \pi, K, P)$$

- The Difference in log-likelihood (DLL) between two hypothesis

$$DLL = \sum_i^{npads} \ln \frac{pdf_{i,\pi}}{pdf_{i,K}}$$



❖ The implementation within OSCAR is on-going now

DTOF Reconstruction

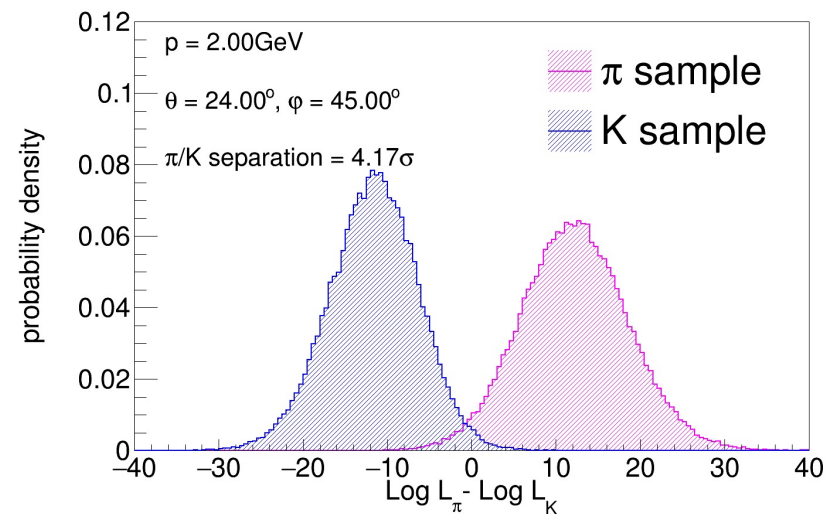
❖ A likelihood-based PID method is studied for DTOF

- use time information of the photo electrons.

$$\mathcal{L}_h = p_h(N_{p.e.}) \prod_{i=0}^{N_{p.e.}} f_h(TOF_i) \quad f_h(t) = \begin{cases} gaus + 0.05, & \text{signal and bkg} \\ 0.05, & \text{bkg} \end{cases}$$
$$\Delta\ell = \text{Log } \mathcal{L}_\pi - \text{Log } \mathcal{L}_K \quad p_h(N_{p.e.}) = \text{crystalball}$$

- separation power reaches 4.17σ
- The migration of the method to OSCAR is on-going now

