Tracking Detector for Luminosity Measurement at PANDA

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February 28, 2017 Instrumentation for Colliding Beam Physics (INSTR-17)





FAIR - Facility for Antiproton and Ion Research



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PANDA



Physics at PANDA

Hadron spectroscopy

• Hadron structure PANDA Physics book: arXiv:0903.3905v1

- Hadron in medium
- Hypernuclear physics

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Normalization required:

$$\frac{\Delta N}{\Delta t} = \mathcal{L} \cdot \sigma$$



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Determination of Luminosity

$$\Rightarrow \mathcal{L} = \frac{\Delta N}{\Delta t} \cdot \frac{1}{\sigma}$$

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aimed resolution:absolute
$$\frac{\Delta \mathcal{L}}{\mathcal{L}} < 5 \%$$
relative $\frac{\Delta \mathcal{L}}{\mathcal{L}} < 1 \%$

Elastic Scattering in PANDA



Measurement of elastic scattered antiprotons with $\Theta=3\text{-}8\,\text{mrad}$

Elastic Scattering

PANDA: Measurement of elastic scattered antiprotons



At small |t|

- Coulomb scattering dominates
- Differential cross section can be calculated

At larger |t|

- Hadronic part dominates
- Description by models using data
- Large uncertainties of the model

Particle Track Reconstruction



Requirements for the Luminosity Detector

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Luminosity Measurement

- Measurement at small angles
- High angular resolution
 - very precise
 - minimal material

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Storage Ring

- High vacuum $< 10^{-9}$ mbar
- \bullet Slow changes of beam pipe diameter $<15^\circ$
- Minimal distortion of the beam

Luminosity Detector Overview



Differential Pumping Scheme





Vacuum to reduce multiple scattering of antiprotons

- \Rightarrow Thin transition foil required to:
 - Not disturb UHV of the beam pipe
 - Not disturb the antiproton beam

Differential Pumping Scheme

Requirements:

- Beam pipe: 10^{-9} mbar
- Vacuum box: 10^{-6} mbar

First test results:

- Beam pipe: 6.10⁻⁸ mbar
- Vacuum box: 4.10⁻⁷ mbar



HV-MAPS

- High Volage Monolythic Active Pixel Sensor
- Under development (Mu3e group in Heidelberg)
 Status of the Mu3e detector: Dirk Wiedner 4:00 pm
- Standard CMOS production
- Digital part on chip
- High bias voltage increases S/N
- Pixel size: $80 \,\mu\mathrm{m} imes 80 \,\mu\mathrm{m}$
- Thikness: \sim 50 μ m
- Dimensions: $\sim 2 \times 2 \text{ cm}^2$
- Expected power consumption < 300 mW/cm²

MuPix 4 prototype $3 \times 4 \text{ mm}^2$



Test Beam at MAMI

Test beam with a HV-MAPS (MuPix6) tracking station



Results



- Efficiency: > 99 %
- Expected noise rate: 0.12 MHz per sensor $\Rightarrow \sim 1$ noise hit per timeframe
- Hit resolution given by pixel cell size
- Time resolution: 7 ns



Arrangement of HV-MAPS

400 sensors (50 $\mu \rm m$ thick) glued on 40 CVD diamond wafers

- 4 planes with 10 modules
- Full azimuthal range

Advantages of CVD diamond:

• very high thermal conductivity

2011

- very hard material
 - \Rightarrow very thin supply structure (200 μ m)





Support Structure

Modules clamped to a support structure

- V2A pipe melted inside aluminum structure
- Cooling of sensors and electronic



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Signal Routing



Connection of HV-MAPS



Average $X/X_0 = 0.32 \%$ $\approx 350 \,\mu m \text{ silicon}$

With copper traces: Average $X/X_0 = 0.55$ %



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Rigid Flex Cable





- FFC connector outside of the box
- Three layers for flex area:
 - 40 differential pairs
 - (signal, clock, ...)
 - High voltage



Simulations on Cooling

Simulation with up to $700\,W/cm^2$ and power dissipating electronics Expected heat per half plane:

- Sensors: 140 W
- Electronics: 110 W



Contact Materials



Testing of contact materials with a module clamp and a copper dummy

Contact Materials



Cooling Tests in Vacuum



Cooling Tests in Vacuum



Software

Online

- Expected data rate: > 5.5 TB/d ⇒ Online selection necessary
- Use of Cellular Automaton for track reconstruction
- Calculation on GPUs

Poster: Data acquisition for the PANDA luminosity detector with online track reconstruction: Stephan Maldaner 5:00 pm

Offline

- Use of Cellular Automaton and Track Follower for track reconstruction
 - Missed tracks < 1 %
 - Fake tracks < 1%
- Precision for luminosity determination below % with realistic scenarios
- All beam influences can be corrected
 - IP distribution
 - IP displacement
 - Beam tilt
 - Beam divergence

Conclusion

- Design is ready
- Software completed
- TDR finished

To Do

Development of assembly procedure:

- Test of glueing of thin sensors
- Positioning of the sensors
- Mounting of the modules and half planes

Radiation test of all electronic components Test of the flex cables Test of full cooling circuit at full load Online Software

Prototype is under the way