More details in Ming's talk

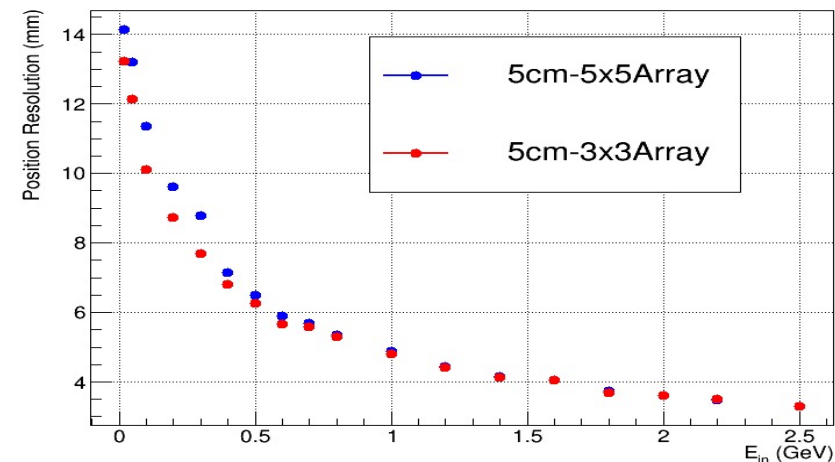
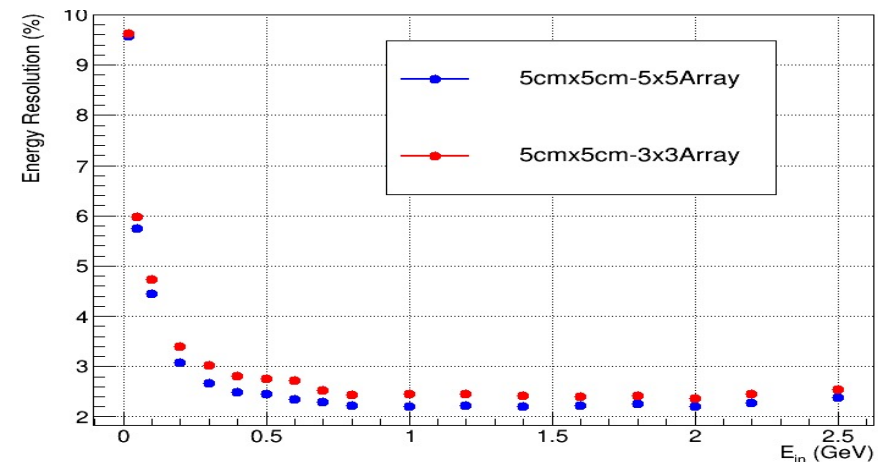
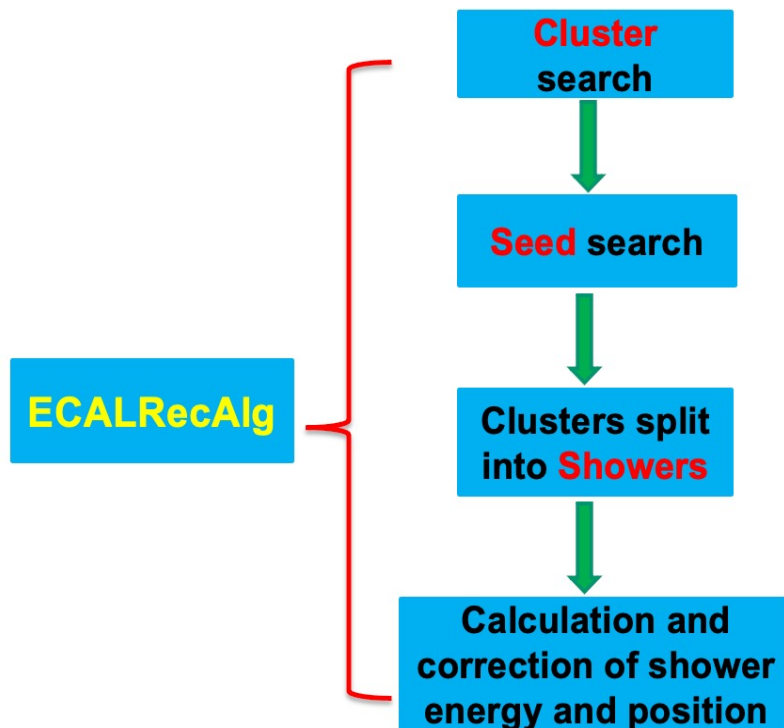


ECAL Reconstruction

❖ The algorithms have been developed and well-tested

- the energy of the shower
- the position of the photo

More details in Yunlong's talk



MUD Reconstruction

❖ The reconstruction algorithms are developed based on BDT method

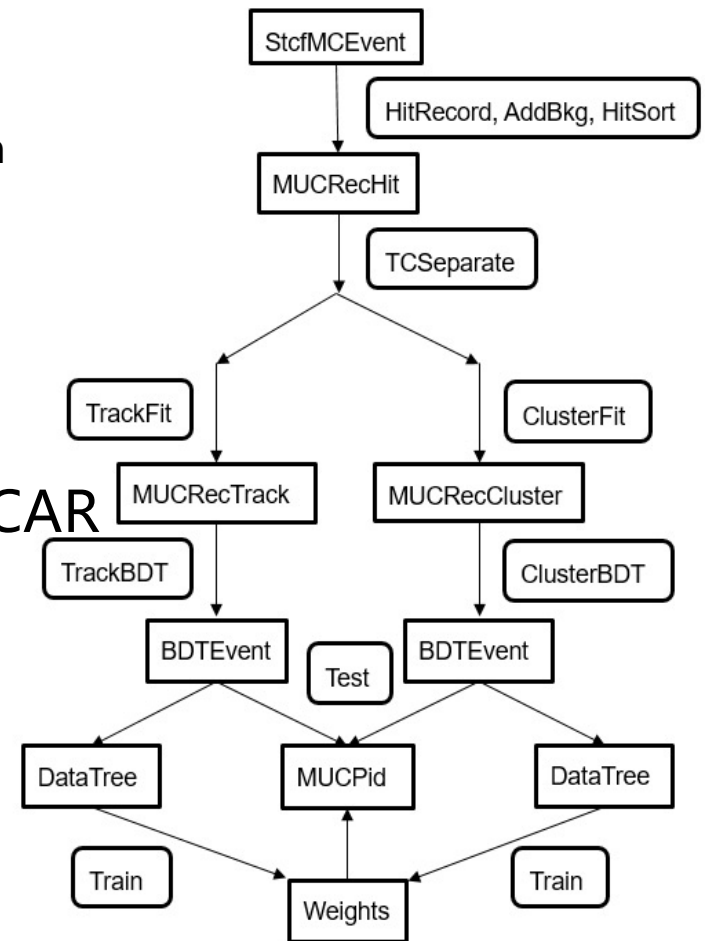
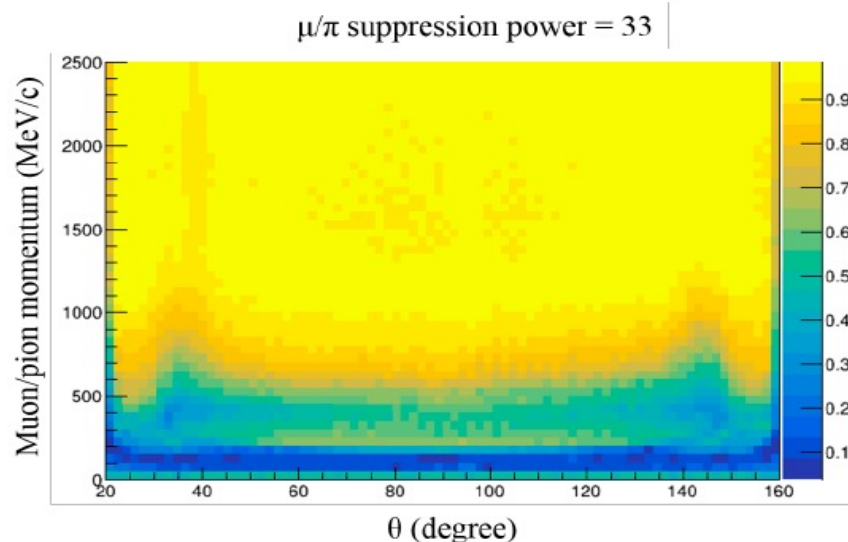
- Charged tracks

- Use MDC , EMC , MUD reconstruction information
- 14 BDT variables

- Neutral particles

- Use EMC ,MUD reconstruction information
- 23 BDT variables

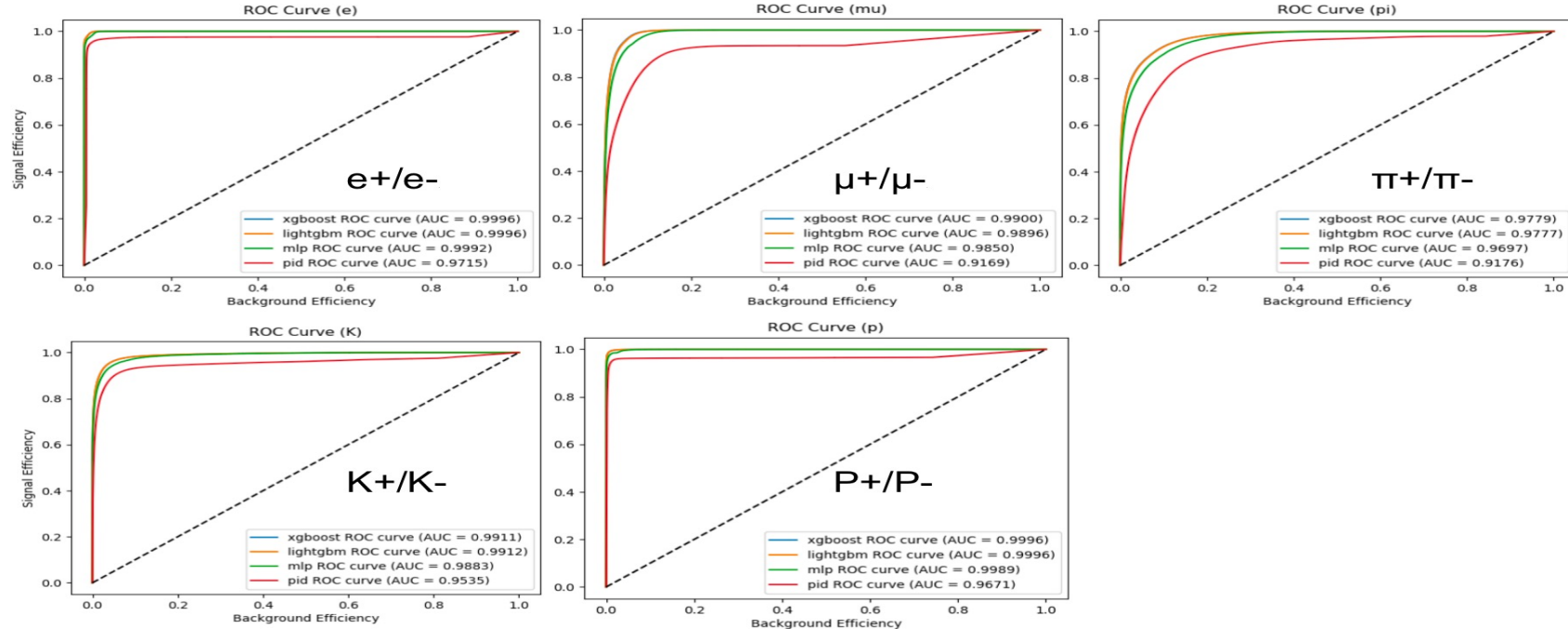
❖ All algorithms has been migrated into OSCAR



More details in Zhujun's talk

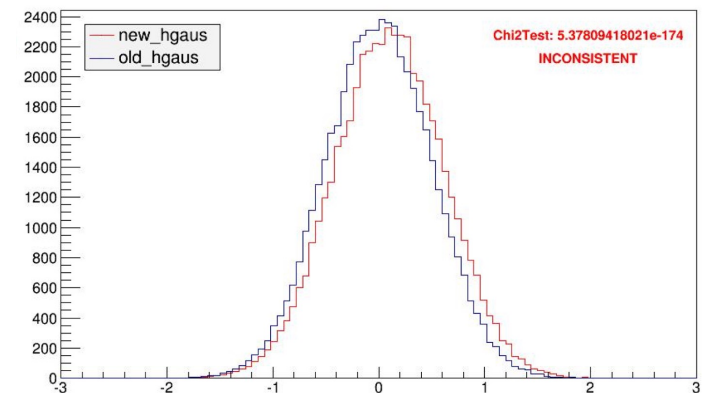
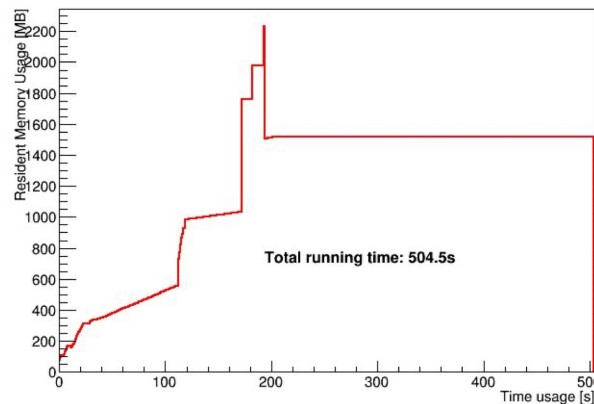
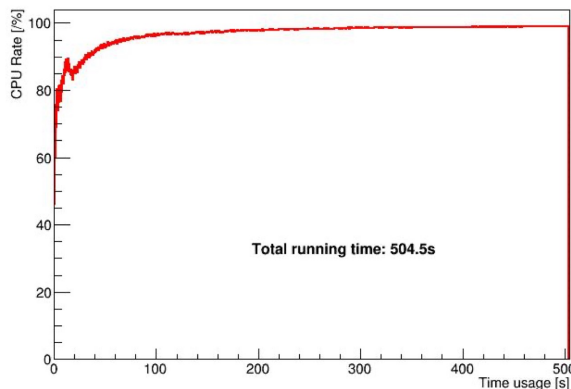
Global PID Algorithm Based on Deep Learning

- ❖ Combine information of multiple sub-detectors
 - MDC, TOF, RICH, EMC, MUC
- ❖ Study the performance of different Models with BESIII Data
 - GBDT, MLP, SVM, CNN, GRU, LSTM
 - GBDT currently outperforms better than other models
- ❖ Plan to use OSCAR MC Data to study PID performance



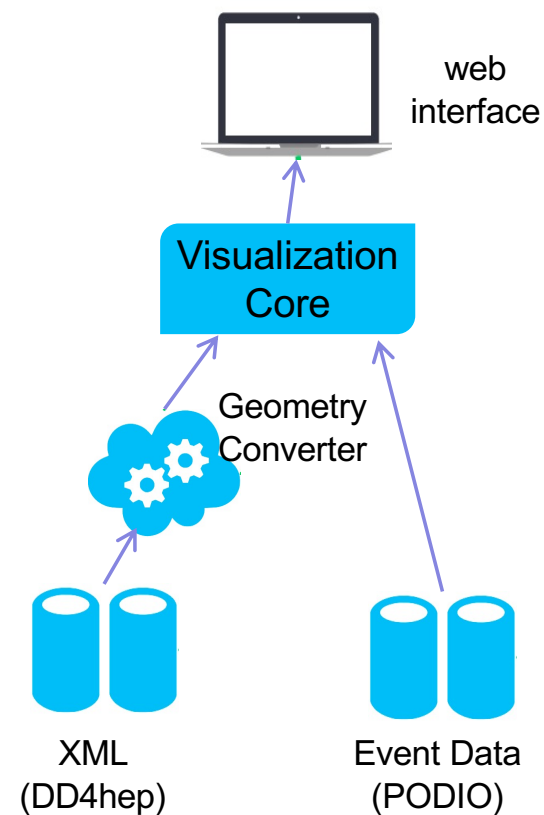
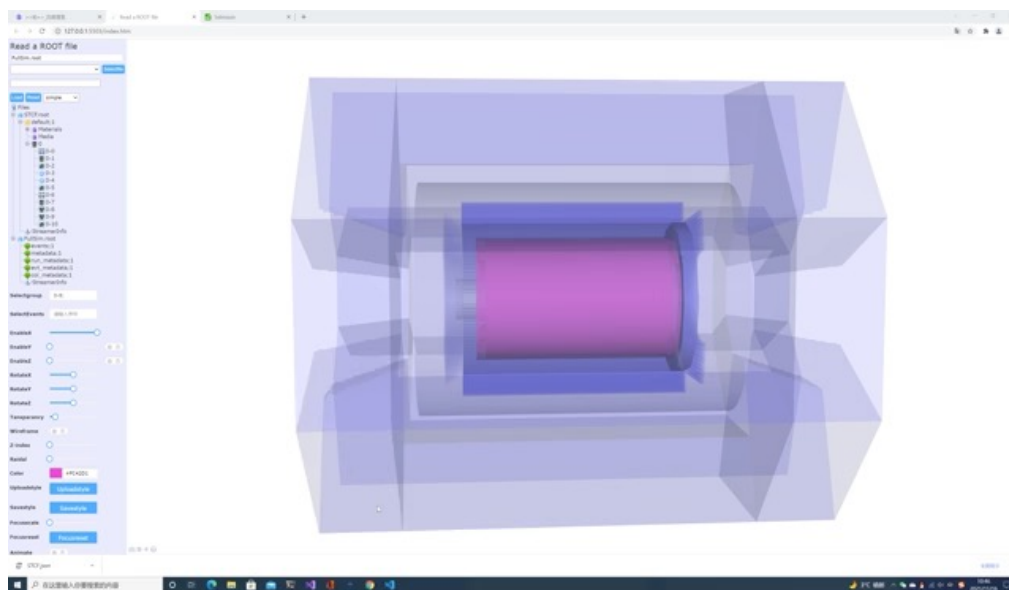
Automated Validation System

- ❖ An automated validation system is being developed for software validation at different levels
 - Unit test, integrated test, performance test, physical validation etc.
- ❖ A powerful toolkit is developed for building software validation workflow
 - Provide interfaces to define and run unit tests
 - Support various detectable failures (log errors, memory leaking, ...)
 - Support performance profiling
 - Support results validation based on statistical methods



Visulization Toolkit

- ❖ A common detector visualization and event display toolkit is being developed based on:
 - **WebGL**: high-performance interactive 3D and 2D visualization
 - **ThreeJS**: 3D mesh renderer
 - **DD4hep**: detector description
 - **PODIO**: event data model
- ❖ Initially developed for HERD, optimizing for STCF now



Software Release

❖ OSCAR_1.0.0 (2020-06)

- Phokhara
- StcfEvtGen
- DIAG36
- MDI geometry
- Magnetic Field
- DataBuffer
- MemMonitor
- DetGeoConSvc
- Qt5
- Oscar command

❖ OSCAR_2.0.0 (2021-01)

- RootIOSvc
- TClonesArray
- CommonSvc
- Accessing EDM in multi-task
- Shared ExternalLibs
- Detector Cell Id
- RICH Geometry update
- RecAlg
- RecEvent

❖ OSCAR_2.1.0 (2021-12)

- EDM with PODIO
- podio00-11
- root 6.20.04
- CMT->cmake
- Validation package
- DDXMLSvc

OSCAR_2.1.0 will be released soon after migration of EDM to PODIO and validation of reconstruction algorithms.

Summary and Future plan

❖ Lots of Progress has been made since last workshop

- Redesign EDM with PODIO and developed new EDM system
- Optimized the full detector simulation chain
- Recon. algorithms for Tracker, ECAL and MUC are implemented with OSCAR
- PID/Global PID algorithms are under developing
- Developed prototype of the Validation and visualization tools
- Software Management updates: SVN->Gitlab, CMT->Cmake

❖ Future plan for next year

- Update geometry information according to the latest detector designs
- Implement more realistic simulation of digitization process
- Finish migration of reconstruction algorithms
- Optimize reconstruction performance with backgrounds

Thanks for your attention!